L-force catalogue

Automation systems
Drive solutions

Controls
Inverters
Motors
Gearboxes
Engineering Tools

Motors: MF three-phase AC motors

Gearboxes: g500-B bevel gearbox

Lenze
As easy as that.

Contents of the L-force catalogue

Selected portfolio

Additional portfolio

Lenze makes many things easy for you.

With our motivated and committed approach, we work together with you to create the best possible solution and set your ideas in motion - whether you are looking to optimise an existing machine or develop a new one. We always strive to make things easy and seek perfection therein. This is anchored in our thinking, in our services and in every detail of our products. It's as easy as that!

1

Developing ideas

Are you looking to build the best machine possible and already have some initial ideas? Then get these down on paper together with us, starting with small innovative details and stretching all the way to completely new machines. Working together, we will develop an intelligent and sustainable concept that is perfectly aligned with your specific requirements.

2

Drafting concepts

We see welcome challenges in your machine tasks, supporting you with our comprehensive expertise and providing valuable impetus for your innovations. We take a holistic view of the individual motion and control functions here and draw up consistent, end-to-end drive and automation solutions for you - keeping everything as easy as possible and as extensive as necessary.

3

Implementing solutions

Our easy formula for satisfied customers is to establish an active partnership with fast decision-making processes and an individually tailored offer. We have been using this simple principle to meet the ever more specialised customer requirements in the field of mechanical engineering for many years.

4

Manufacturing machines

Functional diversity in perfect harmony: as one of the few full-range providers in the market, we can provide you with precisely those products that you actually need for any machine task – no more and no less. Our L-force product portfolio, a consistent platform for implementing drive and automation tasks, is invaluable in this regard.

5

Ensuring productivity

Productivity, reliability and new performance peaks on a daily basis – these are our key success factors for your machine. After delivery, we offer you cleverly devised service concepts to ensure continued safe operation. The primary focus here is on technical support, based on the excellent application expertise of our highly-skilled and knowledgeable after-sales team.

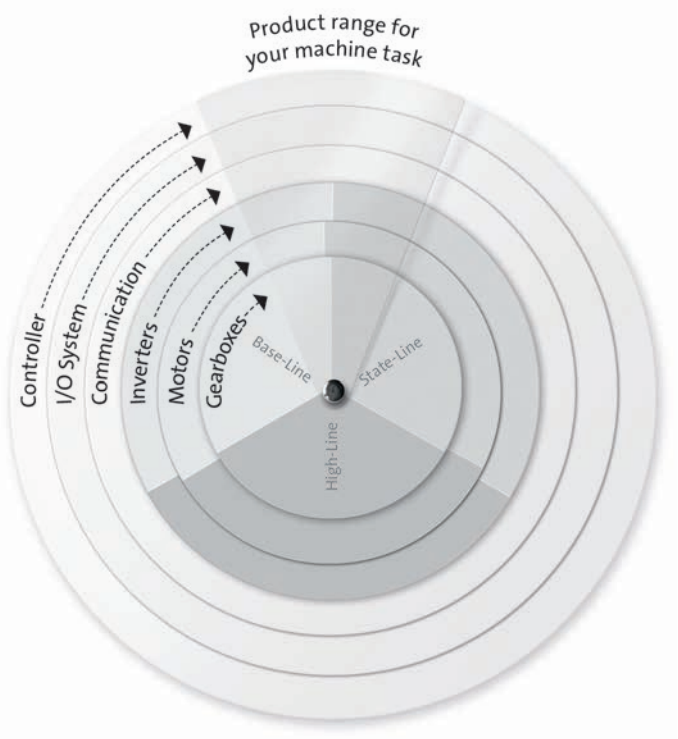
A matter of principle: the right products for every application.

Lenze's extensive L-force product portfolio follows a very simple principle. The functions of our finely scaled products are assigned to the three lines Base-Line, State-Line or High-Line.

But what does this mean for you? It allows you to quickly recognise which products represent the best solution for your own specific requirements.

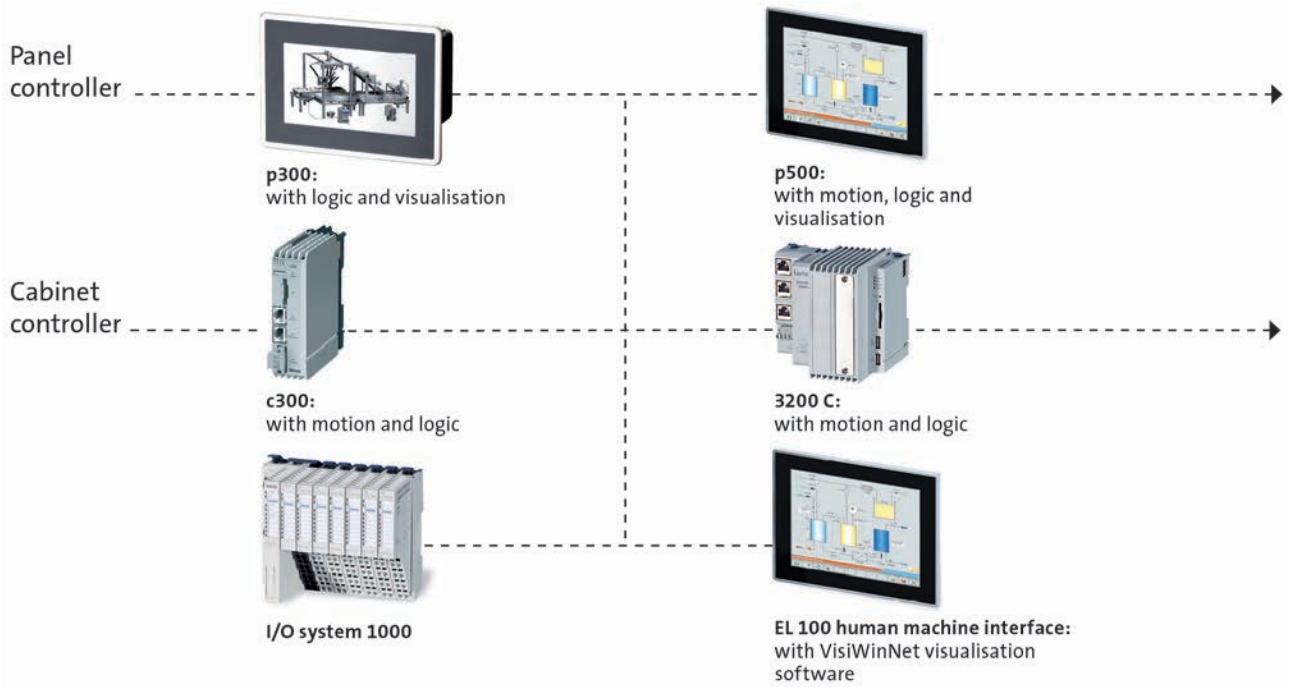
Powerful products with a major impact:
- Easy handling
- High quality and durability
- Reliable technologies in tune with the latest developments

Lenze products undergo the most stringent testing in our own laboratory. This allows us to ensure that you will receive consistently high quality and a long service life. In addition to this, five logistics centres ensure that the Lenze products you select are available for quick delivery anywhere across the globe. It's as easy as that!

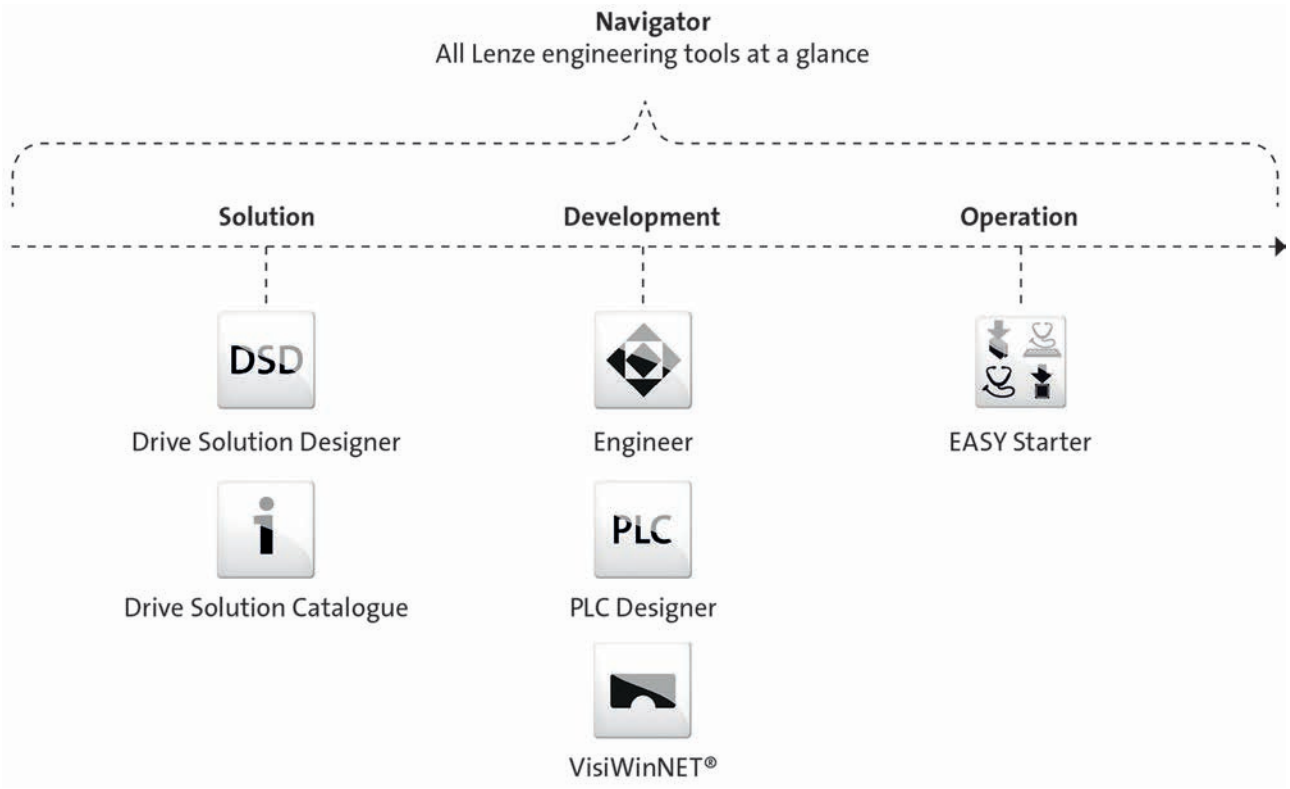


L-force product portfolio

Controls

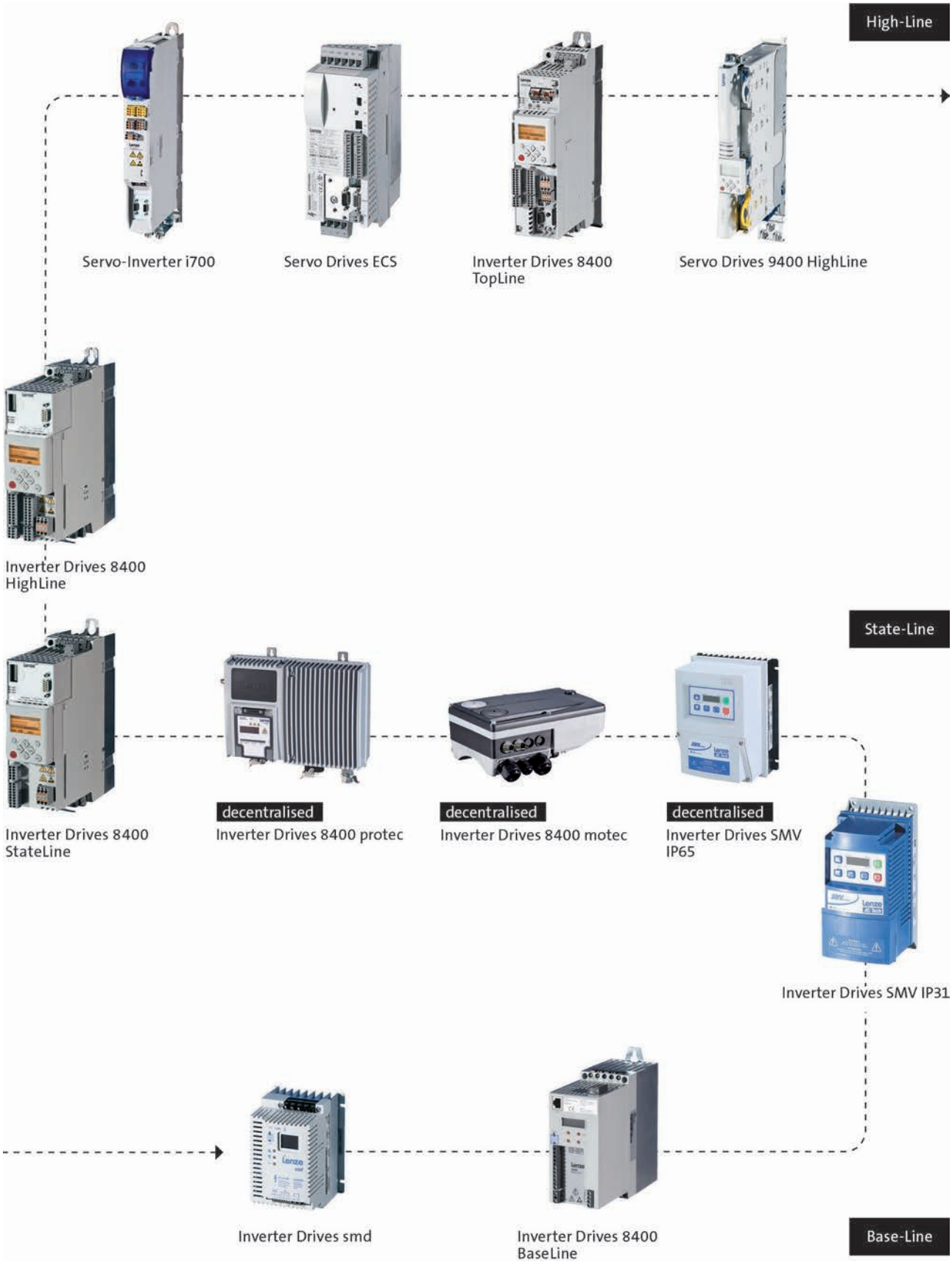


Engineering Tools



L-force product portfolio

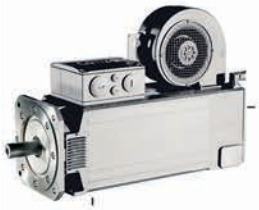
Inverters



L-force product portfolio

Motors

High-Line



MQA asynchronous servo motors

SDSGS synchronous servo motors

MDXKS synchronous servo motors

Synchronous servo motors MCS

Asynchronous servo motors MCA

Asynchronous servo motors SDSGA

State-Line

MF three-phase AC motors

MH three-phase AC motors

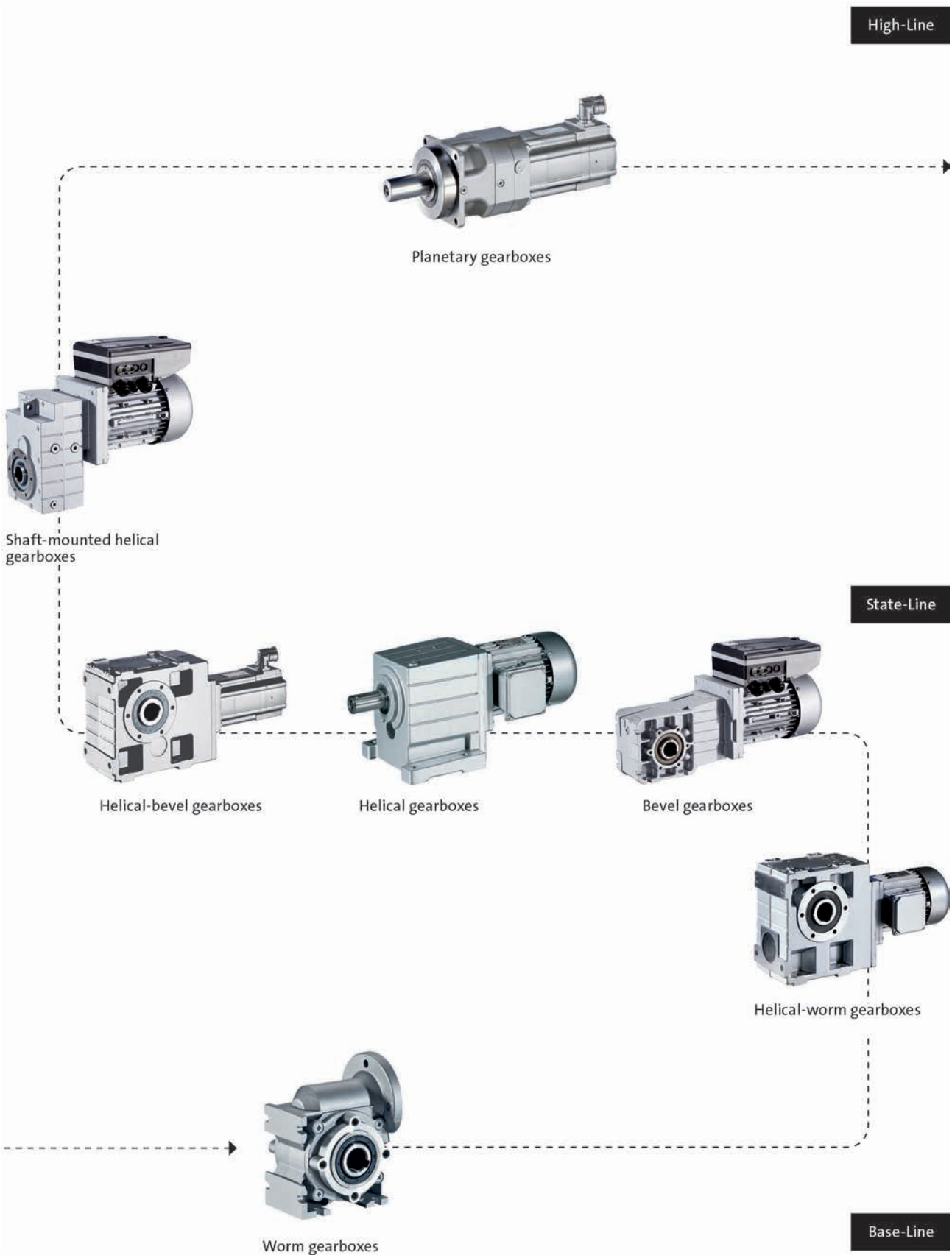
MD three-phase AC motors

Basic MD/MH three-phase AC motors

Base-Line

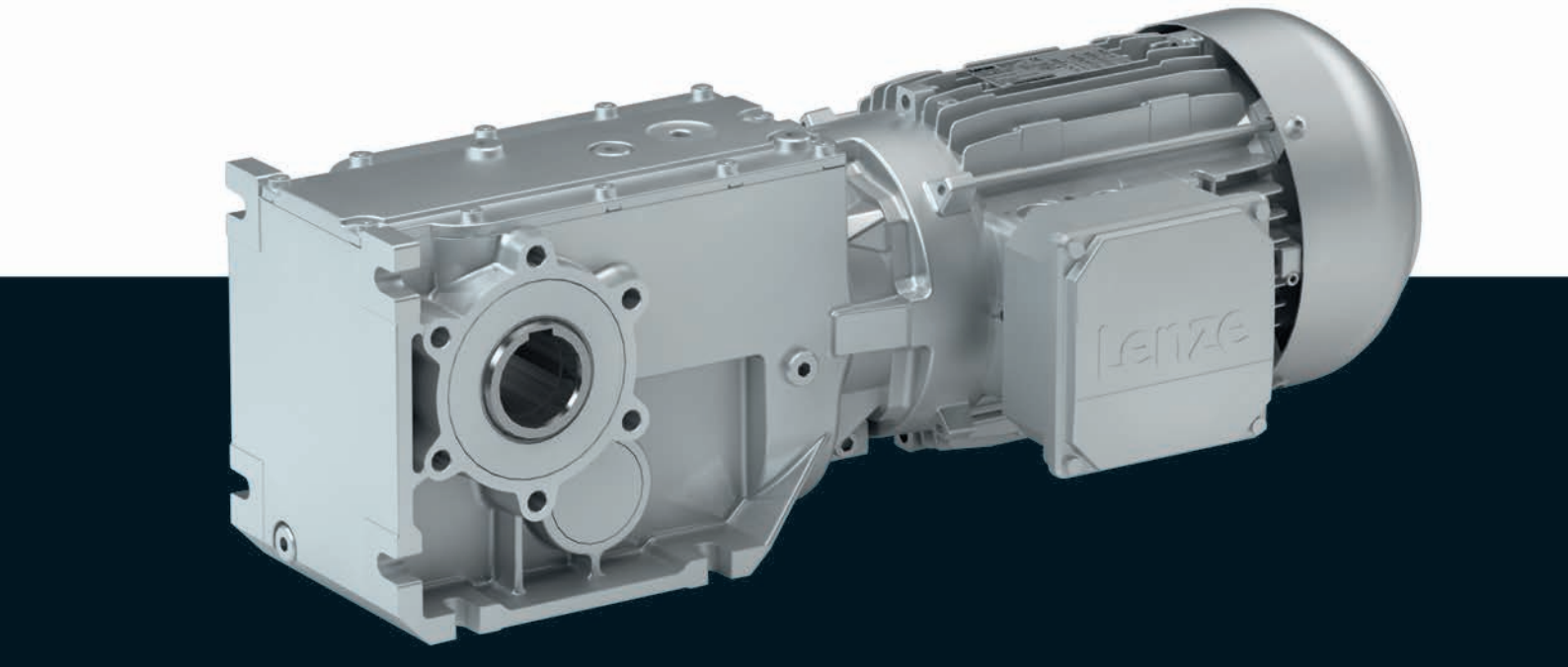
L-force product portfolio

Gearboxes



g500-B bevel geared motors

0.55 to 4 kW (efficiency class better than IE2)



g500-B bevel geared motors

Contents

Contents

List of abbreviations

c		Load capacity
i		Ratio
m	[kg]	Mass
M_2	[Nm]	Output torque
M_{22}	[Nm]	Output torque
$M_{a\_,1}$	[Nm]	Starting torque
$M_{a\_,2}$	[Nm]	Starting torque
n_2	[r/min]	Output speed
n_{21}	[r/min]	Output speed
n_{22}	[r/min]	Output speed

CCC	China Compulsory Certificate
CE	Communauté Européenne
CSA	Canadian Standards Association
cURus	Combined certification marks of UL for the USA and Canada
DIN	Deutsches Institut für Normung e.V.
EMC	Electromagnetic compatibility
EN	European standard
GOST	Certificate for Russian Federation
IEC	International Electrotechnical Commission
IM	International Mounting Code
IP	International Protection Code
NEMA	National Electrical Manufacturers Association
UL	Underwriters Laboratory Listed Product
UR	Underwriters Laboratory Recognized Product
VDE	Verband deutscher Elektrotechniker (Association of German Electrical Engineers)

Product information

In combination with three-phase AC motors, our bevel gearboxes form a compact and powerful drive unit. Numerous options at the input and output end provide for the drive to be exactly adapted to your application.

The efficient bevel gearboxes feature high reliable radial forces, closely stepped gear reductions and a low backlash. They are available in 2-pole and 3-pole design with a torque up to 450 Nm and a ratio of up to i= 360.

Versions

- High-efficient right-angle gearbox in a compact design for space-saving installation
- Standardised shaft and flange dimensions for an easy machine integration
- Low backlash and high torsional stiffness provide for exact results in positioning applications
- With three-phase AC motors better than IE2 in the power range 0.55 ... 4 kW

Inverters for motor-proximity installation

The Drive Package with decentralised Inverter Drives 8400 motec covers a power range up to 4 kW.

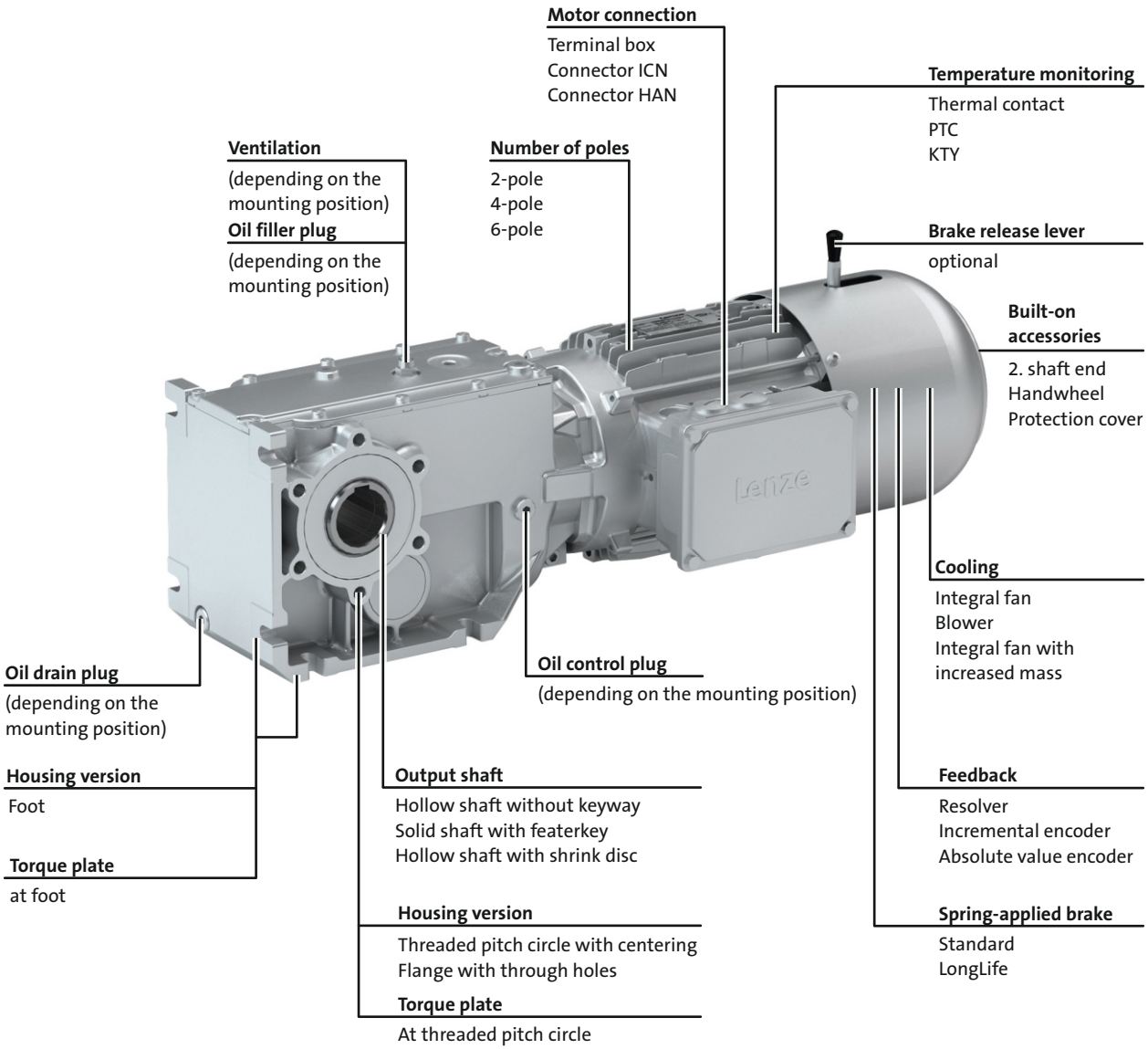
The product name

Gearbox type	Product range		Design	Rated torque [Nm]	Product
Bevel gearbox	g500	-	B	45	g500-B45
				110	g500-B110
				240	g500-B240
				450	g500-B450

Equipment

Overview

The equipment includes all the options available as standard and all the built-on accessories of the product.



The gearbox kit

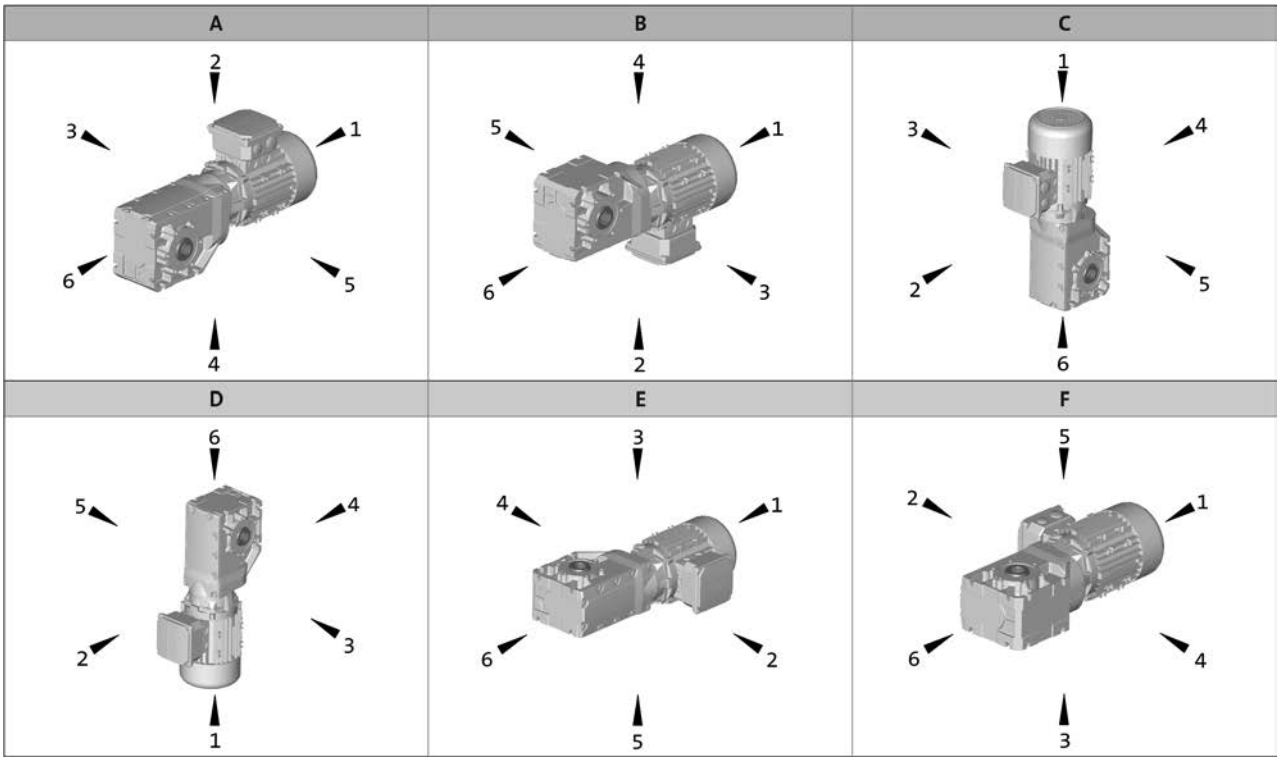
Geared motor

Product	g500-B45	g500-B110	g500-B240	g500-B450
Motor type				
Efficiency class better than IE2	MF□MA AC motors			
4-pole motor				
0.55 - 0.75 kW	063			
1.1 - 1.5 kW		071		
2.2 - 3.0 kW		080		
4.0 kW			090	
5.5 - 7.5 kW				100
Technical data				
Rated power	See selection table			
Mains voltage				
Mains frequency				
Output torque	See selection table			
Output speed	See selection table			
Ratio	See selection table			
Load capacity	See selection table			
Mounting position				
Standard	A/B/C/D/E/F			
Combined	ABCDEF	AEF		
Colour				
	Not coated Primed Paint in various corrosion-protection designs in accordance with RAL colours			
Surface and corrosion protection				
	Without OKS(uncoated) OKS-G (primed) OKS-S (small) OKS-M (medium) OKS-L (large)			

The gearbox kit

Mounting positions

► Mounting position (A to F) and position of system blocks (1 to 6)



Hollow shaft: 0
Solid shaft: 3, 5, 8 (3+5)
Hollow shaft with shrink disc: 3, 5

Without flange: 0
Flange: 3, 5, 8 (3+5)
Terminal box / motec: 2, 3, 4, 5

The gearbox kit

Motor details

Product	MF□MA□□					
	063-32 063-42	071-32	071-42	080-32 080-42	090-32	100-12 100-32
Connection type	Terminal box ICN connector HAN-10E connector HAN-Modular connector					
Spring-applied brake						
Rated torque [Nm]	4		4 8	8 16		16 32
Brake voltage [V]	DC 24/180/205 AC 230/400/460					
Brake design	Standard LongLife					
	Standard Overexcited Cold Brake					
Options	Manual release lever Low noise With cover ring					
Feedback	With absolute value encoder With incremental encoder With resolver					
Cooling	Without blower/integral fan Blower Integral fan with increased mass					
Temperature monitoring	TKO thermal contact KTY83-110 thermal detector KTY84-130 thermal detector PTC thermistor					
Approval	cURus CCC					
Degree of protection	IP55					
Further options	Protection cover 2nd shaft end Handwheel					

► Further information and installation feasibilities can be found in the Motors chapter.

The gearbox kit

Motor details

Connection type

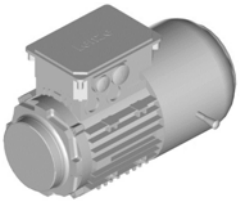

Terminal box

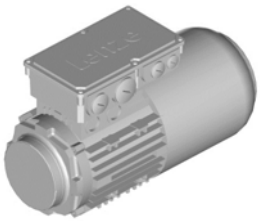

ICN connector


HAN connector

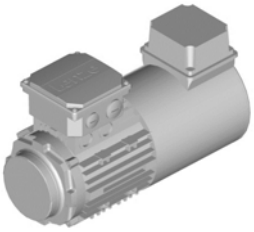
Cooling: integral fan

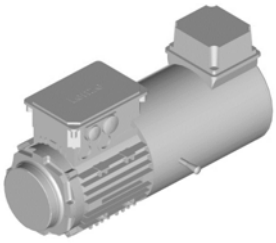

Without built-on accessories

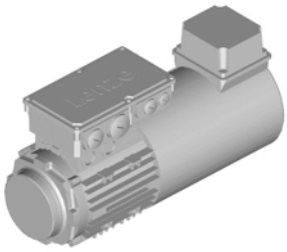

With spring-applied brake
With or without manual release lever


With feedback
With feedback and spring-applied brake

Cooling: blower

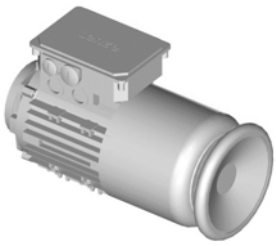

Without built-on accessories

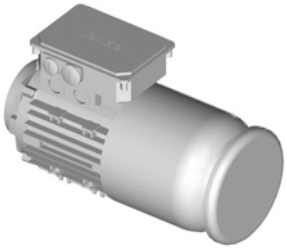

With spring-applied brake
With or without manual release lever


With feedback
With feedback and spring-applied brake

Further options


With 2nd shaft end
Only integral fan


With handwheel
Only integral fan


With protection cover

The gearbox kit

Gearbox details

Product	g500-B45	g500-B110	g500-B240	g500-B450
Driven shaft				
Solid shaft without keyway [mm]				
Solid shaft with featherkey [mm]	20x40		30x60	
Hollow shaft with keyway [mm]	18/20	20/25	30/35	35/40
Hollow shaft with shrink disc [mm]	20		30/35	35
Design	Standard stainless steel			
Gasket	Standard FPM (Viton)			
Bearing	Standard			
Fitting grease	Not enclosed Enclosed			
Housing				
Housing version	With foot With foot and centering			
Output flange				
flange diameter [mm]	110/120	120/160	160/200	200
Lubricant				
Type	CLP 460 [1)] CLP HC 320 CLP HC 220 CLP HC 220 USDA H1			
Oil-level inspection	Without inspection			Without inspection With inspection
Breather element	Without			Standard mounting position: Mounted Combined mounting position: loosely enclosed
Backlash				
Backlash	Standard			
Accessories				
Torque plate	Rubber buffers At threaded pitch circle	At threaded pitch circle	At threaded pitch circle At foot	At foot
Shaft cover	Hollow shaft Shrink disc: Rotating cover Shrink disc: Fixed cover			

[1)] Not suitable for geared servo motors.

► Further information and installation feasibilities can be found in the Gearboxes chapter.

The gearbox kit

Gearbox details

Solid shaft

Foot mounting
without centring

Foot mounting
With centering

Flange with through holes

Hollow shaft

Foot mounting
without centring

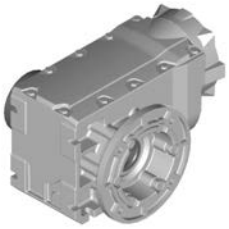
Foot mounting
With centering

Flange with through holes

Hollow shaft with shrink disc

Foot mounting
without centring

Foot mounting
With centering



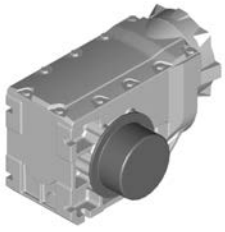
Flange with through holes

Accessories

2nd output shaft end

Torque plate
at foot

Torque plate
at threaded pitch circle



Cover
Hollow shaft/shrink disc

Dimensioning

General information about the data provided in this catalogue

The powers, torques and speeds specified in this catalogue are rounded values and are valid under the following conditions:

- Operating time/day = 8 h (100% OT)
- Duty class I for up to 10 switching operations/h
- Mounting positions and designs in this catalogue
- Standard lubricant
- T_{amb} = 20 °C for gearboxes,
  T_{amb} = 40 °C for motors (in accordance with EN 60034)
- Site altitude < = 1000 m amsl
- The selection tables provide the permissible mechanical powers and torques. For notes on the thermal power limit, see chapter drive dimensioning.
- The rated power specified for motors and geared motors applies to operating mode S1 (in accordance with EN 60034).

Under different operating conditions, the values obtained may vary from those listed here.
In the case of extreme operating conditions, please consult your Lenze sales office.

Dimensioning

Thermal power limit

The thermal power limit, defined by the heat balance, limits the permissible gearbox continuous power. It may be less than the mechanical power ratings listed in the selection tables.

The thermal power limit is affected by:
- the churning losses in the lubricant. These are determined by the mounting position and the circumferential speed of the gears;
- the load and the speed
- the ambient conditions: temperature, air circulation, input or dissipation via shafts and the foundation

If the following input speeds n_1 are exceeded, please contact Lenze:

Motor frame size	Mounting position A, B, E, F	Mounting position C, D
063 ... 100	4000 r/min	3000 r/min
112 ... 132	3000 r/min	1500 r/min

► For a short period of time up to 5 min, 30 % higher speeds are permissible

Possible ways of extending the application area

- synthetic lubricant (option)
- shaft sealing rings made from FP material/Viton (option)
- reduction in lubricant quantity
- cooling of the geared motor by means of air convection on the machine/system

Dimensioning

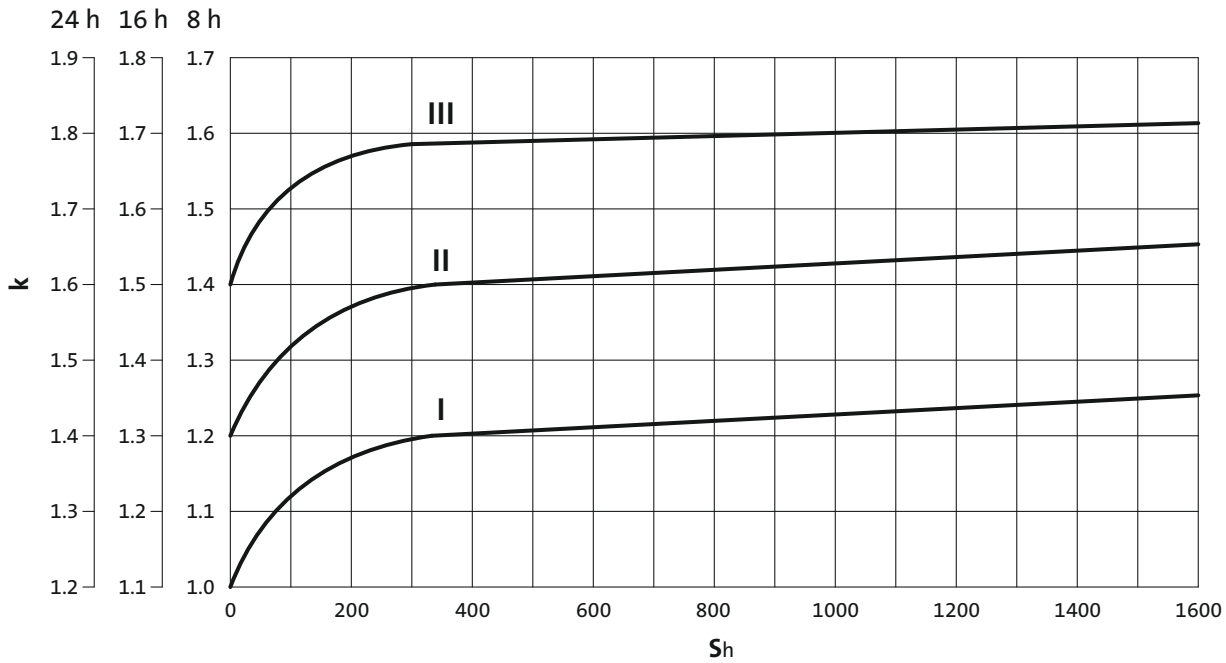
Load capacity and application factor

Load capacity c of gearbox
Rated value for the load capacity of Lenze geared motors.
- c is the ratio of the permissible rated torque of the gearbox to the rated torque supplied by the drive component (e.g. the built-in Lenze motor).
- The value of c must always be greater than the value of the application factor k calculated for the application.

Application factor k (according to DIN 3990)
Takes into account the influence of temporally variable loads which are actually present during the anticipated operating time of gearboxes and geared motors.
k is determined by:
- the type of load
- the load intensity
- temporal influences

Duty class	Load type
I	Smooth operation, small or light jolts
II	Uneven operation, average jolts
III	Uneven operation, severe jolts and/or alternating load

Application factor k



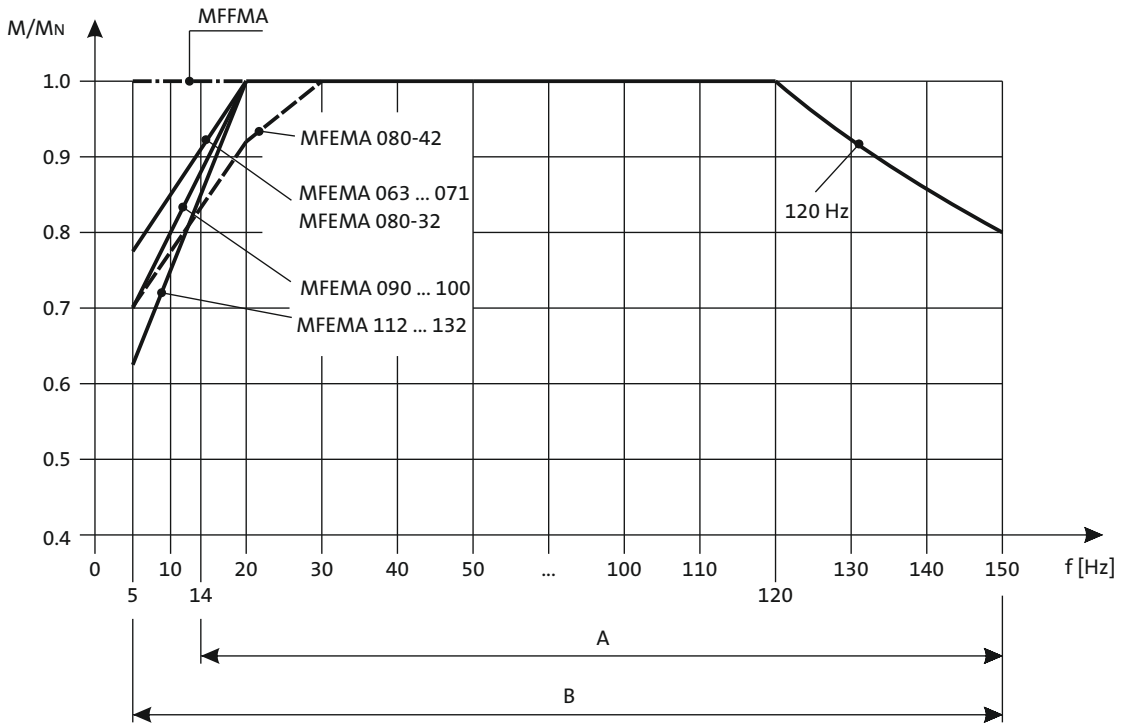
► S_h= switchings/h

Dimensioning

Torque derating at low motor frequencies

Motor size-dependent torque reduction, taking into account the thermal response during operation on the inverter.

Torque characteristics



A = Operation with integral fan and brake
B = Operation with integral fan and brake control "Holding current reduction"

You can use the Drive Solution Designer for precise drive dimensioning.

The Drive Solution Designer helps you to carry out a fast and high-quality drive dimensioning.
The software includes well-founded and proven knowledge on drive applications and electro-mechanical drive components.

Please contact your Lenze sales office.

Dimensioning

Weights

The values given in the tables consider the following gearbox/motor combination:
- Gearbox with hollow shaft without flange including lubricant amount for mounting position A
- Motor without built-on accessories (with integral fan)

For versions deviating from this, additional weights have to be considered.

The respective values can be found for:
- Geared motors without built-on accessories
  > Chapter: Geared motors/Technical data
- Gearbox options
  > Chapter: Gearboxes/Technical data and accessories
- Motor options: Spring-applied brake, feedback, 2. Shaft end, handwheel and increased centrifugal mass
  > Chapter: Motors/Accessories

Moments of inertia

The given moments of inertia of the gearbox refer to the drive shaft. The influence of the ratio (i^2) has been considered in the data.

When the total moment of inertia of the geared motor is calculated, the values of the gearbox, motor and accessories have to be added.

The respective values can be found for:
- Gearboxes
  > Chapter: Gearbox/Technical data
- Motors without built-on accessories
  > Chapter: Motors/Technical data/Rated data
- Motor options: Spring-applied brake, feedback, 2. Shaft end, handwheel and increased centrifugal mass
  > Chapter: Motors/Accessories

Selection tables, notes

Notes on the selection tables with 4-pole motors

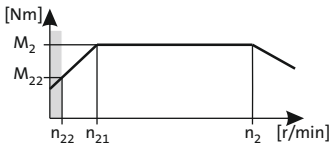
The selection tables show the available combinations of gearbox type, number of stages, ratio and motor. They are used only to provide basic orientation.
The following legend indicates the structure of the selection tables.

Rated power Prated of the drive motor depending on the rated frequency

120 Hz: P_N = 0.55 kW

2-stufige Getriebe ← **Number of the gear stage of the gearbox**

Torque diagram



Inverter operation							i	Product		
5 Hz -		- 20 Hz		- 120 Hz (1:24)						
n_{22} [r/min]	M_{22} [Nm]	n_{21} [r/min]	M_2 [Nm]	n_2 [r/min]	M_2 [Nm]	c		g500	MF□MA□□	
28	5.7	116	8.0	663	8.0	3.9	5.185	-B110	063-32	37
27	5.9	111	8.0	636	8.0	3.8	5.411	-B45	063-32	22

Product Gearbox | **Product Motor** | **Ratio i** | **Page number for dimensions**

Inverter operation
The speed and torque data are valid for self-ventilated and forced ventilated drives. Forced ventilated drives can always output the torque **M2** in the entire setting ranges. In the case of self-ventilated drives, a reduction to **M22** is required in the lower speed range.

The following applies to self-ventilated geared motors:
n22 is the minimum speed where the torque **M22** is permissible, from **n21** to **n2**, the maximum torque is **M2**
The following applies to forced ventilated geared motors:
From the minimum speed **n22** to **n2**, the maximum torque is **M2**

Load capacity c of the gearbox
c is the ratio between the permissible rated torque of the gearbox and the rated torque of the three-phase AC motor (converted to the driven shaft).
c must be always higher than the service factor **k** determined for the application **k**.

$$c = \frac{M_{2,zul}}{M_{1N} \cdot i \cdot \eta_{Getr}} > k$$

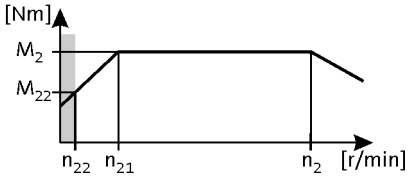
Motor voltages

The power values and torques indicated in the selection tables relate to the following motor voltages:
- 50 Hz : Δ 230 V / Y 400 V
- 60 Hz : 230 V or 460 V
- 87 Hz : Δ 400 V

Operation at 87 Hz

In 87 Hz operation, the three-phase AC motor (which is designed for a voltage of Δ 230 V / Y 400 V at 50 Hz) is operated on an inverter with 400 V rated voltage in a delta connection. It is important to note here that the inverter must be configured for 87Hz output.
This offers the following advantages over 50 Hz operation:
- the setting range of the motor is increased by a factor of 1.73.
- the motor can then provide around 1.73 times greater output, which in turn allows a smaller and more affordable motor to be selected for the application.
- the efficiency of the motor is also improved.

Selection tables, 4-pole motors

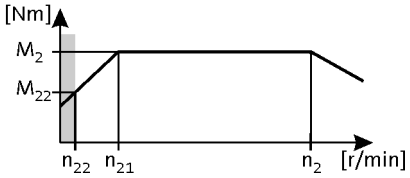


120 Hz: P_N = 0.55 kW

2-stage gearboxes

Inverter operation							i	Product		
5 Hz -		- 20 Hz		- 120 Hz (1:24)						
n_{22} [r/min]	M_{22} [Nm]	n_{21} [r/min]	M_2 [Nm]	n_2 [r/min]	M_2 [Nm]	c		g500	MF□MA□□	
16	10	66	13	378	13	4.5	9.101	-B110	063-32	35
16	10	66	13	378	13	2.6	9.101	-B45	063-32	32
14	12	57	15	329	15	4.5	10.466	-B110	063-32	35
14	12	57	15	329	15	2.3	10.466	-B45	063-32	32
13	13	52	17	301	17	4.1	11.449	-B110	063-32	35
13	13	52	17	296	17	2.0	11.640	-B45	063-32	32
11	14	47	18	271	18	3.7	12.698	-B110	063-32	35
11	15	45	19	257	19	1.8	13.386	-B45	063-32	32
9.9	16	41	21	236	21	3.2	14.603	-B110	063-32	35
9.6	17	40	22	228	22	1.6	15.111	-B45	063-32	32
9.3	17	39	23	221	23	3.1	15.556	-B110	063-32	35
8.3	19	35	25	198	25	1.4	17.378	-B45	063-32	32
8.1	20	34	26	192	26	2.8	17.889	-B110	063-32	35
7.5	21	31	28	178	28	1.2	19.365	-B45	063-32	32
7.4	22	31	28	176	28	2.7	19.556	-B110	063-32	35
6.5	24	27	32	155	32	1.1	22.270	-B45	063-32	32
6.4	25	27	33	153	33	2.4	22.489	-B110	063-32	35
5.8	28	24	36	137	36	1.1	25.051	-B45	063-32	32
5.8	28	24	37	137	37	2.2	25.185	-B110	063-32	35
5.0	32	21	42	119	42	2.0	28.963	-B110	063-32	35
4.5	35	19	46	108	46	1.8	31.919	-B110	063-32	35
4.3	37	18	48	103	48	3.2	33.433	-B240	063-32	38
4.0	40	16	53	94	53	1.6	36.707	-B110	063-32	35
3.9	41	16	54	92	54	1.5	37.400	-B110	063-32	35
3.8	42	16	55	91	55	3.2	37.967	-B240	063-32	38
3.6	44	15	58	86	58	1.2	40.000	-B110	063-32	35
3.4	48	14	63	80	63	3.2	43.267	-B240	063-32	38
3.2	51	13	67	75	67	1.2	46.000	-B110	063-32	35
3.0	53	13	70	71	70	1.4	48.167	-B110	063-32	35
3.0	54	12	71	70	71	2.9	49.133	-B240	063-32	38
2.8	58	11	76	66	76	2.6	52.510	-B240	063-32	38
2.4	66	10	86	58	86	2.4	59.630	-B240	063-32	38
2.4	67	9.8	89	56	89	1.2	61.045	-B110	063-32	35
2.2	74	8.9	97	51	97	1.5	67.113	-B240	063-32	38
1.9	84	7.9	111	45	111	1.5	76.213	-B240	063-32	38

Selection tables, 4-pole motors

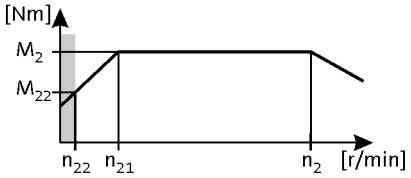


120 Hz: P_N = 0.55 kW

3-stage gearboxes

Inverter operation							i	Product		
5 Hz -		- 20 Hz		- 120 Hz (1:24)						
n_{22} [r/min]	M_{22} [Nm]	n_{21} [r/min]	M_2 [Nm]	n_2 [r/min]	M_2 [Nm]	c		g500	MF□MA□□	
2.1	73	8.8	97	50	97	2.1	68.459	-B240	063-32	38
1.9	83	7.7	110	44	110	1.9	77.741	-B240	063-32	38
1.7	94	6.9	124	39	124	1.7	87.563	-B240	063-32	38
1.6	98	6.7	130	38	130	3.0	89.534	-B450	063-32	41
1.5	109	6.0	144	35	144	2.7	99.274	-B450	063-32	41
1.5	106	6.0	141	35	141	1.5	99.437	-B240	063-32	38
1.3	122	5.4	162	31	162	2.7	111.372	-B450	063-32	41
1.3	122	5.3	161	30	161	1.4	113.673	-B240	063-32	38
1.2	136	4.9	179	28	179	2.4	123.487	-B450	063-32	41
1.1	138	4.6	183	27	183	1.3	129.087	-B240	063-32	38
1.0	158	4.2	209	24	209	2.1	144.128	-B450	063-32	41
1.0	156	4.1	206	24	206	1.1	145.674	-B240	063-32	38
0.9	175	3.8	232	22	232	1.9	159.807	-B450	063-32	41
0.8	192	3.4	254	20	254	1.7	174.919	-B450	063-32	41
0.7	213	3.1	281	18	281	1.5	193.948	-B450	063-32	41
0.6	245	2.7	324	15	324	1.3	223.563	-B450	063-32	41
0.6	272	2.4	359	14	359	1.2	247.882	-B450	063-32	41

Selection tables, 4-pole motors



120 Hz: P_N = 0.75 kW

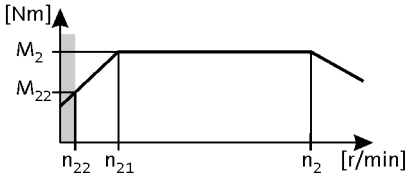
2-stage gearboxes

Inverter operation							i	Product		
5 Hz -		- 20 Hz		- 120 Hz (1:24)						
n_{22} [r/min]	M_{22} [Nm]	n_{21} [r/min]	M_2 [Nm]	n_2 [r/min]	M_2 [Nm]	c		g500	MF□MA□□	
16	14	66	18	374	18	3.3	9.101	-B110	063-42	35
16	14	66	18	374	18	1.9	9.101	-B45	063-42	32
14	16	57	21	325	21	3.2	10.466	-B110	063-42	35
14	16	57	21	325	21	1.6	10.466	-B45	063-42	32
13	17	52	23	297	23	3.0	11.449	-B110	063-42	35
13	17	52	23	292	23	1.5	11.640	-B45	063-42	32
11	19	47	25	268	25	2.7	12.698	-B110	063-42	35
11	20	45	27	254	27	1.3	13.386	-B45	063-42	32
9.9	22	41	29	233	29	2.3	14.603	-B110	063-42	35
9.6	23	40	30	225	30	1.1	15.111	-B45	063-42	32
9.3	23	39	31	219	31	2.3	15.556	-B110	063-42	35
8.1	27	34	36	190	36	2.0	17.889	-B110	063-42	35
7.4	29	31	39	174	39	2.0	19.556	-B110	063-42	35
6.4	34	27	45	151	45	1.8	22.489	-B110	063-42	35
5.8	38	24	50	135	50	1.6	25.185	-B110	063-42	35
5.4	40	22	54	127	54	2.7	26.878	-B240	063-42	38
5.0	43	21	58	117	58	1.4	28.963	-B110	063-42	35
4.8	46	20	61	111	61	2.7	30.522	-B240	063-42	38
4.5	48	19	64	107	64	1.3	31.919	-B110	063-42	35
4.3	50	18	67	102	67	2.3	33.433	-B240	063-42	38
4.0	55	16	73	93	73	1.1	36.707	-B110	063-42	35
3.9	56	16	75	91	75	1.1	37.400	-B110	063-42	35
3.8	57	16	76	90	76	2.3	37.967	-B240	063-42	38
3.4	65	14	87	79	87	2.3	43.267	-B240	063-42	38
3.0	74	12	98	69	98	2.1	49.133	-B240	063-42	38
2.8	79	11	105	65	105	1.9	52.510	-B240	063-42	38
2.4	89	10	119	57	119	1.7	59.630	-B240	063-42	38
2.2	101	8.9	134	51	134	1.1	67.113	-B240	063-42	38
1.9	114	7.9	153	45	153	1.1	76.213	-B240	063-42	38

3-stage gearboxes

Inverter operation							i	Product		
5 Hz -		- 20 Hz		- 120 Hz (1:24)						
n_{22} [r/min]	M_{22} [Nm]	n_{21} [r/min]	M_2 [Nm]	n_2 [r/min]	M_2 [Nm]	c		g500	MF□MA□□	
4.0	54	17	73	94	73	2.7	36.373	-B450	063-42	41
3.6	60	15	81	84	81	3.1	40.330	-B450	063-42	41
3.2	68	13	91	75	91	2.6	45.245	-B450	063-42	41
2.9	75	12	100	68	100	2.6	50.167	-B450	063-42	41
2.3	93	9.6	125	55	125	3.1	62.262	-B450	063-42	41
2.1	100	8.8	134	50	134	1.6	68.459	-B240	063-42	38

Selection tables, 4-pole motors

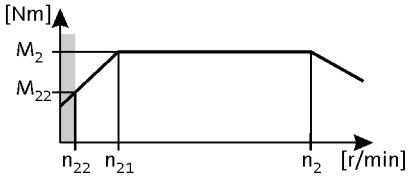


120 Hz: P_N = 0.75 kW

3-stage gearboxes

Inverter operation							i	Product		
5 Hz -		- 20 Hz		- 120 Hz (1:24)						
n_{22} [r/min]	M_{22} [Nm]	n_{21} [r/min]	M_2 [Nm]	n_2 [r/min]	M_2 [Nm]	c		g500	MF□MA□□	
1.7	128	6.9	171	39	171	1.2	87.563	-B240	063-42	38
1.6	134	6.7	179	38	179	2.2	89.534	-B450	063-42	41
1.5	149	6.0	199	34	199	2.0	99.274	-B450	063-42	41
1.5	145	6.0	194	34	194	1.1	99.437	-B240	063-42	38
1.3	167	5.4	223	31	223	1.9	111.372	-B450	063-42	41
1.3	166	5.3	222	30	222	1.0	113.673	-B240	063-42	38
1.2	185	4.9	247	28	247	1.8	123.487	-B450	063-42	41
1.0	216	4.2	288	24	288	1.5	144.128	-B450	063-42	41
0.9	239	3.8	320	21	320	1.4	159.807	-B450	063-42	41
0.8	262	3.4	350	19	350	1.2	174.919	-B450	063-42	41
0.7	290	3.1	388	18	388	1.1	193.948	-B450	063-42	41

Selection tables, 4-pole motors



120 Hz: P_N = 1.1 kW

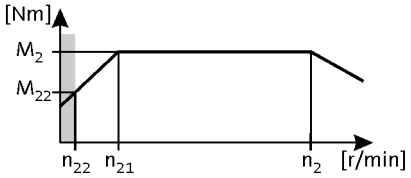
2-stage gearboxes

Inverter operation							i	Product		
5 Hz -		- 20 Hz		- 120 Hz (1:24)						
n_{22} [r/min]	M_{22} [Nm]	n_{21} [r/min]	M_2 [Nm]	n_2 [r/min]	M_2 [Nm]	c		g500	MF□MA□□	
23	14	96	18	558	18	4.2	6.257	-B240	071-32	38
16	20	66	26	384	26	2.4	9.101	-B110	071-32	35
14	23	57	30	334	30	2.2	10.466	-B110	071-32	35
13	25	52	33	305	33	2.1	11.449	-B110	071-32	35
11	28	47	36	275	36	1.9	12.698	-B110	071-32	35
9.9	32	41	42	239	42	1.6	14.603	-B110	071-32	35
9.3	34	39	44	224	44	1.6	15.556	-B110	071-32	35
8.1	39	34	51	195	51	1.4	17.889	-B110	071-32	35
7.4	43	31	56	179	56	1.4	19.556	-B110	071-32	35
7.0	45	29	59	169	59	3.1	20.650	-B240	071-32	38
6.4	49	27	64	155	64	1.2	22.489	-B110	071-32	35
6.2	52	26	67	149	67	2.7	23.450	-B240	071-32	38
5.8	55	24	72	139	72	1.1	25.185	-B110	071-32	35
5.4	59	22	77	130	77	2.4	26.878	-B240	071-32	38
5.0	64	21	83	121	83	1.0	28.963	-B110	071-32	35
4.8	67	20	87	114	87	2.1	30.522	-B240	071-32	38
4.3	73	18	96	104	96	1.9	33.433	-B240	071-32	38
3.8	83	16	109	92	109	1.7	37.967	-B240	071-32	38
3.4	95	14	124	81	124	1.7	43.267	-B240	071-32	38
3.0	108	12	140	71	140	1.5	49.133	-B240	071-32	38
2.8	115	11	150	67	150	1.3	52.510	-B240	071-32	38
2.4	131	10	171	59	171	1.2	59.630	-B240	071-32	38

3-stage gearboxes

Inverter operation							i	Product		
5 Hz -		- 20 Hz		- 120 Hz (1:24)						
n_{22} [r/min]	M_{22} [Nm]	n_{21} [r/min]	M_2 [Nm]	n_2 [r/min]	M_2 [Nm]	c		g500	MF□MA□□	
4.0	80	17	104	96	104	3.2	36.373	-B450	071-32	41
3.6	89	15	115	87	115	3.4	40.330	-B450	071-32	41
3.2	99	13	129	77	129	3.0	45.245	-B450	071-32	41
2.9	110	12	143	70	143	2.7	50.167	-B450	071-32	41
2.6	123	11	161	62	161	2.4	56.154	-B450	071-32	41
2.3	137	9.6	178	56	178	2.2	62.262	-B450	071-32	41
2.1	151	8.7	197	51	197	2.0	68.788	-B450	071-32	41
1.9	167	7.9	218	46	218	1.8	76.271	-B450	071-32	41
1.6	197	6.7	256	39	256	1.5	89.534	-B450	071-32	41
1.5	218	6.0	284	35	284	1.4	99.274	-B450	071-32	41
1.3	245	5.4	318	31	318	1.3	111.372	-B450	071-32	41
1.2	271	4.9	353	28	353	1.2	123.487	-B450	071-32	41
1.0	316	4.2	412	24	412	1.0	144.128	-B450	071-32	41

Selection tables, 4-pole motors



120 Hz: P_N = 1.5 kW

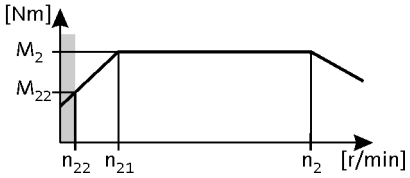
2-stage gearboxes

Inverter operation							i	Product		
5 Hz -		- 20 Hz		- 120 Hz (1:24)						
n_{22} [r/min]	M_{22} [Nm]	n_{21} [r/min]	M_2 [Nm]	n_2 [r/min]	M_2 [Nm]	c		g500	MF□MA□□	
23	19	96	25	551	25	3.1	6.257	-B240	071-42	38
16	27	66	36	379	36	1.8	9.101	-B110	071-42	35
14	31	57	41	330	41	1.6	10.466	-B110	071-42	35
13	34	52	45	301	45	1.5	11.449	-B110	071-42	35
12	36	50	48	286	48	3.1	12.081	-B240	071-42	38
11	38	47	50	272	50	1.4	12.698	-B110	071-42	35
11	41	44	54	252	54	3.0	13.719	-B240	071-42	38
9.9	44	41	58	236	58	1.2	14.603	-B110	071-42	35
9.7	45	40	59	230	59	2.9	15.008	-B240	071-42	38
9.3	47	39	61	222	61	1.1	15.556	-B110	071-42	35
8.6	51	36	66	205	66	2.7	16.857	-B240	071-42	38
8.1	54	34	71	193	71	1.0	17.889	-B110	071-42	35
7.6	57	31	76	180	76	2.4	19.143	-B240	071-42	38
7.0	62	29	81	167	81	2.2	20.650	-B240	071-42	38
6.2	70	26	92	147	92	2.0	23.450	-B240	071-42	38
5.4	81	22	106	128	106	1.7	26.878	-B240	071-42	38
4.8	91	20	120	113	120	1.5	30.522	-B240	071-42	38
4.3	100	18	132	103	132	1.4	33.433	-B240	071-42	38
3.8	114	16	150	91	150	1.2	37.967	-B240	071-42	38
3.4	130	14	171	80	171	1.2	43.267	-B240	071-42	38
3.0	147	12	194	70	194	1.1	49.133	-B240	071-42	38

3-stage gearboxes

Inverter operation							i	Product		
5 Hz -		- 20 Hz		- 120 Hz (1:24)						
n_{22} [r/min]	M_{22} [Nm]	n_{21} [r/min]	M_2 [Nm]	n_2 [r/min]	M_2 [Nm]	c		g500	MF□MA□□	
8.9	49	37	64	211	64	3.1	16.349	-B450	071-42	41
8.1	54	34	71	193	71	3.1	17.885	-B450	071-42	41
7.3	59	30	78	174	78	3.1	19.831	-B450	071-42	41
6.4	68	26	90	151	90	2.9	22.813	-B450	071-42	41
5.7	76	24	100	136	100	2.9	25.294	-B450	071-42	41
5.2	84	22	110	124	110	2.6	27.945	-B450	071-42	41
4.7	93	19	122	111	122	2.6	30.985	-B450	071-42	41
4.0	109	17	143	95	143	2.3	36.373	-B450	071-42	41
3.6	121	15	159	86	159	2.4	40.330	-B450	071-42	41
3.2	135	13	178	76	178	2.2	45.245	-B450	071-42	41
2.9	150	12	198	69	198	2.0	50.167	-B450	071-42	41
2.6	168	11	221	61	221	1.8	56.154	-B450	071-42	41
2.3	186	9.6	246	55	246	1.6	62.262	-B450	071-42	41
2.1	206	8.7	271	50	271	1.4	68.788	-B450	071-42	41

Selection tables, 4-pole motors

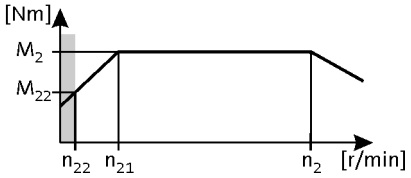


120 Hz: P_N = 1.5 kW

3-stage gearboxes

Inverter operation							i	Product		
5 Hz -		- 20 Hz		- 120 Hz (1:24)						
n_{22} [r/min]	M_{22} [Nm]	n_{21} [r/min]	M_2 [Nm]	n_2 [r/min]	M_2 [Nm]	c		g500	MF□MA□□	
1.9	228	7.9	301	45	301	1.3	76.271	-B450	071-42	41
1.6	268	6.7	353	39	353	1.1	89.534	-B450	071-42	41

Selection tables, 4-pole motors



120 Hz: P_N = 2.2 kW

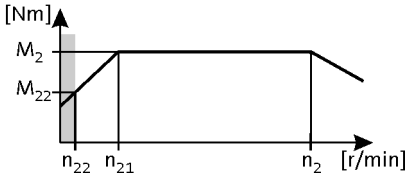
2-stage gearboxes

Inverter operation							i	Product		
5 Hz -		- 20 Hz		- 120 Hz (1:24)						
n_{22} [r/min]	M_{22} [Nm]	n_{21} [r/min]	M_2 [Nm]	n_2 [r/min]	M_2 [Nm]	c		g500	MF□MA□□	
23	27	96	36	559	36	3.3	6.257	-B240	080-32	38
16	39	66	52	385	52	1.2	9.101	-B110	080-32	35
14	45	57	60	334	60	1.1	10.466	-B110	080-32	35
13	49	52	65	306	65	1.0	11.449	-B110	080-32	35
12	52	50	69	290	69	2.3	12.081	-B240	080-32	38
11	59	44	78	255	78	2.1	13.719	-B240	080-32	38
9.7	64	40	86	233	86	2.0	15.008	-B240	080-32	38
8.6	72	36	96	208	96	1.9	16.857	-B240	080-32	38
7.6	82	31	109	183	109	1.7	19.143	-B240	080-32	38
7.0	88	29	118	170	118	1.5	20.650	-B240	080-32	38
6.2	100	26	134	149	134	1.4	23.450	-B240	080-32	38
5.4	115	22	153	130	153	1.2	26.878	-B240	080-32	38
4.8	131	20	174	115	174	1.0	30.522	-B240	080-32	38

3-stage gearboxes

Inverter operation							i	Product		
5 Hz -		- 20 Hz		- 120 Hz (1:24)						
n_{22} [r/min]	M_{22} [Nm]	n_{21} [r/min]	M_2 [Nm]	n_2 [r/min]	M_2 [Nm]	c		g500	MF□MA□□	
7.3	85	30	113	177	113	3.0	19.831	-B450	080-32	41
6.4	98	26	130	153	130	2.6	22.813	-B450	080-32	41
5.7	108	24	144	138	144	2.4	25.294	-B450	080-32	41
5.2	119	22	159	125	159	2.1	27.945	-B450	080-32	41
4.7	132	19	177	113	177	1.9	30.985	-B450	080-32	41
4.0	156	17	207	96	207	1.6	36.373	-B450	080-32	41
3.6	172	15	230	87	230	1.7	40.330	-B450	080-32	41
3.2	193	13	258	77	258	1.5	45.245	-B450	080-32	41
2.9	214	12	286	70	286	1.4	50.167	-B450	080-32	41
2.6	240	11	320	62	320	1.2	56.154	-B450	080-32	41
2.3	266	9.6	355	56	355	1.1	62.262	-B450	080-32	41

Selection tables, 4-pole motors



120 Hz: P_N = 3.0 kW

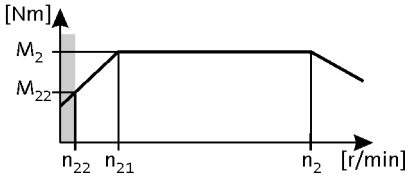
2-stage gearboxes

Inverter operation							i	Product		
5 Hz -		- 30 Hz		- 120 Hz (1:24)						
n_{22} [r/min]	M_{22} [Nm]	n_{21} [r/min]	M_2 [Nm]	n_2 [r/min]	M_2 [Nm]	c		g500	MF□MA□□	
23	37	144	49	556	49	2.4	6.257	-B240	080-42	38
12	71	75	94	288	94	1.7	12.081	-B240	080-42	38
11	81	66	107	254	107	1.5	13.719	-B240	080-42	38
9.7	88	60	117	232	117	1.4	15.008	-B240	080-42	38
8.6	99	53	132	206	132	1.4	16.857	-B240	080-42	38
7.6	112	47	150	182	150	1.2	19.143	-B240	080-42	38
7.0	121	44	162	169	162	1.1	20.650	-B240	080-42	38

3-stage gearboxes

Inverter operation							i	Product		
5 Hz -		- 30 Hz		- 120 Hz (1:24)						
n_{22} [r/min]	M_{22} [Nm]	n_{21} [r/min]	M_2 [Nm]	n_2 [r/min]	M_2 [Nm]	c		g500	MF□MA□□	
8.9	96	55	128	213	128	2.6	16.349	-B450	080-42	41
8.1	105	50	140	195	140	2.4	17.885	-B450	080-42	41
7.3	116	45	155	176	155	2.2	19.831	-B450	080-42	41
6.4	134	40	178	153	178	1.9	22.813	-B450	080-42	41
5.7	148	36	198	138	198	1.7	25.294	-B450	080-42	41
5.2	164	32	219	125	219	1.6	27.945	-B450	080-42	41
4.7	182	29	242	112	242	1.4	30.985	-B450	080-42	41
4.0	213	25	284	96	284	1.2	36.373	-B450	080-42	41
3.6	237	22	315	86	315	1.2	40.330	-B450	080-42	41
3.2	265	20	354	77	354	1.1	45.245	-B450	080-42	41

Selection tables, 4-pole motors



120 Hz: P_N = 4.0 kW

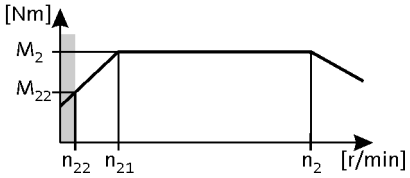
2-stage gearboxes

Inverter operation							i	Product		
5 Hz -		- 20 Hz		- 120 Hz (1:24)						
n_{22} [r/min]	M_{22} [Nm]	n_{21} [r/min]	M_2 [Nm]	n_2 [r/min]	M_2 [Nm]	c		g500	MF□MA□□	
23	46	96	65	556	65	1.8	6.257	-B240	090-32	38
8.6	123	36	176	206	176	1.0	16.857	-B240	090-32	38

3-stage gearboxes

Inverter operation							i	Product		
5 Hz -		- 20 Hz		- 120 Hz (1:24)						
n_{22} [r/min]	M_{22} [Nm]	n_{21} [r/min]	M_2 [Nm]	n_2 [r/min]	M_2 [Nm]	c		g500	MF□MA□□	
8.9	119	37	170	213	170	1.9	16.349	-B450	090-32	41
8.1	131	34	186	195	186	1.8	17.885	-B450	090-32	41
7.3	145	30	207	176	207	1.6	19.831	-B450	090-32	41
6.4	167	26	238	153	238	1.4	22.813	-B450	090-32	41
5.7	185	24	264	138	264	1.3	25.294	-B450	090-32	41
5.2	204	22	291	125	291	1.2	27.945	-B450	090-32	41
4.7	226	19	323	112	323	1.1	30.985	-B450	090-32	41

Selection tables, 4-pole motors



120 Hz: P_N = 5.5 kW

3-stage gearboxes

Inverter operation							i	Product		
5 Hz -		- 20 Hz		- 120 Hz (1:24)						
n_{22} [r/min]	M_{22} [Nm]	n_{21} [r/min]	M_2 [Nm]	n_2 [r/min]	M_2 [Nm]	c		g500	MF□MA□□	
6.4	226	26	323	155	323	1.1	22.813	-B450	100-12	41

Dimensions, notes

Notes on the dimensions

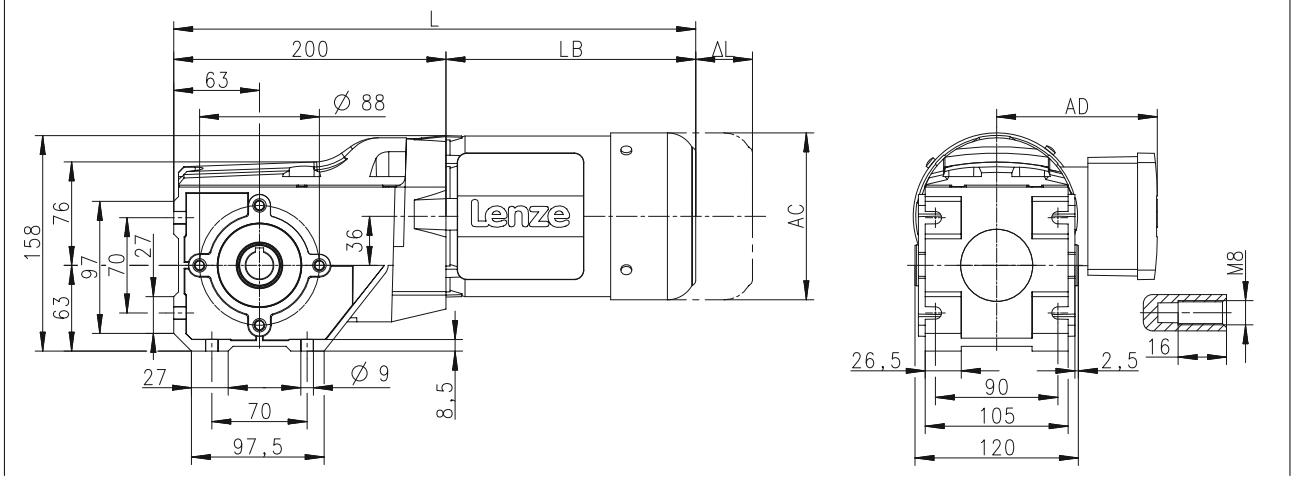
The following legend shows the layout of the dimension sheets.

Product gearbox

g500-B110

Driven shaft design

Abmessungen mit Hohlwelle



Product Motor

Produkt			MD□MA□□							
			063-12	063-32	063-42	071-32	071-42	080-32	080-42	090-32
Abmessungen										
Gesamtlänge	**L**	**[mm]**		358		378		395		419
Länge Motor	**LB**	**[mm]**		187		207		224.5		248
Länge Motoranbauten	**Δ L**	**[mm]**		170		165		183		181
Motordurchmesser	**AC**	**[mm]**		123		139		156		176
Abstand Motor/Anschluss	**AD**	**[mm]**		100		109		150		157

Distance of motor centre to the end of terminal box

Total length of the drive without built-on accessories

Motor diameter

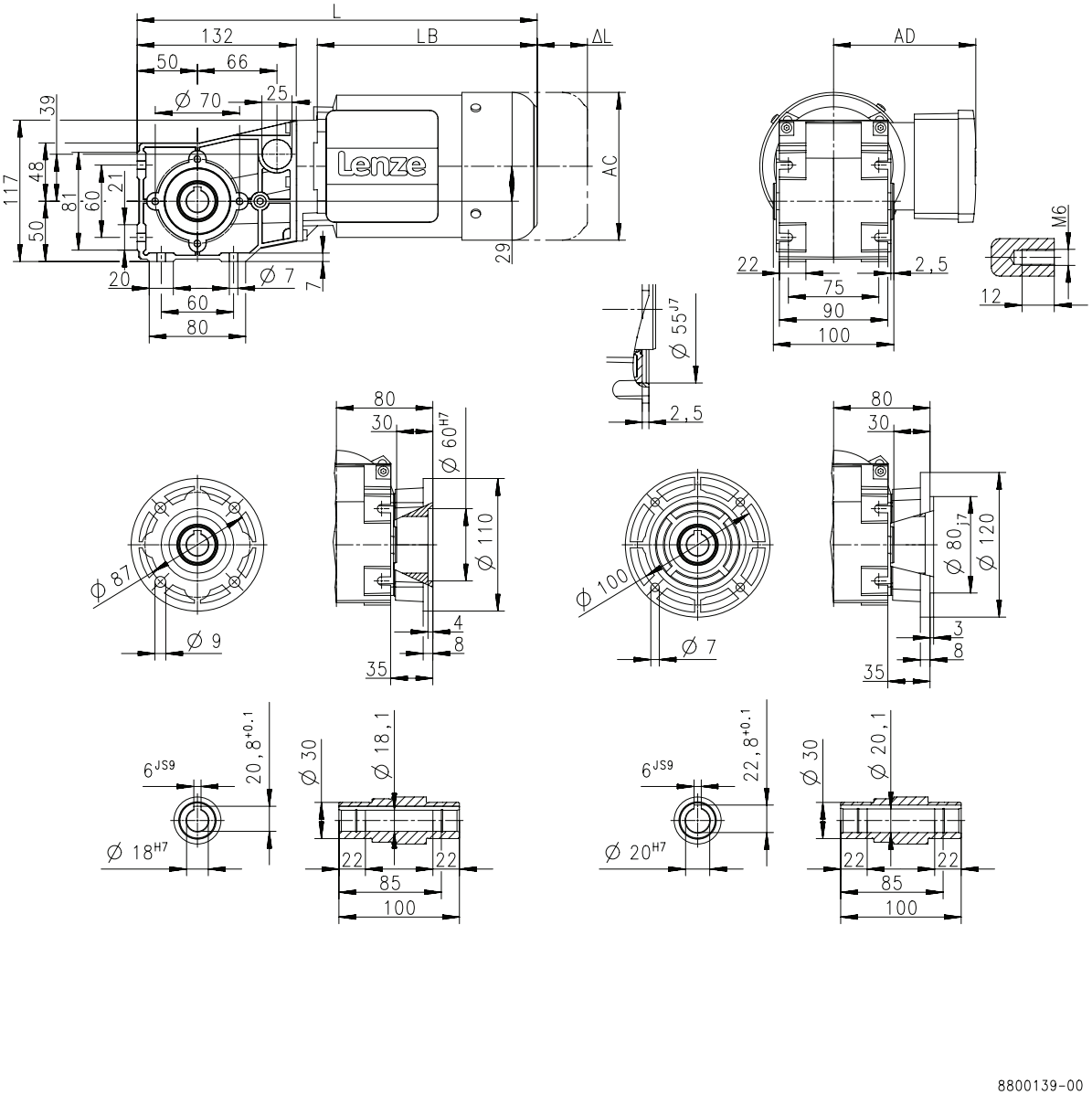
Motor length without built-on accessories

Additional length of the built-on accessories (longest version)

Dimensions, 4-pole motors

g500-B45

Dimensions with hollow shaft

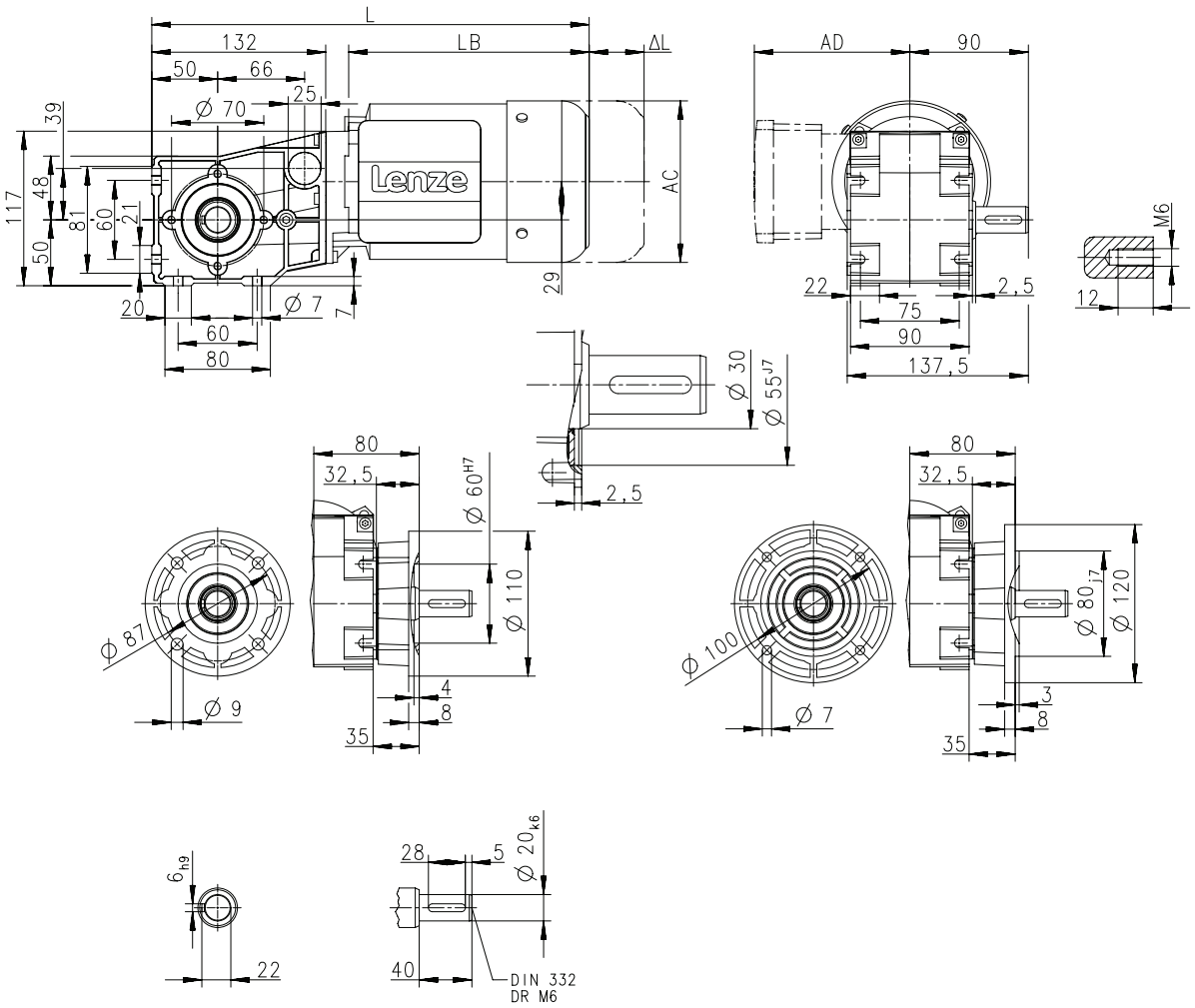


Product			MF□MA□□	
			063-32	063-42
Dimensions				
Total length	**L**	**[mm]**	332	
Motor length	**LB**	**[mm]**	183	
Length of motor options	**Δ L**	**[mm]**	170	
Motor diameter	**AC**	**[mm]**	123	
Distance motor/connection	**AD**	**[mm]**	100	

Dimensions, 4-pole motors

g500-B45

Dimensions with solid shaft

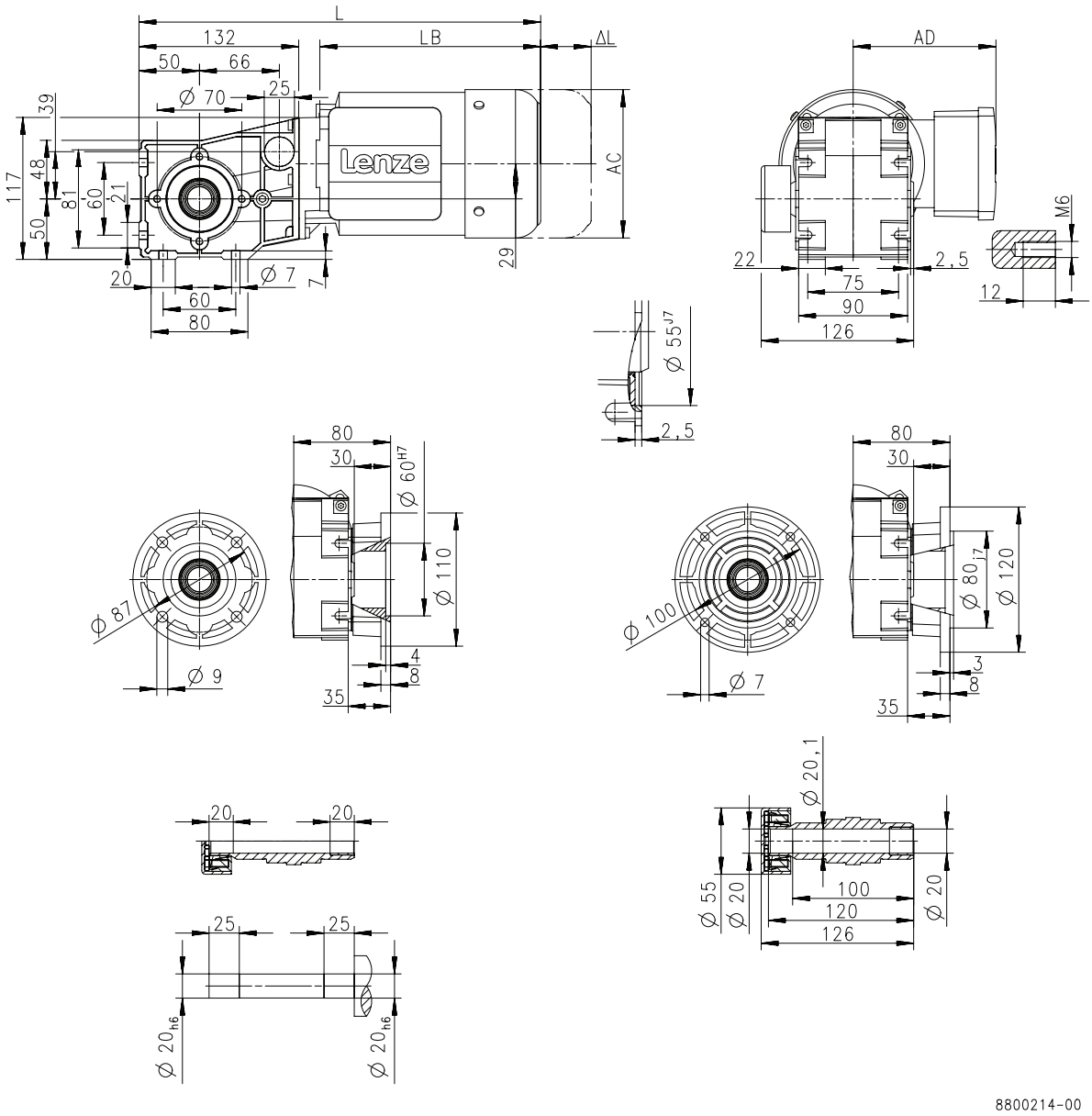


Product			MF□MA□□	
			063-32	063-42
Dimensions				
Total length	**L**	**[mm]**	332	
Motor length	**LB**	**[mm]**	183	
Length of motor options	**Δ L**	**[mm]**	170	
Motor diameter	**AC**	**[mm]**	123	
Distance motor/connection	**AD**	**[mm]**	100	

Dimensions, 4-pole motors

g500-B45

Dimensions with shrink disc

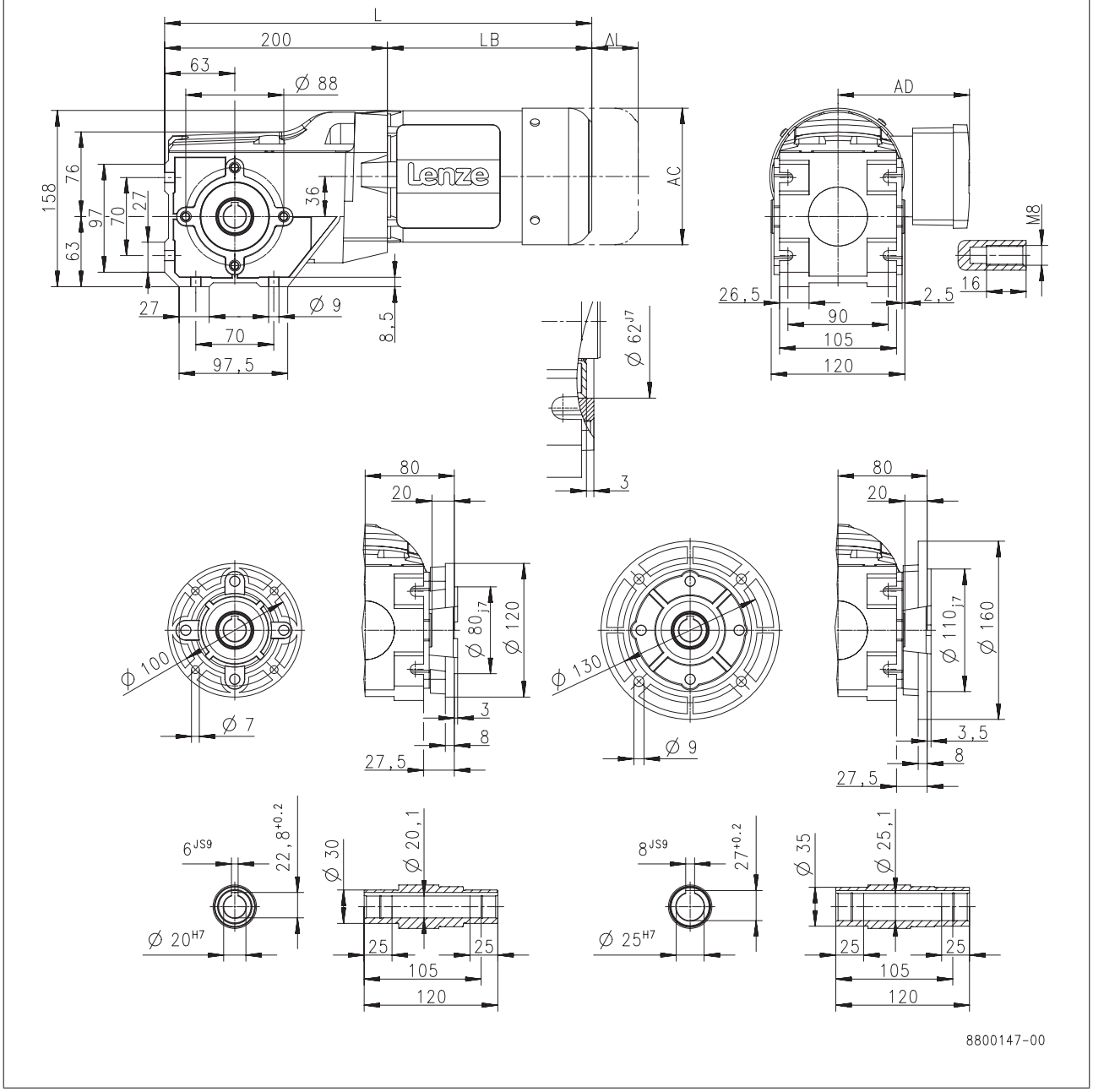


Product			MF□MA□□	
			063-32	063-42
Dimensions				
Total length	**L**	**[mm]**	332	
Motor length	**LB**	**[mm]**	183	
Length of motor options	**Δ L**	**[mm]**	170	
Motor diameter	**AC**	**[mm]**	123	
Distance motor/connection	**AD**	**[mm]**	100	

Dimensions, 4-pole motors

g500-B110

Dimensions with hollow shaft

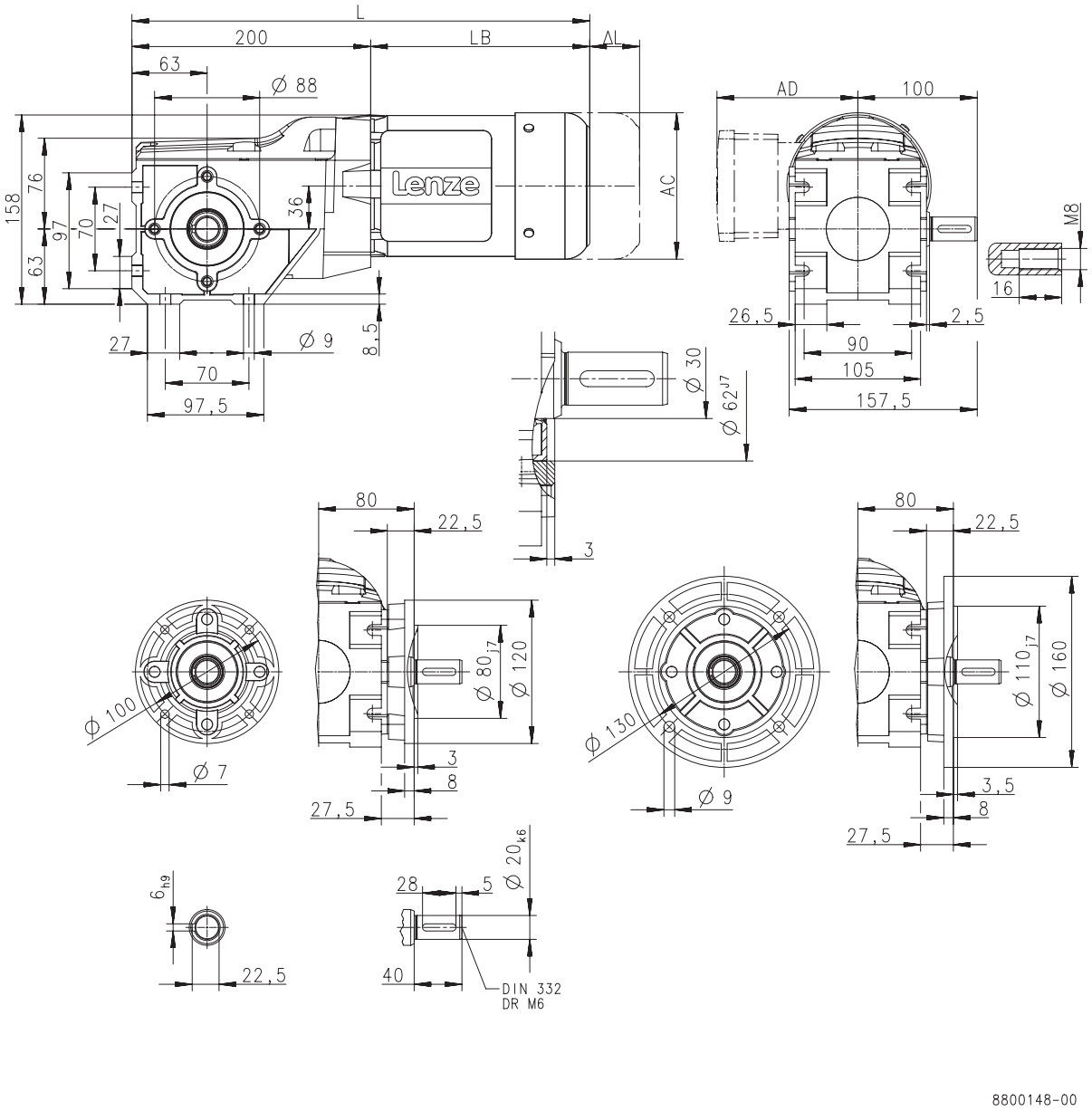


Product			MF□MA□□				
			063-32	063-42	071-32	071-42	080-32
Dimensions							
Total length	**L**	**[mm]**	383		403		426
Motor length	**LB**	**[mm]**	183		203		226
Length of motor options	**Δ L**	**[mm]**	170		165		183
Motor diameter	**AC**	**[mm]**	123		139		156
Distance motor/connection	**AD**	**[mm]**	100		109		150

Dimensions, 4-pole motors

g500-B110

Dimensions with solid shaft

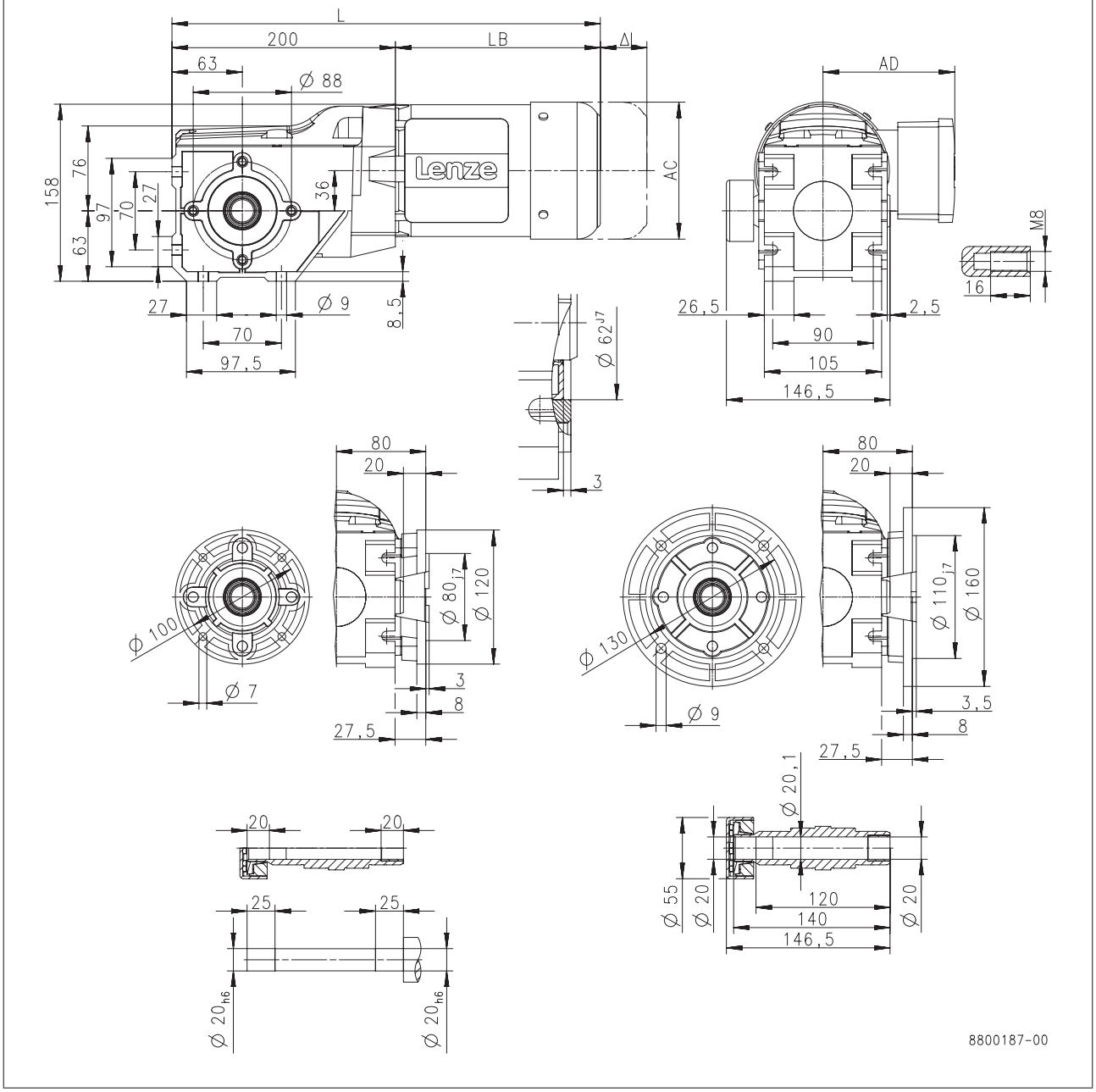


Product			MF□MA□□				
			063-32	063-42	071-32	071-42	080-32
Dimensions							
Total length	**L**	**[mm]**	383		403		426
Motor length	**LB**	**[mm]**	183		203		226
Length of motor options	**Δ L**	**[mm]**	170		165		183
Motor diameter	**AC**	**[mm]**	123		139		156
Distance motor/connection	**AD**	**[mm]**	100		109		150

Dimensions, 4-pole motors

g500-B110

Dimensions with shrink disc

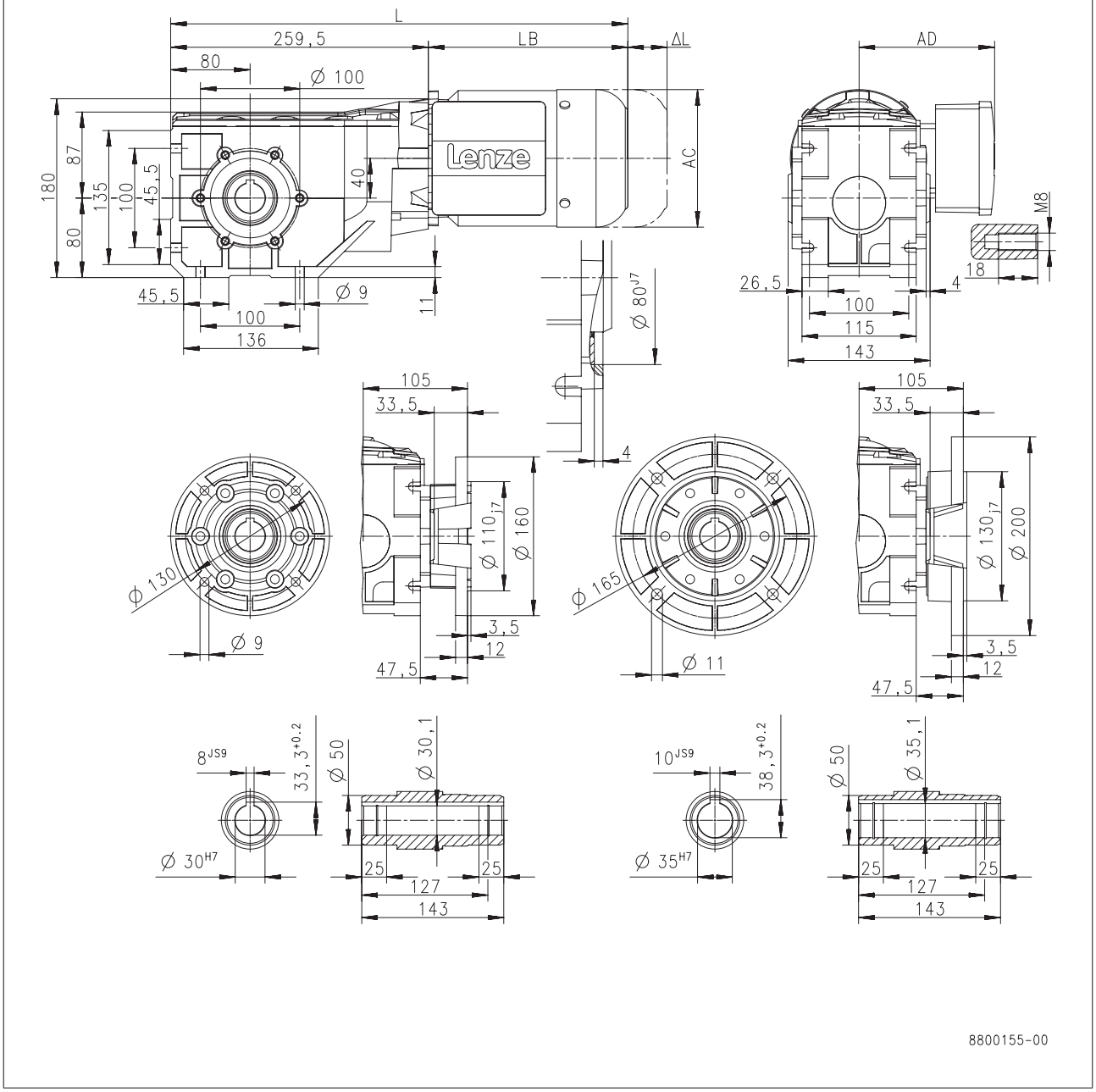


Product			MF□MA□□				
			063-32	063-42	071-32	071-42	080-32
Dimensions							
Total length	**L**	**[mm]**	383		403		426
Motor length	**LB**	**[mm]**	183		203		226
Length of motor options	**Δ L**	**[mm]**	170		165		183
Motor diameter	**AC**	**[mm]**	123		139		156
Distance motor/connection	**AD**	**[mm]**	100		109		150

Dimensions, 4-pole motors

g500-B240

Dimensions with hollow shaft

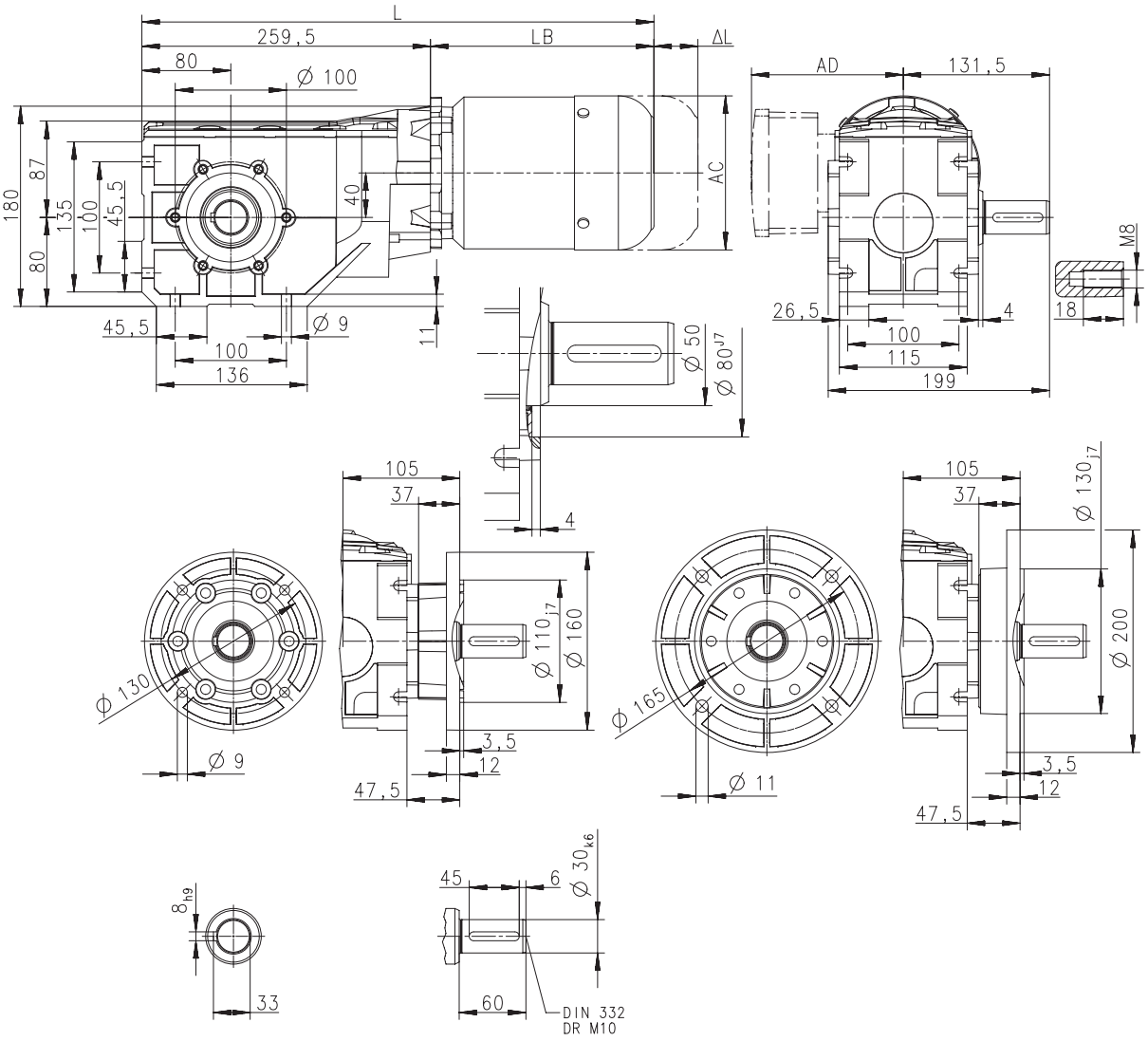


Product			MF□MA□□						
			063-32	063-42	071-32	071-42	080-32	080-42	090-32
Dimensions									
Total length	**L**	**[mm]**	443		463		486		534
Motor length	**LB**	**[mm]**	183		203		226		274
Length of motor options	**Δ L**	**[mm]**	170		165		183		181
Motor diameter	**AC**	**[mm]**	123		139		156		176
Distance motor/connection	**AD**	**[mm]**	100		109		150		157

Dimensions, 4-pole motors

g500-B240

Dimensions with solid shaft

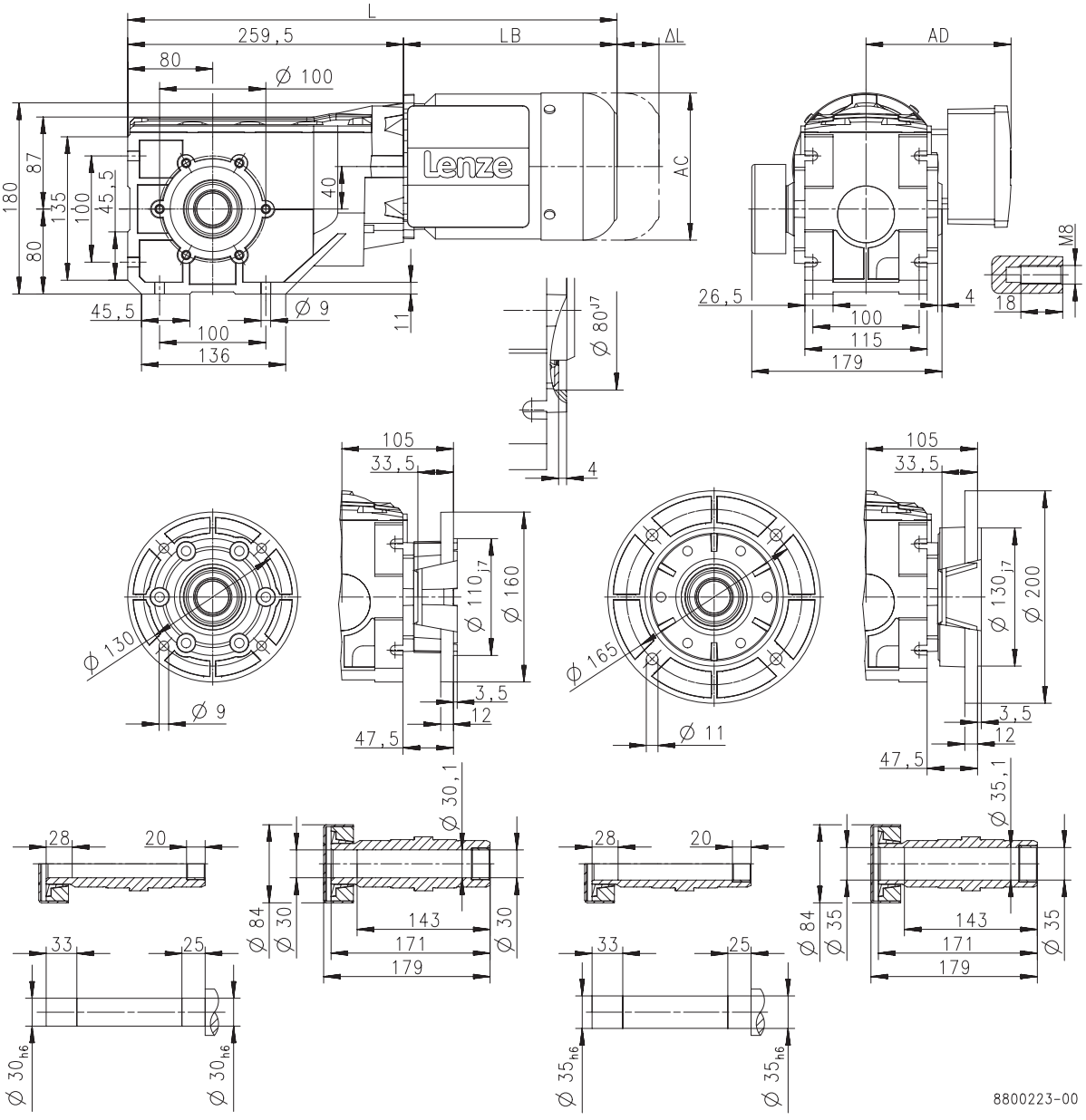


Product			MF□MA□□						
			063-32	063-42	071-32	071-42	080-32	080-42	090-32
Dimensions									
Total length	**L**	**[mm]**	443		463		486		534
Motor length	**LB**	**[mm]**	183		203		226		274
Length of motor options	**Δ L**	**[mm]**	170		165		183		181
Motor diameter	**AC**	**[mm]**	123		139		156		176
Distance motor/connection	**AD**	**[mm]**	100		109		150		157

Dimensions, 4-pole motors

g500-B240

Dimensions with shrink disc

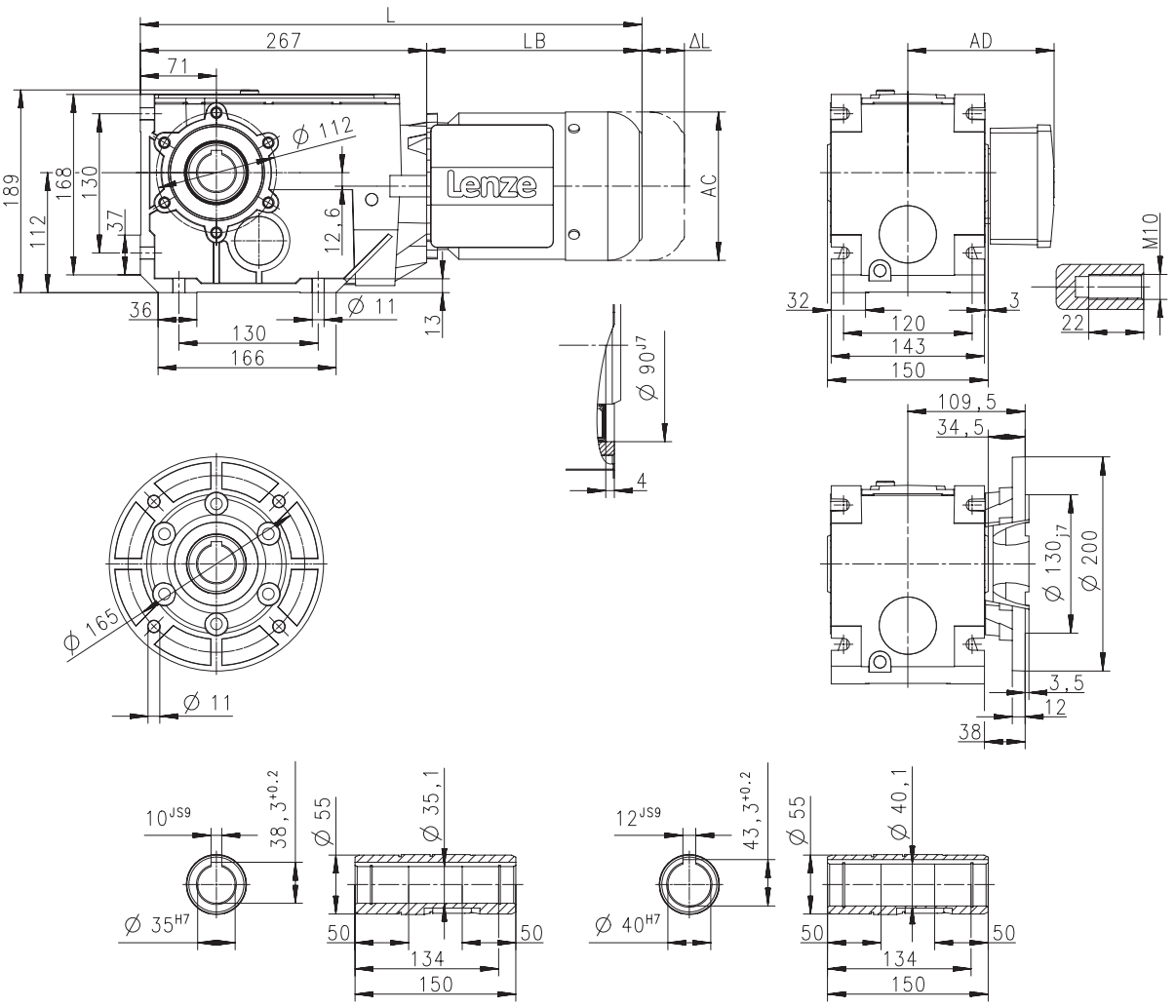


Product			MF□MA□□						
			063-32	063-42	071-32	071-42	080-32	080-42	090-32
Dimensions									
Total length	**L**	**[mm]**	443		463		486		534
Motor length	**LB**	**[mm]**	183		203		226		274
Length of motor options	**Δ L**	**[mm]**	170		165		183		181
Motor diameter	**AC**	**[mm]**	123		139		156		176
Distance motor/connection	**AD**	**[mm]**	100		109		150		157

Dimensions, 4-pole motors

g500-B450

Dimensions with hollow shaft

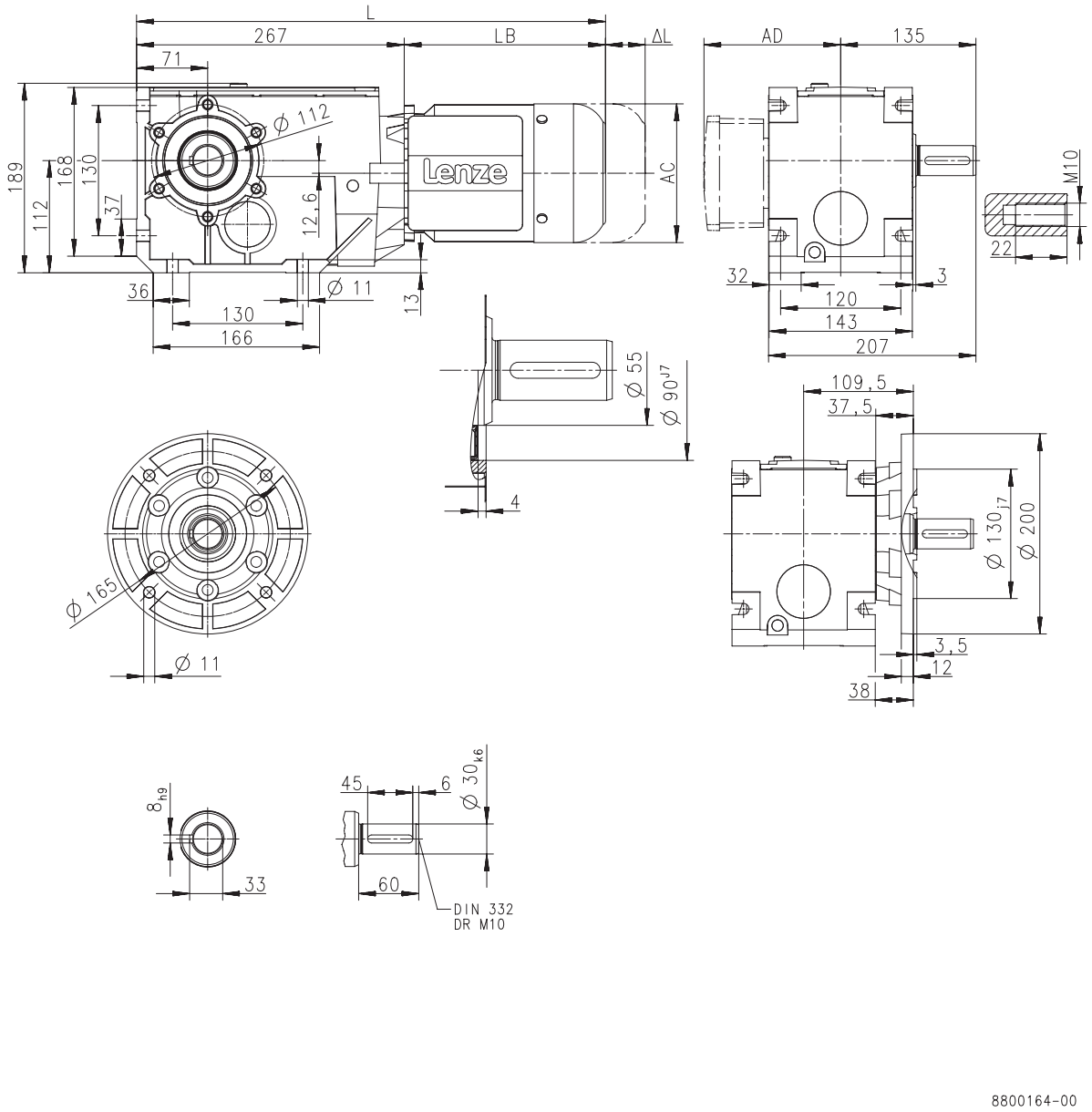


Product			MF□MA□□							
			063-32	063-42	071-32	071-42	080-32	080-42	090-32	100-12
Dimensions										
Total length	**L**	**[mm]**	450		470		493		541	588
Motor length	**LB**	**[mm]**	183		203		226		274	321
Length of motor options	**Δ L**	**[mm]**	170		165		183		181	170
Motor diameter	**AC**	**[mm]**	123		139		156		176	194
Distance motor/connection	**AD**	**[mm]**	100		109		150		157	166

Dimensions, 4-pole motors

g500-B450

Dimensions with solid shaft

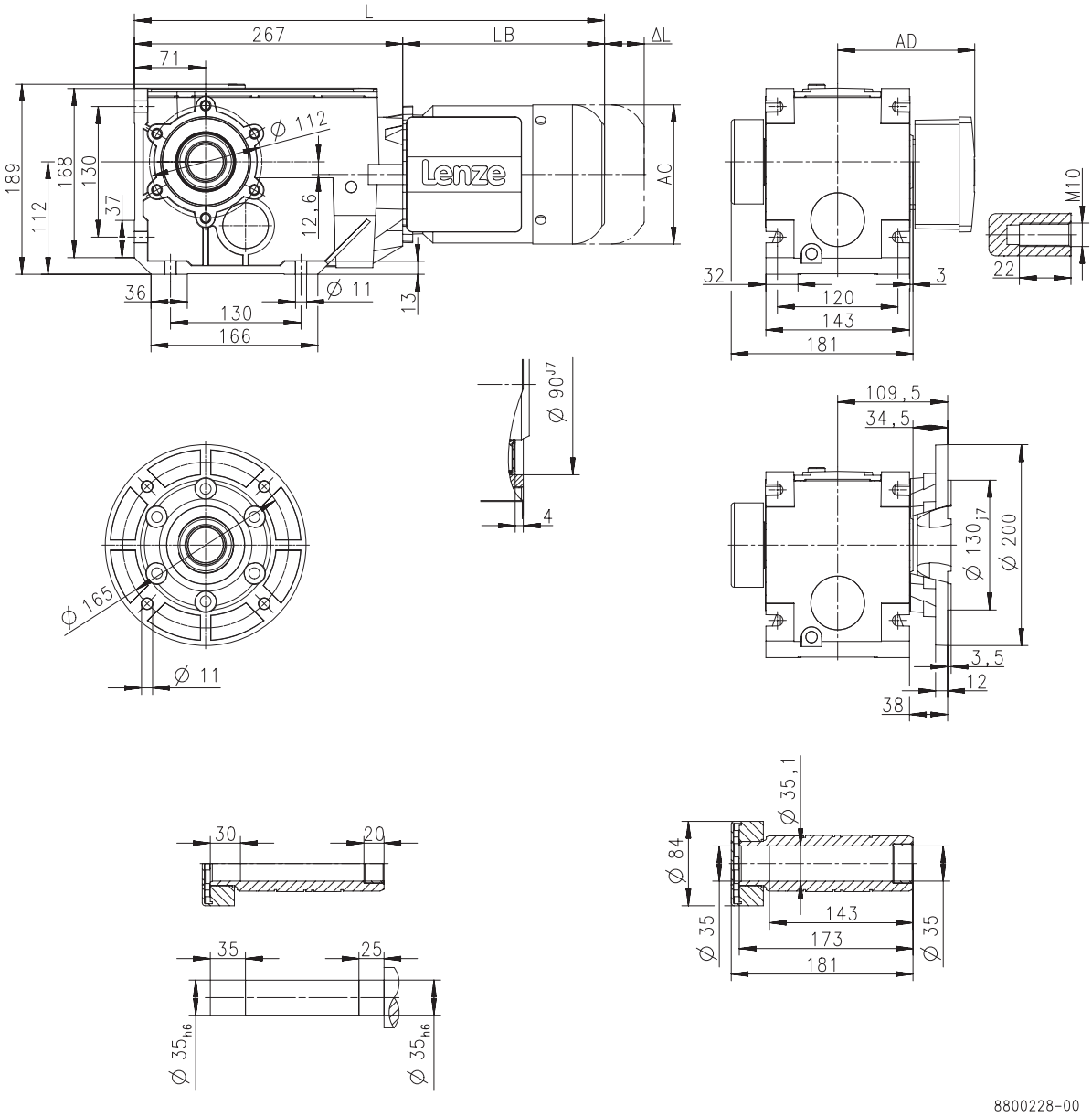


Product			MF□MA□□							
			063-32	063-42	071-32	071-42	080-32	080-42	090-32	100-12
Dimensions										
Total length	**L**	**[mm]**	450		470		493		541	588
Motor length	**LB**	**[mm]**	183		203		226		274	321
Length of motor options	**Δ L**	**[mm]**	170		165		183		181	170
Motor diameter	**AC**	**[mm]**	123		139		156		176	194
Distance motor/connection	**AD**	**[mm]**	100		109		150		157	166

Dimensions, 4-pole motors

g500-B450

Dimensions with shrink disc



Product			MF□MA□□							
			063-32	063-42	071-32	071-42	080-32	080-42	090-32	100-12
Dimensions										
Total length	**L**	**[mm]**	450		470		493		541	588
Motor length	**LB**	**[mm]**	183		203		226		274	321
Length of motor options	**Δ L**	**[mm]**	170		165		183		181	170
Motor diameter	**AC**	**[mm]**	123		139		156		176	194
Distance motor/connection	**AD**	**[mm]**	100		109		150		157	166

Weights, 4-pole motors

2-stage gearboxes

				MF□MA□□				
				063-32 063-42	071-32 071-42	080-32	080-42	090-32
g500	-B45	m	[kg]	7.3				
	-B110	m	[kg]	8.9	11	15		
	-B240	m	[kg]	13	15	19		26

3-stage gearboxes

				MF□MA□□				
				063-32 063-42	071-32 071-42	080-32 080-42	090-32	100-12
g500	-B240	m	[kg]	13				
	-B450	m	[kg]	16	18	22	29	38

Surface and corrosion protection

For optimum protection of geared motors against ambient conditions, the surface and corrosion protection system (OKS) offers tailor-made solutions.

Various surface coatings combined with other protective measures ensure that the geared motors operate reliably even at high air humidity, in outdoor installations or in the presence of atmospheric impurities. Any colour from the RAL Classic collection can be chosen for the top coat. The geared motors are also available unpainted (no surface and corrosion protection).

Surface and corrosion protection	Applications	Measures
OKS-G (primed)	• Dependent on subsequent top coat applied	• 2K PUR priming coat (grey) • Zinc-coated screws • Rust-free breather elements Optional measures • Stainless steel nameplate
OKS-S (small)	• Standard applications • Internal installation in heated buildings • Air humidity up to 90%	• Surface coating as per corrosivity category C1 (in line with EN 12944-2) • Zinc-coated screws • Rust-free breather elements Optional measures • Stainless steel nameplate
OKS-M (medium)	• Internal installation in non-heated buildings • Covered, protected external installation • Air humidity up to 95%	• Surface coating as per corrosivity category C2 (in line with EN 12944-2) • Zinc-coated screws • Rust-free breather elements Optional measures • Stainless steel shaft • Stainless steel nameplate • Rust-free shrink disc (on request)
OKS-L (large)	• External installation • Air humidity above 95% • Chemical industry plants • Food industry	• Surface coating as per corrosivity category C3 (in line with EN 12944-2) • Blower cover and B end shield additionally primed • Cable glands with gaskets • Corrosion-resistant brake with cover ring, stainless friction plate, and chrome-plated armature plate (on request) • All screws/screw plugs zinc-coated • Stainless breather elements • Threaded holes that are not used are closed by means of plastic plugs Optional measures • Sealed recesses on motor (on request) • Stainless steel shaft • Stainless steel nameplate • Rust-free shrink disc (on request) • Additional priming coat on cast iron fan • Oil expansion tank and torque plates painted separately and supplied loose

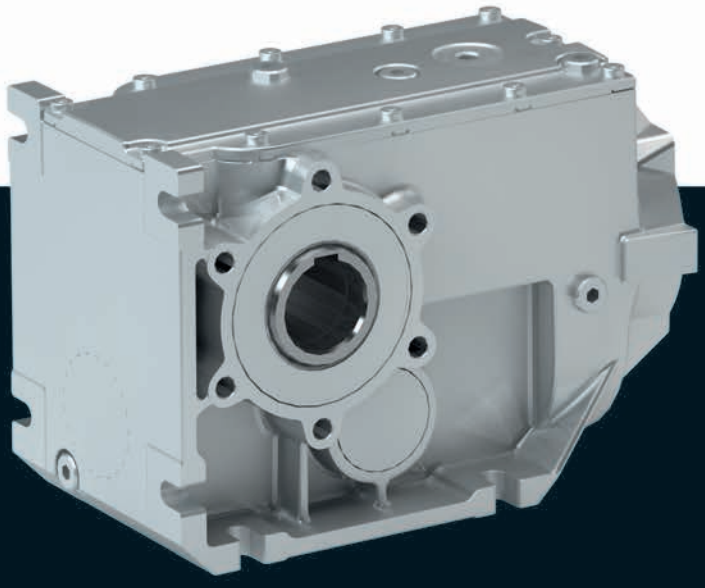
Surface and corrosion protection

Structure of surface coating

Surface and corrosion protection	Corrosivity category	Surface coating	Colour
	DIN EN ISO 12944-2	Structure	
Without OKS(uncoated)		Dipping primed gearbox	
OKS-G (primed)		Dipping primed gearbox 2K PUR priming coat	
OKS-S (small)	C1	Dipping primed gearbox 2K-PUR top coat	Standard: RAL 7012 Optional: RAL Classic
OKS-M (medium)	C2	Dipping primed gearbox 2K PUR priming coat 2K-PUR top coat	
OKS-L (large)	C3		

g500-B bevel gearboxes

45 to 450 Nm



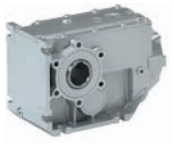
g500-B bevel gearbox

Contents

Contents

List of abbreviations

$F_{ax,max}$	[N]	Max. axial force
$F_{rad,max}$	[N]	Max. radial force
i		Ratio
J	[kgcm²]	Moment of inertia
m	[kg]	Mass



Product information

The efficient bevel gearboxes feature high reliable radial forces, closely stepped gear reductions and a low backlash. They are available in 2-pole and 3-pole design with a torque up to 450 Nm and a ratio of up to i= 360.

Versions

- High-efficient right-angle gearbox in a compact design for space-saving installation
- Standardised shaft and flange dimensions for an easy machine integration
- Low backlash and high torsional stiffness provide for exact results in positioning applications

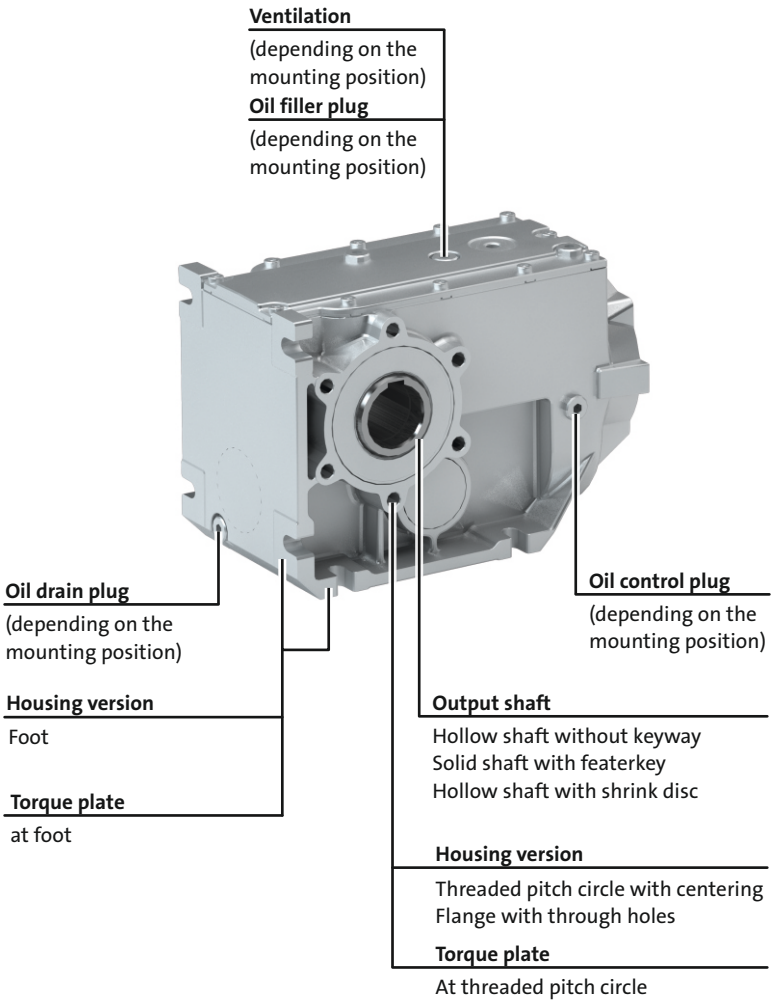
The product name

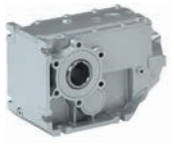
Gearbox type	Product range		Design	Rated torque [Nm]	Product
Bevel gearbox	g500	-	B	45	g500-B45
				110	g500-B110
				240	g500-B240
				450	g500-B450

Equipment

Overview

The equipment includes all the options available as standard and all the built-on accessories of the product.





The gearbox kit

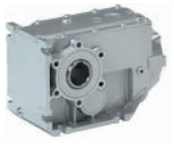
Gearbox details

Product	g500-B45	g500-B110	g500-B240	g500-B450
Driven shaft				
Solid shaft without keyway [mm]				
Solid shaft with featherkey [mm]	20x40		30x60	
Hollow shaft with keyway [mm]	18/20	20/25	30/35	35/40
Hollow shaft with shrink disc [mm]	20		30/35	35
Design	Standard stainless steel			
Gasket	Standard FPM (Viton)			
Bearing	Standard			
Fitting grease	Not enclosed Enclosed			
Housing				
Housing version	With foot With foot and centering			
Output flange				
flange diameter [mm]	110/120	120/160	160/200	200
Lubricant				
Type	CLP 460 [1)] CLP HC 320 CLP HC 220 CLP HC 220 USDA H1			
Oil-level inspection	Without inspection			Without inspection With inspection
Breather element	Without			Standard mounting position: Mounted Combined mounting position: loosely enclosed
Backlash				
Backlash	Standard			
Accessories				
Torque plate	Rubber buffers At threaded pitch circle	At threaded pitch circle	At threaded pitch circle At foot	At foot
Shaft cover	Hollow shaft Shrink disc: Rotating cover Shrink disc: Fixed cover			

6.7

[1)] Not suitable for geared servo motors.

► Further information and installation feasibilities can be found in the Gearboxes chapter.



The gearbox kit

Gearbox details

Solid shaft

Foot mounting
without centring

Foot mounting
With centering

Flange with through holes

Hollow shaft

Foot mounting
without centring

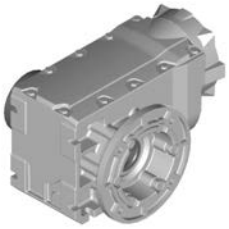
Foot mounting
With centering

Flange with through holes

Hollow shaft with shrink disc

Foot mounting
without centring

Foot mounting
With centering



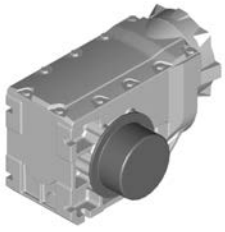
Flange with through holes

Accessories

2nd output shaft end

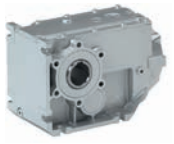
Torque plate
at foot

Torque plate
at threaded pitch circle



Cover
Hollow shaft/shrink disc

6.7

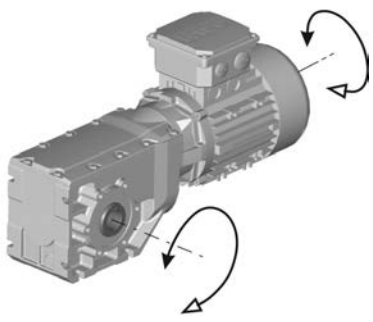
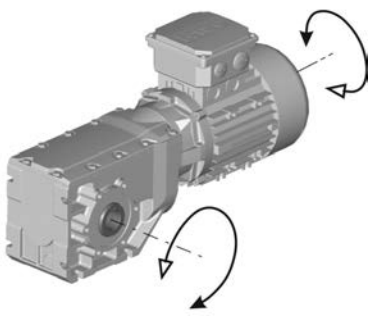


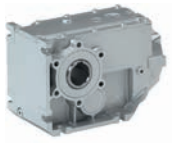
Functions and features

Product	g500-B45	g500-B110	g500-B240	g500-B450
Housing				
Design	Cuboid			
Material	Aluminium			
Solid shaft				
Design	with keyway to DIN 6885			
Tolerance	Shaft diameter ≤ 50 mm: k6 Shaft diameter > 50 mm: m6			
Material	Tempered steel C45 Nirosta X46Cr13			
Hollow shaft				
Design	With keyway Without keyway (for shrink disc)			
Tolerance	Bore H7			
Material	Tempered steel C45 Nirosta X46Cr13			
Toothed parts				
Design	Ground tooth flanks Optimised tooth flank geometry			
Material	Case-hardened steel			
Shaft-hub joint				
	1st and 2nd step: Force-fit 3rd step: positive-fit			
Shaft sealing rings				
Design	With dust lip			
Material	NB / FP			
Bearing				
Design	Ball bearing / tapered-roller bearing depending on size and design			
Lubricants				
	Standard: mineral oil Optional: synthetic oil [1]			
Quantities	Corresponding to mounting position (see nameplate)			
Mechanical efficiency				
2-stage gearboxes [$\eta_{c=1}$]	0.96			
3-stage gearboxes [$\eta_{c=1}$]			0.95	

[1] Standard for geared servo motors.

Direction of rotation

2-stage gearboxes B45 ... B240 3-stage gearbox B450	3-stage gearbox B240
	



Lubricants

Lenze gearboxes and geared motors are ready for operation on delivery and are filled with lubricants specific to both the drive and the design. The mounting position and design specified in the order are key factors in choosing the volume of lubricant.

The lubricants listed in the lubricant table are approved for use in Lenze drives.

Lubricant table

Mode	CLP 460	CLP HC 320	CLP HC 220 USDA H1
Ambient temperature [°C]	0 ... +40	-25 ... +50	-20 ... +40
Specification	Mineral based oil with additives	Synthetic-based oil (synthetic hydrocarbon / poly-alpha-olefin oil)	
Changing interval	16000 operating hours not later than after three years (oil temperature 70 to 80 °C)	25000 operating hours not later than after three years (oil temperature 70 to 80 °C)	16000 operating hours not later than after three years (oil temperature 70 to 80 °C)
Fuchs	Fuchs Renolin CLP 460	Fuchs Renolin Unisyn CLP 320	bremer & leguil Cassida Fluid GL 220
Klüber	Klüberoil GEM1-460 N	Klübersynth GEM4-320 N	Klüberoil 4 UH1-220 N
Shell	Shell Omala S2 G 460	Shell Omala S4 GX HD 320	

► Please contact your Lenze sales office if you are operating at ambient temperatures in areas up to< -20 °C bzw. > or up to +40°C.

Shaft sealing rings

By default, the gearboxes come with NBR shaft sealing rings at the output end. At high speed and unfavourable ambient conditions as high temperature, reduced circulation of air etc., Lenze recommends the use of Viton shaft sealing rings.

Please consider this in your order.

Ventilation

Non-ventilated gearboxes

No ventilation is required for gearboxes g500-B45 to B240.

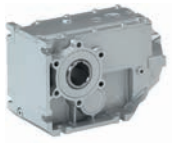
Ventilated gearboxes

The g500-B450 gearbox is supplied with a breather element as standard.

Gearboxes in combined mounting position

To reduce the number of different versions, the gearboxes can also be ordered with combined mounting positions.
Depending on the gearbox in question, the following combinations are available:
- g500-B45 in combined mounting position ABCDEF
- g500-B110 ... B450 in combined mounting position AEF

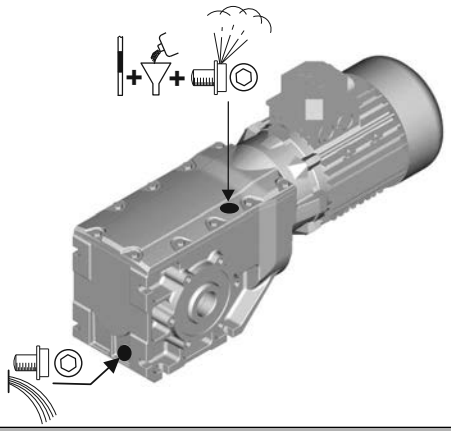
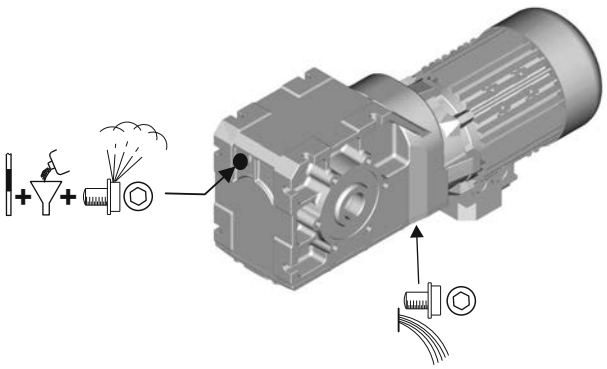
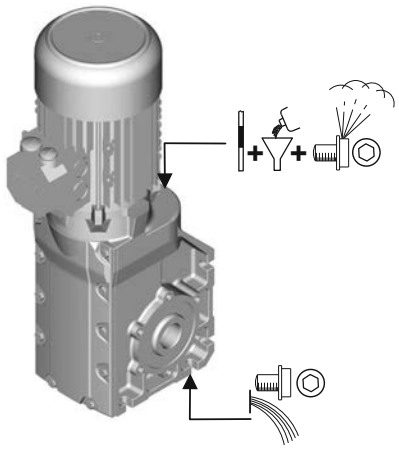
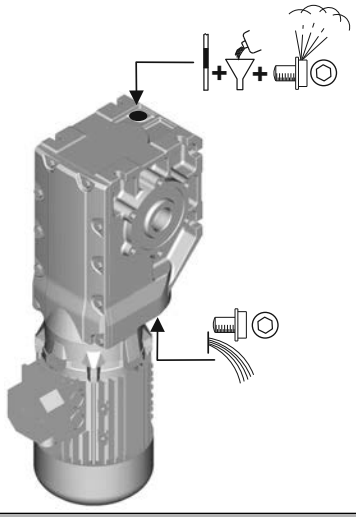
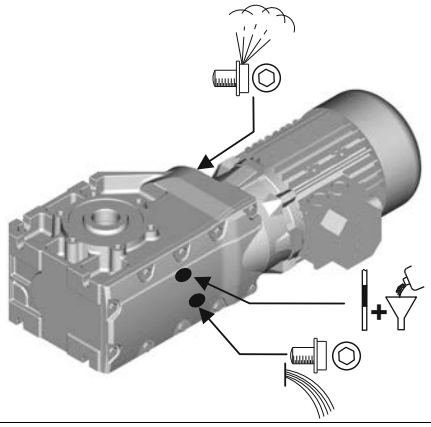
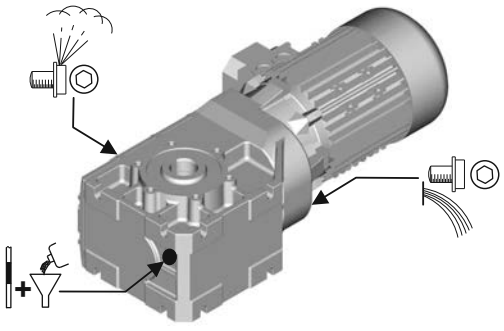
The breather elements are supplied loose.



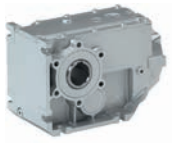
Ventilation

g500-B240

► **A ... F** mounting position

A	B
	
C	**D**
	
E	**F**
	

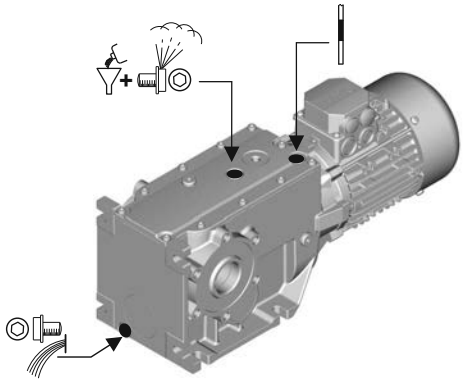
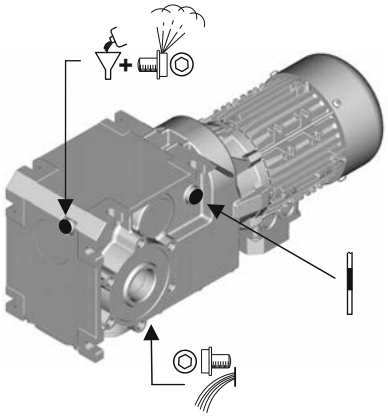
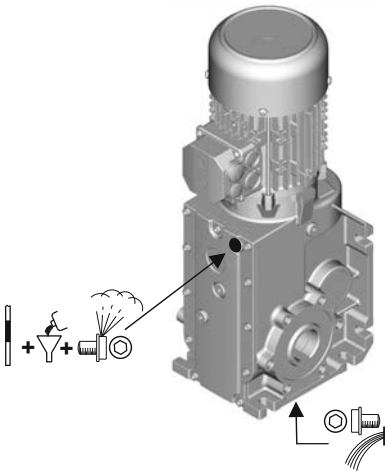
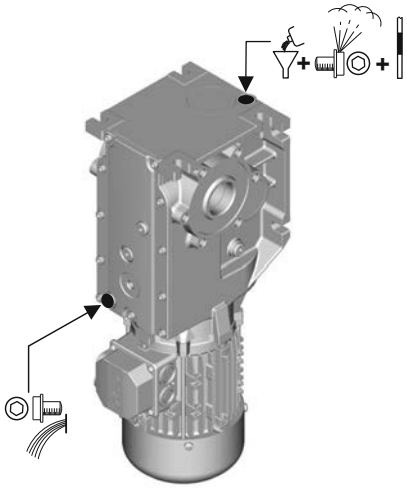
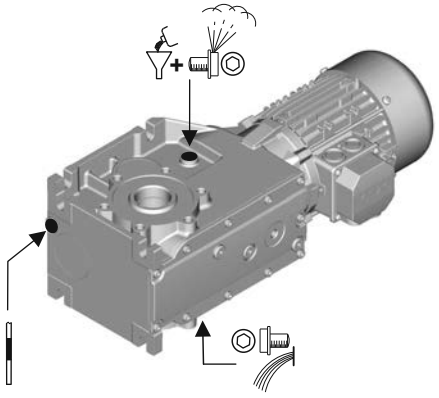
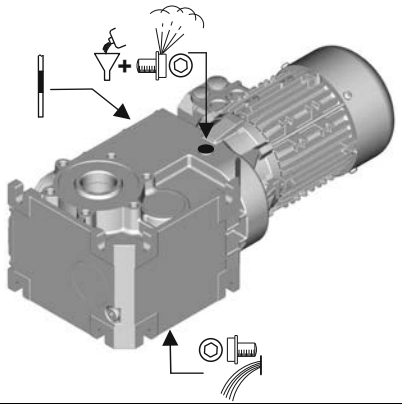
	Filler		Drain
	Breather element		Check



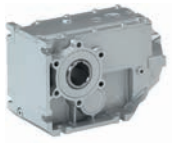
Ventilation

g500-B450

► **A ... F** mounting position

A	B
	
C	**D**
	
E	**F**
	

	Filler		Drain
	Breather element		Check



Permissible radial and axial forces at output

Permissible radial force

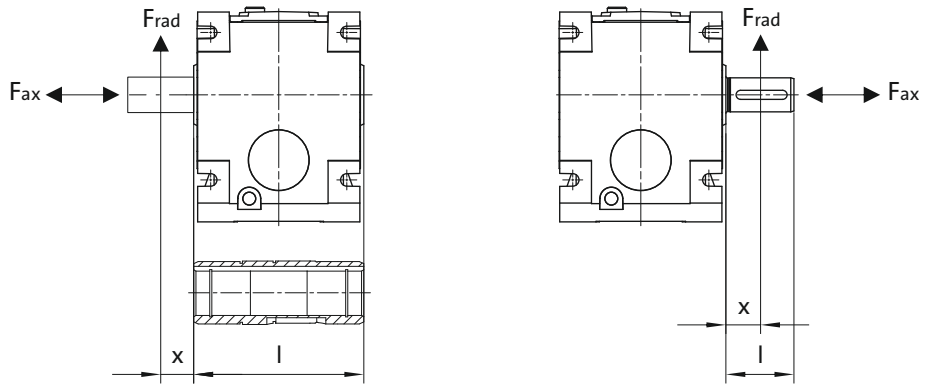
$F_{rad,perm} = f_w \times F_{rad,max}$

► If F_{rad} **and** $F_{ax} \neq 0$, please contact Lenze.

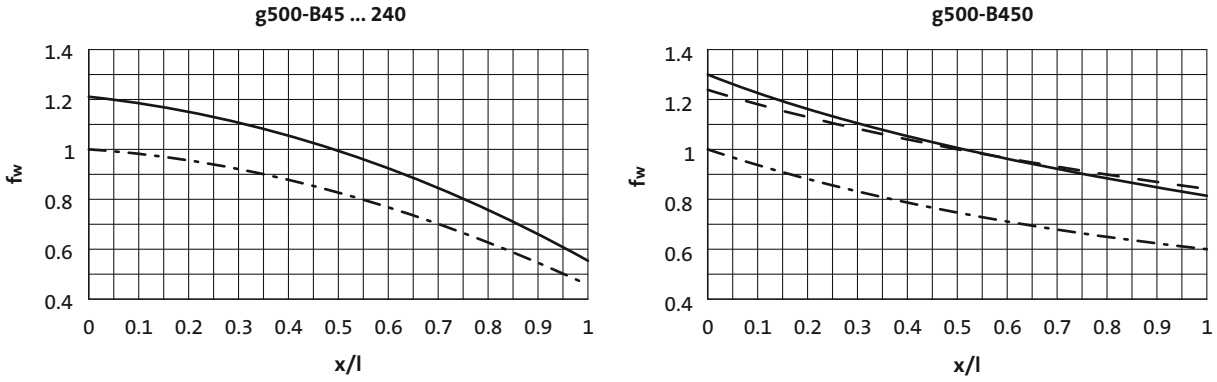
Permissible axial force

If there is no radial force, the maximum permissible axial force is 50 % of the table value $F_{rad,max}$

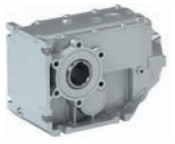
Application of forces



Additional load factor f_w at output shaft



——— Solid shaft
— — — Solid shaft with flange
— · — Hollow shaft



Permissible radial and axial forces at output

The values given in the table refer to the center shaft end force application point and are minimum values calculated according to the most unfavourable conditions (force application angle, mounting position, direction of rotation). The values were calculated for the motor/gearbox combination with a load capacity of c= 1.3 and an input speed of 1400 rpm.

- ► If the torque is transmitted via the flange face, max 50 % of the radial force $F_{rad,max}$ are permissible.
- ► Neither radial nor axial forces are permissible for the hollow shaft with shrink disc.

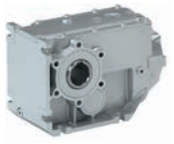
In case of different operating conditions, considerably higher forces can be transmitted. Please contact Lenze.

Product	n_2 [r/min]									
	1000	630	400	250	160	100	63	40	25	≤16

	Max. radial force, Hollow shaft									
	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$
	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]
g500-B45	900	1200	2200	2500	2800	3000	3000	3000	3000	3000
g500-B110	1000	2200	2550	3000	3300	3600	3600	3600	3600	3600
g500-B240	1500	2250	3800	4500	5100	6200	7400	7800	7800	7800
g500-B450	3000	3800	5000	5200	5200	5500	7000	9000	9000	9000

	Max. radial force, Solid shaft without flange									
	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$
	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]
g500-B45	900	1200	1800	2100	2400	2800	3000	3000	3000	3000
g500-B110	1000	1800	2100	2500	2700	3000	3000	3000	3000	3000
g500-B240	1500	2350	3000	3600	4500	5000	6000	6500	6500	6500
g500-B450	1800	2800	3600	4200	5100	6000	7200	7800	7800	7800

	Max. radial force, Solid shaft with flange									
	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$	$F_{rad,max}$
	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]	[N]
g500-B45	900	1200	1800	2100	2400	2800	3000	3000	3000	3000
g500-B110	1000	1800	2100	2500	2700	3000	3000	3000	3000	3000
g500-B240	2400	3600	5200	6000	6500	6500	6500	6500	6500	6500
g500-B450	3000	4000	5500	6200	7000	7500	7800	7800	7800	7800



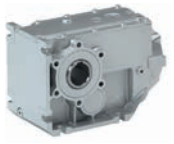
Moments of inertia

- The moments of inertia relate to the drive shaft of the gearbox.
- The total moment of inertia is calculated by adding the values of the gearbox, motor and accessories.

2-stage gearboxes

Product	Ratio	Moment of inertia
	i	J
		[kgcm²]
g500-B45	5.411	0.31
	6.222	0.28
	7.111	0.20
	8.178	0.18
	9.101	0.13
	10.466	0.12
	11.640	0.086
	13.386	0.079
	15.111	0.059
	17.378	0.055
	19.365	0.038
	22.270	0.054
	25.051	0.025
	28.808	0.023
	32.593	0.016
	37.481	0.015
	42.222	0.010
	48.556	0.009
	53.889	0.006
	61.972	0.006
g500-B110	5.185	0.79
	5.963	0.70
	7.111	0.48
	8.178	0.43
	9.101	0.32
	10.466	0.29
	11.449	0.26
	12.698	0.19
	14.603	0.18
	15.556	0.14
	17.889	0.13
	19.556	0.095
	22.489	0.088
	25.185	0.063
	28.963	0.060
	31.919	0.041
	36.707	0.039
	37.400	0.072
	40.000	0.028
	46.000	0.027
	48.167	0.050
	52.698	0.017
	60.603	0.016
	61.045	0.033
	76.500	0.023
	100.786	0.014

Product	Ratio	Moment of inertia
	i	J
		[kgcm²]
g500-B240	3.565	2.97
	4.889	1.74
	6.257	1.15
	6.883	1.67
	7.817	1.51
	9.440	1.05
	10.720	0.97
	12.081	0.73
	13.719	0.68
	15.008	0.59
	16.857	0.45
	19.143	0.42
	20.650	0.34
	23.450	0.32
	26.878	0.21
	30.522	0.20
	33.433	0.15
	37.967	0.15
	43.267	0.096
	49.133	0.092
	52.510	0.070
	59.630	0.067
	67.113	0.045
	76.213	0.043



Moments of inertia

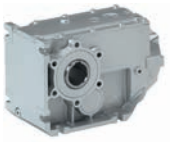
3-stage gearboxes

Product	Ratio	Moment of inertia
	i	J
		[kgcm²]
g500-B240	68.459	0.093
	77.741	0.091
	87.563	0.062
	99.437	0.061
	113.673	0.044
	129.087	0.043
	145.674	0.030
	165.426	0.030
	188.442	0.021
	213.994	0.020
	245.178	0.014
	278.422	0.014
	317.617	0.003
	360.683	0.003

Product	Ratio	Moment of inertia
	i	J
		[kgcm²]
g500-B450	5.002	4.36
	6.860	2.48
	9.315	3.21
	10.328	3.06
	12.775	1.87
	14.165	1.79
	16.349	1.23
	17.885	1.05
	19.831	1.01
	22.813	0.70
	25.294	0.68
	27.945	0.51
	30.985	0.49
	36.373	0.31
	40.330	0.30
	45.245	0.22
	50.167	0.21
	56.154	0.47
	62.262	0.47
	68.788	0.36
	76.271	0.36
	89.534	0.22
	99.274	0.22
	111.372	0.16
	123.487	0.16
	144.128	0.10
	159.807	0.099
	174.919	0.073
	193.948	0.072
	223.563	0.046
	247.882	0.046

Additional weights for gearboxes

Product			g500-B45	g500-B110	g500-B240	g500-B450
Mass						
Solid shaft	m	[kg]	0.4	0.5	1.4	1.3
Shrink disc	m	[kg]	0.2	0.2	0.7	0.6
Flange	m	[kg]	0.3	0.4	0.7	0.9



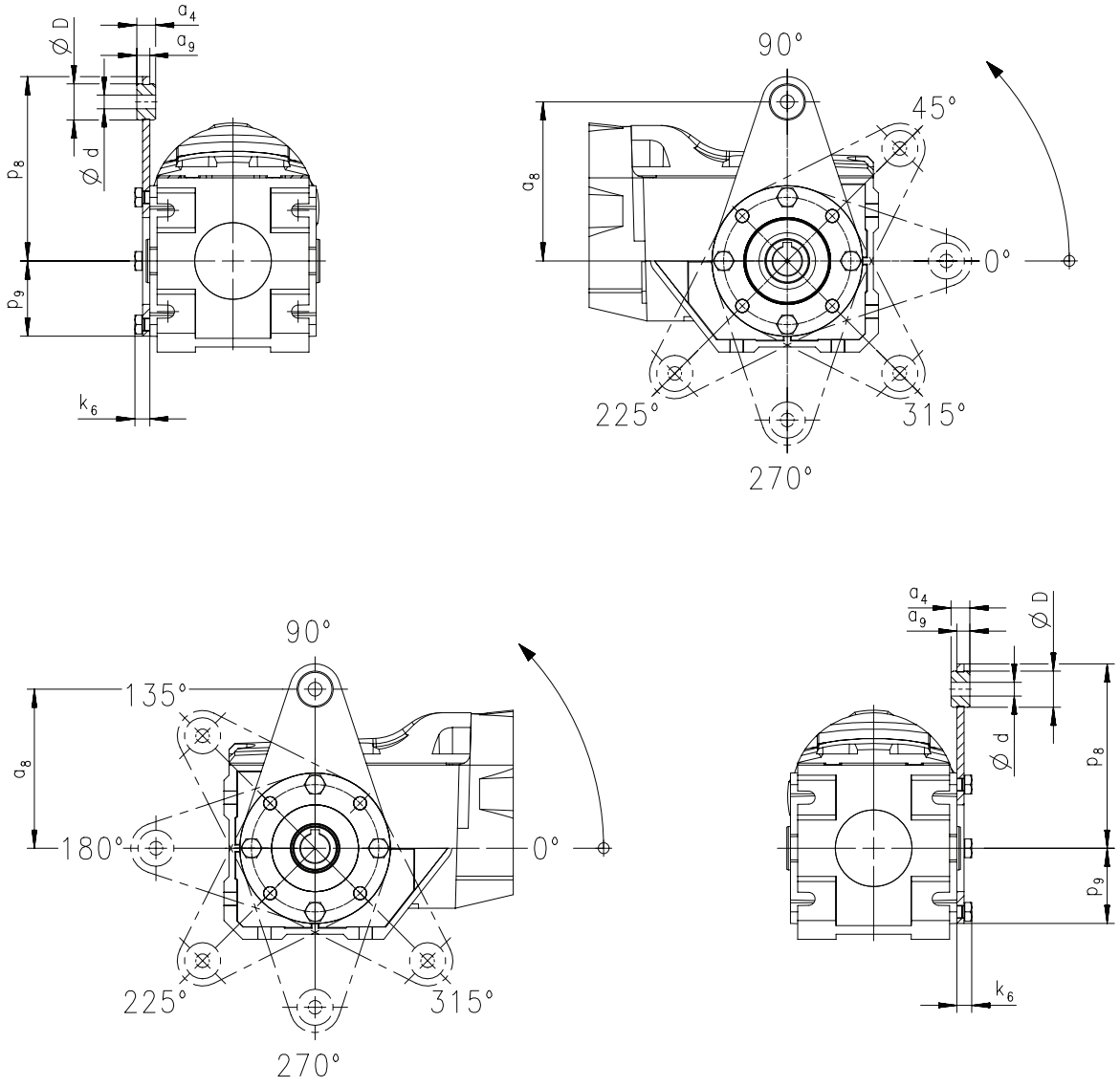
Torque plate

Torque support is usually effected by means of the foot or flange. Another simple possibility is provided by the attachable torque plates. Here, torque support is implemented solely via one point, which, among other things, is suitable for shaft-mounted gearboxes. Supplied rubber buffers provide for mounting with minimum stress and absorb light shocks.
The torque plates are available in two designs, for mounting on the available threaded pitch circle, or for the gearbox foot.

In addition, torque support for the g500-B45 gearbox can be effected via the holding fixture of the housing, which is integrated on both sides, by means of a rubber buffer.
The rubber buffers can be ordered optionally.

Torque plate

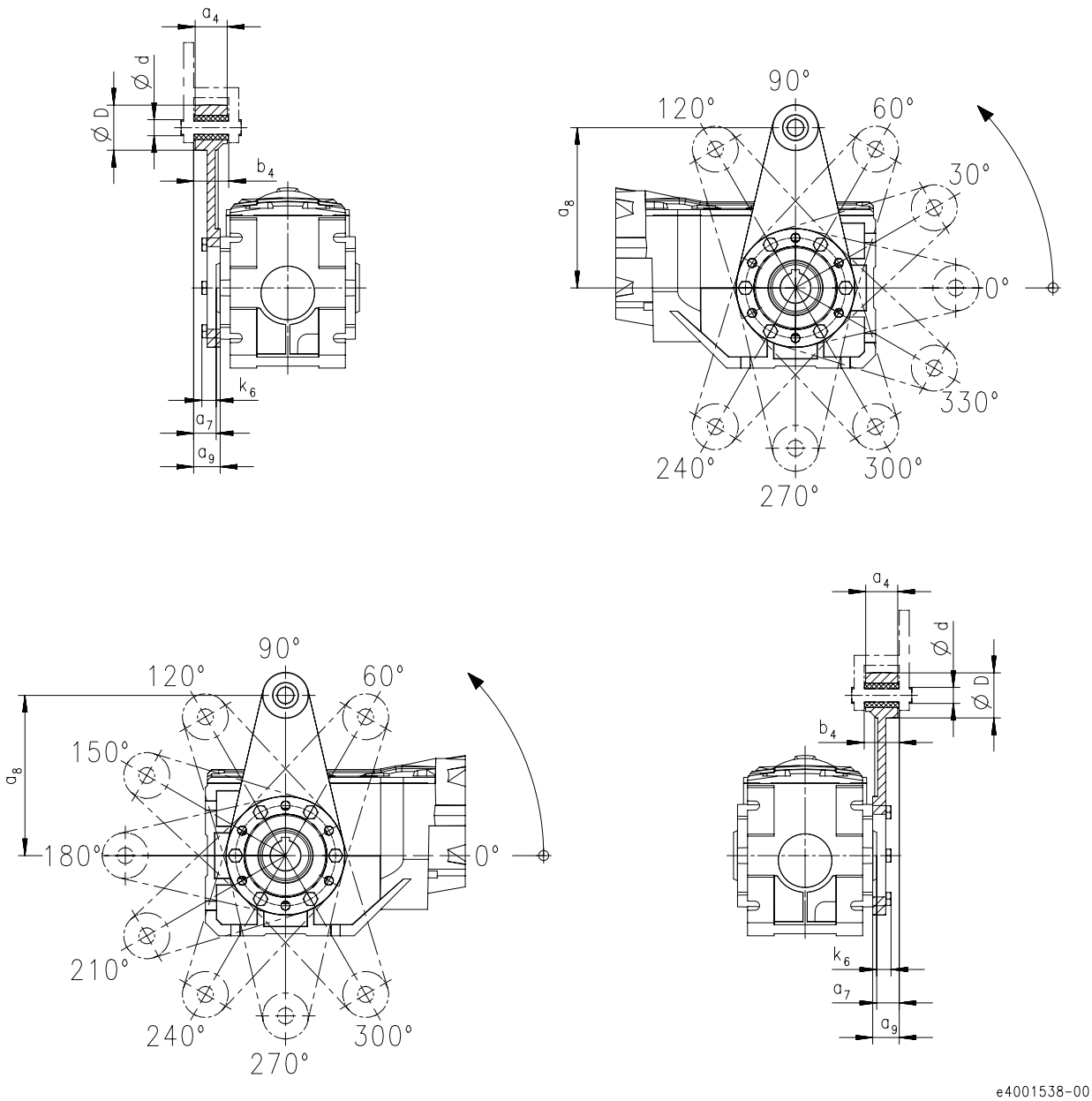
Torque plate on threaded pitch circle



Product	Dimensions								Mass
	a_4	a_8	a_9	d	D	p_8	p_9	k_6	m
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[kg]
g500-B45	12.0	100	8.0	8.0	20.0	115	42.0	9.0	0.30
g500-B110	13.0	110	9.0	10.0	25.0	128	54.0	11.0	0.50

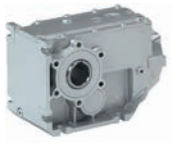
Torque plate

Torque plate on threaded pitch circle



Product	Dimensions								Mass
	a_4	a_7	a_8	a_9	b_4	d	D	k_6	m
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[kg]
- g500-B240	34.0	23.5	160	27.5	38.5	16.0	45.0	15.0	1.30

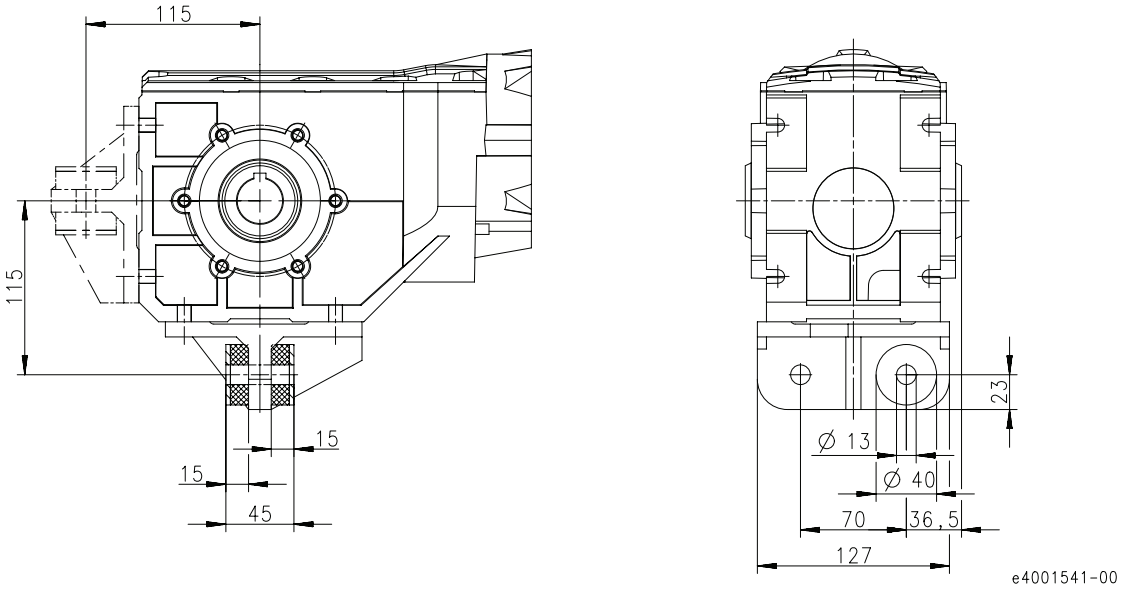
6.7



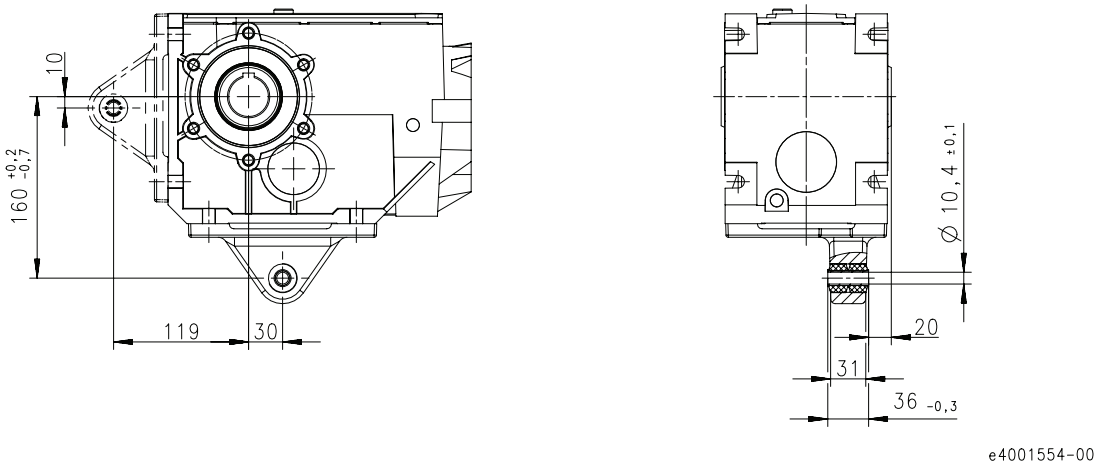
Torque plate

Torque plate at housing foot

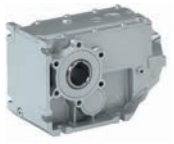
g500-B240



g500-B450



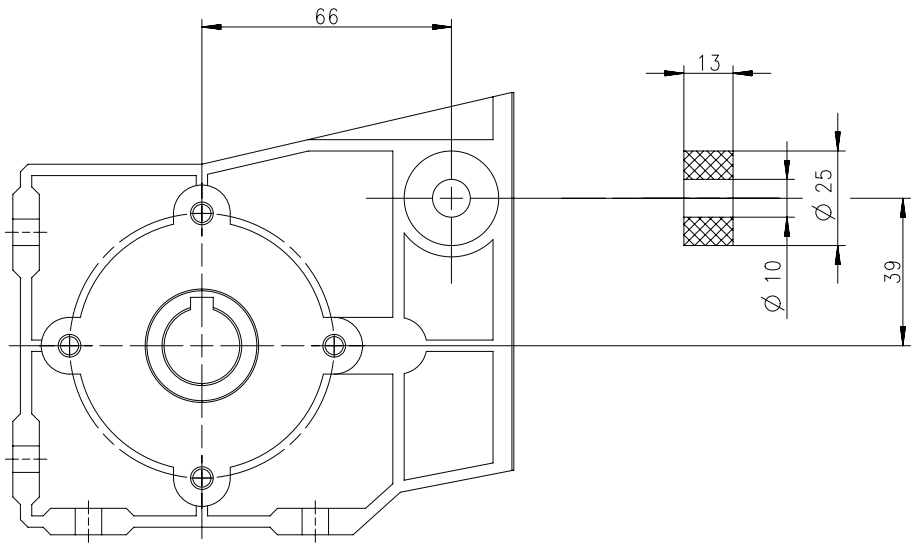
Product	Mass
	m
	[kg]
g500-B240	2.40
g500-B450	1.10

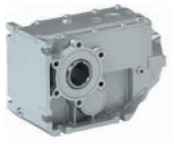


Torque plate

Rubber buffer for torque plate

g500-B45



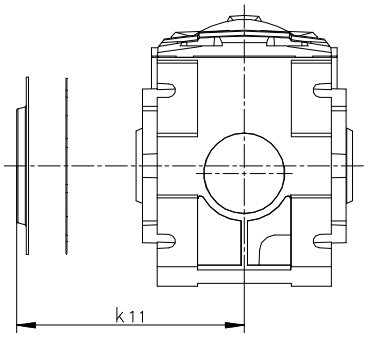


Shaft cover

Hoseproof hollow shaft cover

The cover protects the hollow shaft from objects falling in. It is sealed by a flat gasket between cover and housing. Thus, the hollow shaft is protected from dust and water jets.

The cover is loosely enclosed and can be mounted on both sides of the hollow shaft bore.



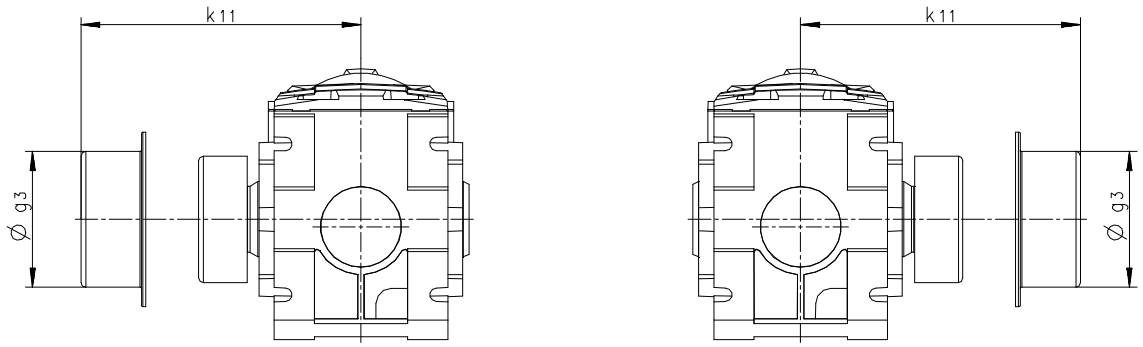
6.7

Product	Dimensions	Mass
	k_{11}	m
	[mm]	[kg]
g500-B45	55.0	0.050
g500-B110	65.0	0.050
g500-B240	75.0	0.10
g500-B450	79.5	0.15

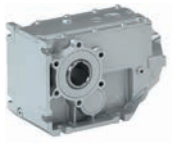
Shaft cover

Shrink disc cover

The cover is provided for the shrink disc to be protected from contact.

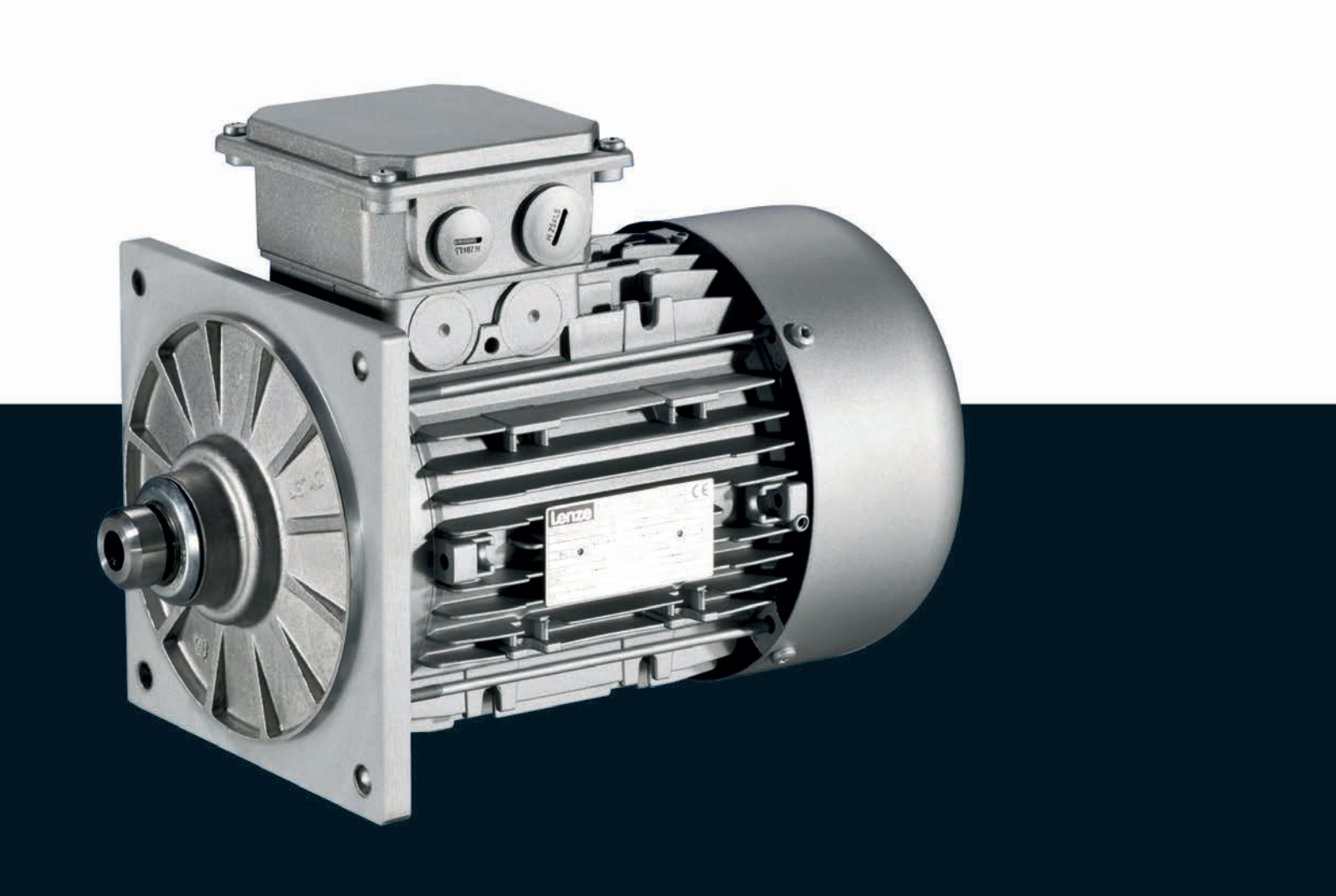


Product	Dimensions		Mass
	g_3	k_{11}	m
	[mm]	[mm]	[kg]
g500-B45	65.0	87.5	0.050
g500-B110	79.0	97.5	0.050
g500-B240	90.0	111	0.050
g500-B450	90.0	108	0.050



MF three-phase AC motors

0.55 to 22 kW



MF three-phase AC motors

Contents

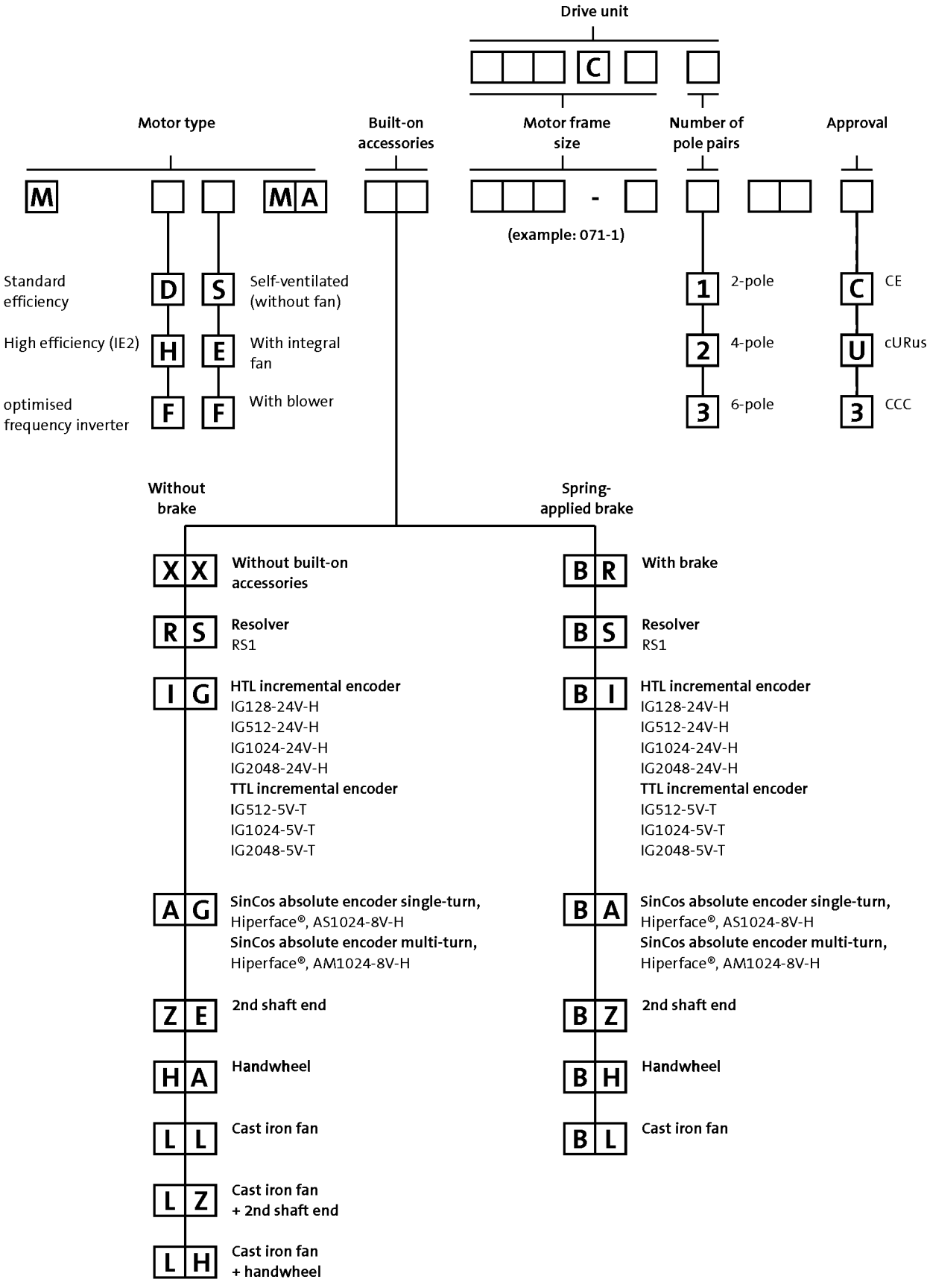
List of abbreviations

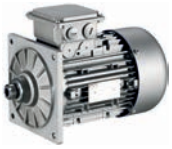
$\eta_{100\,\%}$	[%]	Efficiency
$\eta_{75\,\%}$	[%]	Efficiency
$\eta_{50\,\%}$	[%]	Efficiency
cos φ		Power factor
I_N	[A]	Rated current
I_{max}	[A]	Max. current consumption
J	[kgcm²]	Moment of inertia
m	[kg]	Mass
M_a	[Nm]	Starting torque
M_b	[Nm]	Stalling torque
M_{max}	[Nm]	Max. torque
M_N	[Nm]	Rated torque
n_N	[r/min]	Rated speed
P_N	[kW]	Rated power
P_{max}	[kW]	Max. power input

U_{max}	[V]	Max. mains voltage
U_{min}	[V]	Min. mains voltage
$U_{N,\Delta}$	[V]	Rated voltage
$U_{N,Y}$	[V]	Rated voltage

CE	Communauté Européenne
CSA	Canadian Standards Association
DIN	Deutsches Institut für Normung e.V.
EMC	Electromagnetic compatibility
EN	European standard
IEC	International Electrotechnical Commission
IM	International Mounting Code
IP	International Protection Code
NEMA	National Electrical Manufacturers Association
UL	Underwriters Laboratory Listed Product
UR	Underwriters Laboratory Recognized Product
VDE	Verband deutscher Elektrotechniker (Association of German Electrical Engineers)
CCC	China Compulsory Certificate
GOST	Certificate for Russian Federation
cURus	Combined certification marks of UL for the USA and Canada
UkrSEPRO	Certificate for Ukraine

Product key

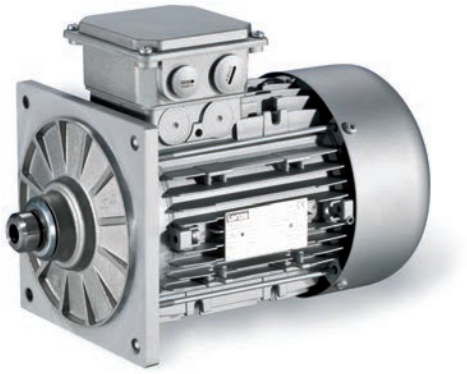

Drive unit
C
Motor type
Built-on accessories
Motor frame size
Number of pole pairs
Approval
M
M A
-
(example: 071-1)
Standard efficiency
D
S
Self-ventilated (without fan)
High efficiency (IE2)
H
E
With integral fan
optimised frequency inverter
F
F
With blower
1
2-pole
2
4-pole
3
6-pole
C
CE
U
cURus
3
CCC
Without brake
Spring-applied brake
X X
Without built-on accessories
R S
Resolver
RS1
I G
HTL incremental encoder
IG128-24V-H
IG512-24V-H
IG1024-24V-H
IG2048-24V-H
TTL incremental encoder
IG512-5V-T
IG1024-5V-T
IG2048-5V-T
A G
SinCos absolute encoder single-turn,
Hiperface®, AS1024-8V-H
SinCos absolute encoder multi-turn,
Hiperface®, AM1024-8V-H
Z E
2nd shaft end
H A
Handwheel
L L
Cast iron fan
L Z
Cast iron fan
+ 2nd shaft end
L H
Cast iron fan
+ handwheel
B R
With brake
B S
Resolver
RS1
B I
HTL incremental encoder
IG128-24V-H
IG512-24V-H
IG1024-24V-H
IG2048-24V-H
TTL incremental encoder
IG512-5V-T
IG1024-5V-T
IG2048-5V-T
B A
SinCos absolute encoder single-turn,
Hiperface®, AS1024-8V-H
SinCos absolute encoder multi-turn,
Hiperface®, AM1024-8V-H
B Z
2nd shaft end
B H
Handwheel
B L
Cast iron fan



Product information

Special motors have been designed for direct attachment to Lenze gearboxes.

These motors are attached to the gearbox without the use of a clutch. Torque transmission between the toothing and the motor shaft is friction-locked via a tapered connection here.
This motor design means that the geared motors only require a small installation space.



L-force MF three-phase AC motors are available in a power range from 0.55 to 22 kW and have been fully optimised for inverter operation.

The benefits for you:
- Up to sizes smaller than standard three-phase AC motors
- The motors exceed the minimum efficiency levels of efficiency class IE2
- Large speed setting range: 1:24 (without field weakening)
- Dynamic thanks to a low moment of inertia

Basic versions
- The thermal sensors integrated as standard allow for permanent temperature monitoring and are coordinated to the motor winding's temperature class F (155°C).
- The motors of the basic version are adapted to ambient conditions by enclosure IP55.
- In tough operating conditions, the surface and corrosion protection system is provided to reliably protect the motor from corrosive media.

Options
- Various brake sizes – each available with several braking torques – can be combined with the three-phase AC motors.
- The LongLife version of the brake can easily reach 10 x 10^6 switching cycles.
- A resolver and various incremental and absolute value encoders can be fitted for speed and position detection.
- For fast commissioning, the motors are also available with connectors for the power connection, brake, blower and feedback.
- Instead of an integral fan, the motor can optionally be equipped with a blower. No torque reduction is then necessary, even at speeds below 20 Hz.
- For drive tasks in decentralised applications, the motor can be ordered with the motec inverter connected to the terminal box.
- The motors are available with cURus, GOST-R, CCC and UkrSepro approval.
- Smooth start/braking is possible by increasing the motor's centrifugal mass with a cast iron fan.
- The motor can be equipped with a handwheel for manual setup or emergency operations.
- To protect the fan from objects falling in, the fan cover can be equipped with a protection cover.
- A 2nd shaft end is available for further modifications.

Functions and features

Size				
Motor	063	071	080	090
Spring-applied brake				
Design	Standard or LongLife design Reduced or standard braking torque With rectifier With manual release lever Low noise		Standard or LongLife design Reduced, standard or increased braking torque With rectifier With manual release lever Low noise	
Feedback				
Design	Resolver Incremental encoder Absolute value encoder (multi-turn)			
Thermal sensor				
Thermal contact	TKO			
Thermal detector	KTY83-110 KTY84-130			
PTC thermistor	PTC			
Motor connection				
Power connection	Terminal box ICN connector HAN10E connector HAN modular connector			
Brake connection	Terminal box ICN connector HAN modular connector HAN10E connector			
Blower connection	Terminal box ICN connector			
Feedback connection	Terminal box ICN connector			
Temperature sensor connection	Terminal box TKO or PTC at connector in the power connection KTY at connector in the feedback connection			
Shaft bearings				
Position of the locating bearing	Standard motors (B3, B5, B14): side B Motors for gearbox direct mounting: side A			
Bearing type	Deep-groove ball bearing with high-temperature resistant grease, 2 sealing discs or cover plates			
Colour				
	Not coated Primed Paint in various corrosion-protection designs in accordance with RAL colours			
Further options				
	Protection cover	Protection cover 2nd shaft end		

Functions and features

Size			
Motor	100	112	132
Spring-applied brake			
Design	Standard or LongLife design Reduced, standard or increased braking torque With rectifier With manual release lever Low noise	Standard design Reduced, standard or increased braking torque With rectifier With manual release lever Low noise	
Feedback			
Design	Resolver Incremental encoder Absolute value encoder (multi-turn)		
Thermal sensor			
Thermal contact	TKO		
Thermal detector	KTY83-110 KTY84-130		
PTC thermistor	PTC		
Motor connection			
Power connection	Terminal box ICN connector HAN10E connector HAN modular connector	Terminal box	Terminal box HAN modular connector
Brake connection	Terminal box ICN connector HAN modular connector HAN10E connector	Terminal box	Terminal box HAN modular connector
Blower connection	Terminal box ICN connector		
Feedback connection	Terminal box ICN connector		
Temperature sensor connection	Terminal box TKO or PTC at connector in the power connection KTY at connector in the feedback connection	Terminal box KTY at connector in the feedback connection	
Shaft bearings			
Position of the locating bearing	Standard motors (B3, B5, B14): side B Motors for gearbox direct mounting: side A		
Bearing type	Deep-groove ball bearing with high-temperature resistant grease, 2 sealing discs or cover plates		
Colour			
	Not coated Primed Paint in various corrosion-protection designs in accordance with RAL colours		
Further options			
	Protection cover 2nd shaft end		

Functions and features

Surface and corrosion protection

For optimum protection of three-phase AC motors against ambient conditions, the surface and corrosion protection system (OKS) offers tailor-made solutions.

Various surface coatings ensure that the motors operate reliably even at high air humidity, in outdoor installation or in the presence of atmospheric impurities. Any colour from the RAL Classic collection can be chosen for the top coat. The three-phase AC motors are also available unpainted (no surface and corrosion protection).

Surface and corrosion protection system	Applications	Measures
OKS-G (primed)	• Dependent on subsequent top coat applied	• 2K PUR priming coat (grey)
OKS-S (small)	• Standard applications • Internal installation in heated buildings • Air humidity up to 90%	• Surface coating as per corrosivity category C1 (in line with EN 12944-2)
OKS-M (medium)	• Internal installation in non-heated buildings • Covered, protected external installation • Air humidity up to 95%	• Surface coating as per corrosivity category C2 (in line with EN 12944-2)
OKS-L (high)	• External installation • Air humidity above 95% • Chemical industry plants • Food industry	• Surface coating as per corrosivity category C3 (in line with EN 12944-2) • Blower cover and B end shield additionally primed • Screws zinc-coated • Cable glands with gaskets • Corrosion-resistant brake with cover ring, stainless friction plate, and chrome-plated armature plate (on request) Optional measures: • Motor recesses sealed off (on request)

Structure of surface coating

Surface and corrosion protection system	Corrosivity category	Surface coating	Colour
	DIN EN ISO 12944-2	Structure	
Without OKS (uncoated)			
OKS-G (primed)		2K PUR priming coat	
OKS-S (small)	C1	2K-PUR top coat	Standard: RAL 7012 Optional: RAL Classic
OKS-M (medium)	C2	2K PUR priming coat 2K-PUR top coat	
OKS-L (high)	C3		

Motor – inverter assignment

Rated frequency 120 Hz

- Decentralised inverter 8400 motec (E84DVB)
- Inverter Drives 8400 (E84AV)

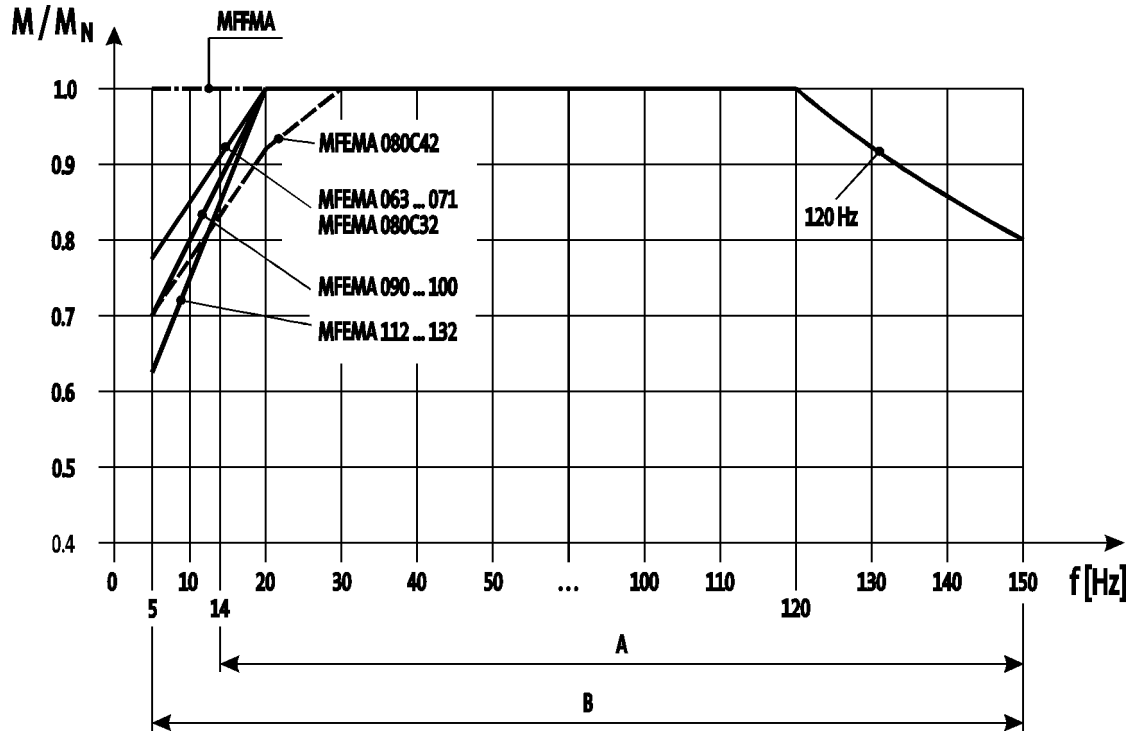
Rated power	Product key		
	Motor	Inverter	
P_N			
[kW]			
0.55	MF□□□□□063-32	E84DVB□5514S□□□2□	E84AV□□□5514□□0
0.75	MF□□□□□063-42	E84DVB□7514S□□□2□	E84AV□□□7514□□0
1.10	MF□□□□□071-32	E84DVB□1124S□□□2□	E84AV□□□1124□□0
1.50	MF□□□□□071-42	E84DVB□1524S□□□2□	E84AV□□□1524□□0
2.20	MF□□□□□080-32	E84DVB□2224S□□□2□	E84AV□□□2224□□0
3.00	MF□□□□□080-42	E84DVB□3024S□□□2□	E84AV□□□3024□□0
4.00	MF□□□□□090-32	E84DVB□4024S□□□2□	E84AV□□□4024□□0
5.50	MF□□□□□100-12	E84DVB□5524S□□□2□	E84AV□□□5524□□0
7.50	MF□□□□□100-32	E84DVB□7524S□□□2□	E84AV□□□7524□□0
11.0	MF□□□□□112-22		E84AV□□□1134□□0
15.0	MF□□□□□132-12		E84AV□□□1534□□0
18.5	MF□□□□□132-22		E84AV□□□1834□□0
22.0	MF□□□□□132-32		E84AV□□□2234□□0

Dimensioning

Torque derating at low motor frequencies

Motor size-dependent torque reduction, taking into account the thermal response during operation on the inverter.

Torque characteristics



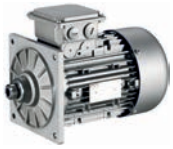
A = Operation with integral fan and brake
B = Operation with integral fan and brake control "Holding current reduction"

► The motor specifications stated in this catalogue for inverter operation apply to operation with a Lenze inverter. If you are uncertain, get in touch with the manufacturer of the inverter to ask whether the device is capable of driving the motor with the stated specifications (e.g. setting range, base frequency).

You can use the Drive Solution Designer for precise drive dimensioning.

The Drive Solution Designer helps you to carry out a fast and high-quality drive dimensioning.
The software includes well-founded and proven knowledge on drive applications and electro-mechanical drive components.

Please contact your Lenze sales office.



Standards and operating conditions

Enclosure			
EN 60529			IP55 [1)] IP65 [1)] IP66 [1)]
Conformity			
CE			Low-Voltage Directive
			2006/95/EC
EAC			TP TC 004/2011 (TR C
Approval			
			UkrSEPRO
CCC			GB Standard 12350-2009
CSA			CSA 22.2 No. 100
cURus			UL 1004-1 UL 1004-8 Power Conversion Equipment (File-No. E210321)
Temperature class			
IEC/EN 60034-1; utilisation			B
IEC/EN 60034-1; insulation system (enamel-insulated wire)			F
Min. ambient operating temperature			
	$T_{opr,min}$	[°C]	-20
Max. ambient temperature for operation			
	$T_{opr,max}$	[°C]	40
With power reduction	$T_{opr,max}$	[°C]	60
Site altitude			
Amsl	H_{max}	[m]	4000
Max. speed			
	n_{max}	[r/min]	4500

[1)] Designs with different degrees of protection:
IP55 with brake (IP54 with manual release lever).
IP54 with resolver RS1.
IP54 with HTL incremental encoder IG128-24V-H.

Rated data for 120 Hz

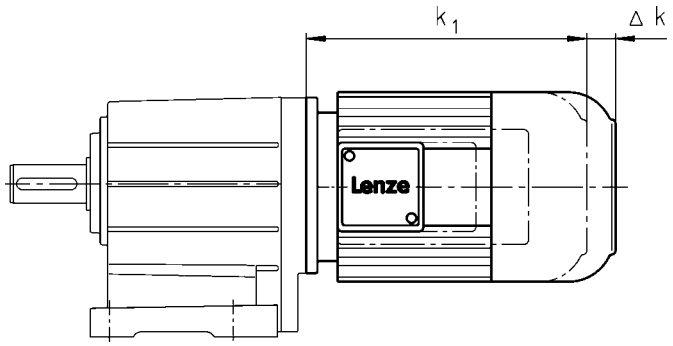
4-pole motors

	P_N	n_N	$U_{N,\Delta}$	$I_{N,\Delta}$	$U_{N,Y}$	$I_{N,Y}$
			± 10 %		± 10 %	
	[kW]	[r/min]	[V]	[A]	[V]	[A]
MF□□□□□063-32	0.55	3440	200	3.20	345	1.80
MF□□□□□063-42	0.75	3400	210	4.00	370	2.30
MF□□□□□071-32	1.10	3490	200	5.50	345	3.20
MF□□□□□071-42	1.50	3450	205	6.80	360	3.90
MF□□□□□080-32	2.20	3500	200	9.10	345	5.30
MF□□□□□080-42	3.00	3480	210	11.4	370	6.60
MF□□□□□090-32	4.00	3480			370	8.50
MF□□□□□100-12	5.50	3525			340	12.9
MF□□□□□100-32	7.50	3515			375	15.9
MF□□□□□112-22	11.0	3530			370	23.5
MF□□□□□132-12	15.0	3560			370	31.2
MF□□□□□132-22	18.5	3560			360	39.0
MF□□□□□132-32	22.0	3550			380	44.5

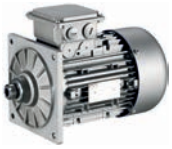
	M_N	M_{max}	cos φ	$\eta_{75\,\%}$	$\eta_{100\,\%}$	J [1)]	m [1)]
	[Nm]	[Nm]		[%]	[%]	[kgcm²]	[kg]
MF□□□□□063-32	1.53	6.00	0.68	75.0	75.0	3.70	4.40
MF□□□□□063-42	2.11	8.00	0.69	79.6	79.6	3.70	4.40
MF□□□□□071-32	3.01	12.0	0.77	81.4	81.4	12.8	6.40
MF□□□□□071-42	4.15	16.0	0.80	82.8	82.8	12.8	6.40
MF□□□□□080-32	6.00	24.0	0.86	84.3	84.3	28.0	11.0
MF□□□□□080-42	8.20	32.0	0.86	85.5	85.5	28.0	11.0
MF□□□□□090-32	10.9	44.0	0.85	87.0	86.6	32.0	18.0
MF□□□□□100-12	14.9	60.0	0.81	87.9	87.7	61.0	26.5
MF□□□□□100-32	20.3	80.0	0.81	88.9	88.7	61.0	26.5
MF□□□□□112-22	29.7	120	0.78	89.8	89.8	107	38.0
MF□□□□□132-12	40.3	160	0.84	88.9	90.6	336	66.0
MF□□□□□132-22	49.6	200	0.84	89.9	91.2	336	66.0
MF□□□□□132-32	59.2	240	0.83	90.5	91.6	336	66.0

[1)] Without accessories

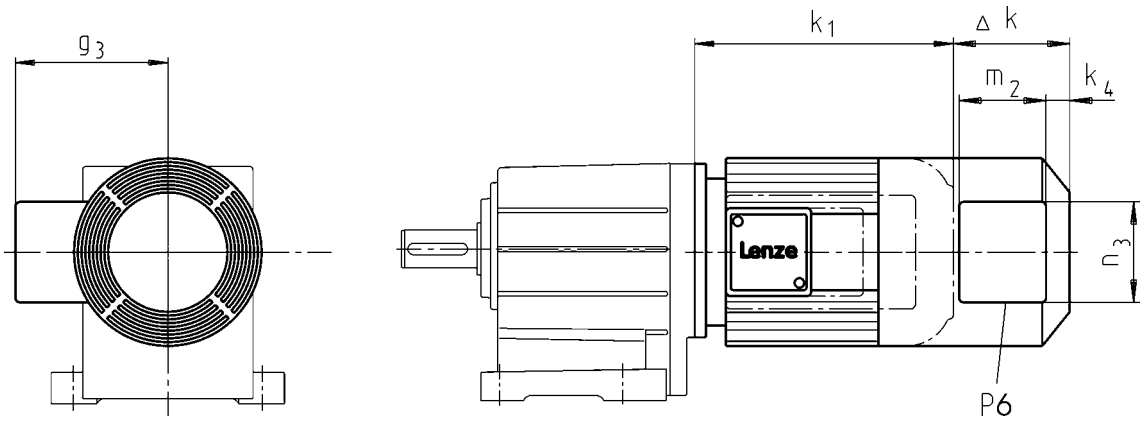
Dimensions, self-ventilated (4-pole)



	Motor type			
	MFEMAXX	MFEMABR	MFEMABS MFEMABI MFEMABA	MFEMARS MFEMAIG MFEMAAG
Motor frame size				
	Δ k	Δ k	Δ k	Δ k
	[mm]	[mm]	[mm]	[mm]
063-32 063-42	0	40	103	56
071-32 071-42		52	96	52
080-32 080-42		73	111	111
090-32		68	105	87
100-12 100-32		76	101	81
112-22		90	120	80
132-12 132-22 132-32		110	125	103



Dimensions, forced ventilated (4-pole)

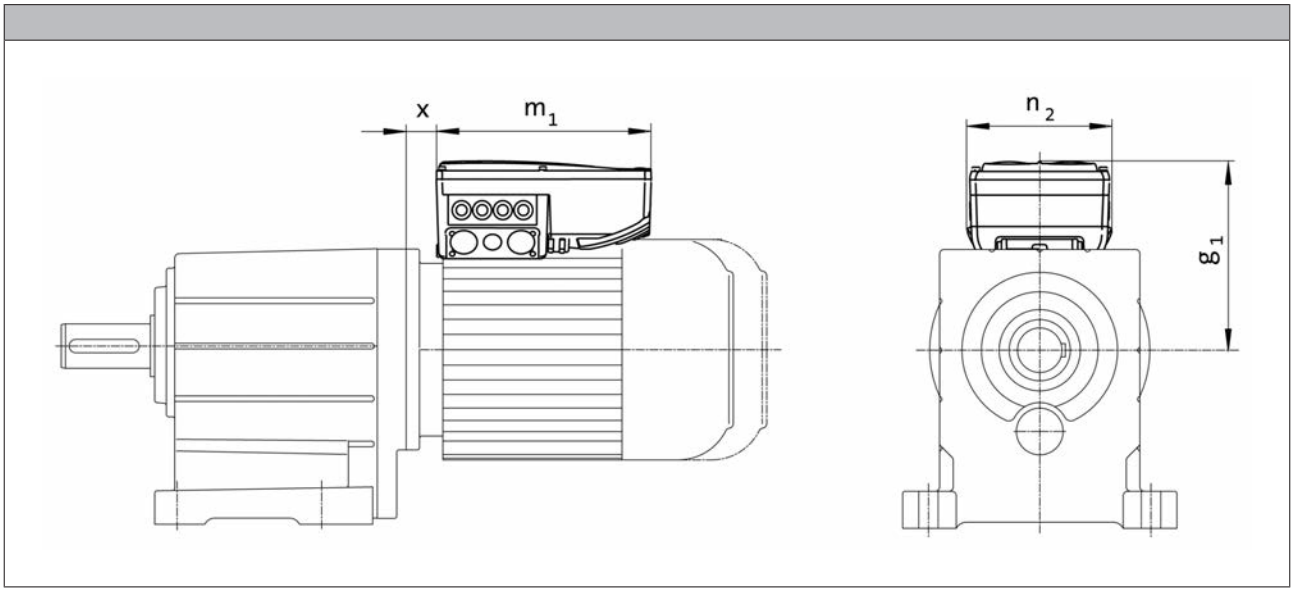


Motor type									
	MFFMAXX	MFFMABR	MFFMABS MFFMABI MFFMABA	MFFMARS MFFMAIG MFFMAAG					

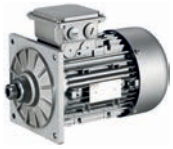
Motor frame size									
	Δ k	Δ k	Δ k	Δ k	k_4	g_3	m_2	n_3	P_6
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
063-32 063-42	128	170	170	128	12	115	95	105	1x M16x1.5
071-32 071-42		165	165			122			
080-32 080-42		183	183		13	132	96	106	
090-32		181	181		22	141	95	105	
100-12 100-32	109	170	170	109		150			
112-22	102	183	183	183		162			
132-12 132-22 132-32	115	202	202	202	32	182			

Dimensions, 8400 motec inverter

Rated frequency 120 Hz



Product key					
Motor	Inverter				
		$g_{1,\ 120Hz}$	$m_{1,\ 120Hz}$	$n_{2,\ 120Hz}$	x_{120Hz}
		[mm]	[mm]	[mm]	[mm]
MF□□□□□063-32	E84DVB□5514S□□□2□	154	241	161	18.8
MF□□□□□063-42	E84DVB□7514S□□□2□				
MF□□□□□071-32	E84DVB□1124S□□□2□	163			21.0
MF□□□□□071-42	E84DVB□1524S□□□2□				
MF□□□□□080-32	E84DVB□2224S□□□2□	201	260	176	24.5
MF□□□□□080-42	E84DVB□3024S□□□2□				
MF□□□□□090-32	E84DVB□4024S□□□2□	261	325	195	16.0
MF□□□□□100-12	E84DVB□5524S□□□2□	272			17.1
MF□□□□□100-32	E84DVB□7524S□□□2□				



Spring-applied brakes

Three-phase AC motors can be fitted with a spring-applied brake. This is activated after the supply voltage is switched off (closed-circuit principle). For optimum adjustment of the brake motor to the application, a range of braking torques and control modes is available for every motor frame size. For applications with very high operating frequencies the brake is also available in a LongLife version, with reinforced mechanical brake components.

Features

Versions
- **Standard**
  - 1 x 10^6 repeating switching cycles
  - 1 x 10^6 reversing switching cycles
- **LongLife**
  - 10 x 10^6 repeating switching cycles
  - 15 x 10^6 reversing switching cycles

Control
- DC supply
- AC supply via rectifier in the terminal box

Enclosure
- Without manual release IP55
- With manual release IP54

Friction lining
- Non-asbestos, low wearing

Options
- Manual release
- UL/CSA approval
- Noise-reduced

Motor – brake assignment

Design	Standard		LongLife	
Motor frame size	Size	Rated torque	Size	Rated torque
	Brake		Brake	
		M_k		M_k
		[Nm]		[Nm]
063-32 063-42	06 06	2.50 4.00	06	4.00
071-32	06 06 08	2.50 4.00 3.50	06 08	4.00 3.50
071-42	06 06 08 08	2.50 4.00 3.50 8.00	06 08 08	4.00 3.50 8.00
080-32	08 08 10	3.50 8.00 7.00	08 10	8.00 7.00
080-42	08 08 10 10	3.50 8.00 7.00 16.0	08 10 10	8.00 7.00 16.0

Spring-applied brakes

Motor – brake assignment

Design	Standard	LongLife

Motor frame size	Size	Rated torque	Size	Rated torque
	Brake		Brake	
		M_k		M_k
		[Nm]		[Nm]
090-32	08 08 10 10 10	3.50 8.00 7.00 16.0 23.0	08 10 10	8.00 7.00 16.0
100-12	10 10 12 12	7.00 16.0 14.0 32.0	10 12 12	16.0 14.0 32.0
100-32	10 10 12 12 12	7.00 16.0 14.0 32.0 46.0		
112-22	12 12 14 14	14.0 32.0 35.0 60.0		
132-12	14 14 16 16	35.0 60.0 60.0 80.0		
132-22 132-32	14 14 16 16 16	35.0 60.0 60.0 80.0 100		

Spring-applied brakes

Direct connection without rectifier

If the brake is activated directly without a rectifier, a freewheeling diode or a spark suppressor is required to protect against induction peaks.

- Supply voltages
  DC 24 V
  DC 180 V
  DC 205 V

Connection via mains voltage with brake rectifier

If the brake is not directly supplied with DC voltage, a rectifier is required. This is included in the scope of supply and is located in the terminal box of the motor. The rectifier converts the AC voltage of the connection into DC voltage. The following rectifiers are available:

Half-wave rectifier, 6-pole

- Ratio of supply voltage to brake coil voltage = 2.22
- Approved by UL/CSA
- Supply voltages
  AC 230 V
  AC 400 V
  AC 460 V

Bridge rectifier, 6-pole

- Ratio of supply voltage to brake coil voltage = 1.11
- Supply voltage
  AC 230 V

Bridge/half-wave rectifier, 6-pole

- Ratio of supply voltage to brake coil voltage
  up to overexcitation time = 1.11
  beyond overexcitation time = 2.22

Supply voltages:

- AC 230 V
- AC 400 V

Spring-applied brakes

Connection via mains voltage with brake rectifier

Bridge/half-wave rectifier, 6-pole
- Ratio of supply voltage to brake coil voltage
  up to overexcitation time = 1.11
  beyond overexcitation time = 2.22

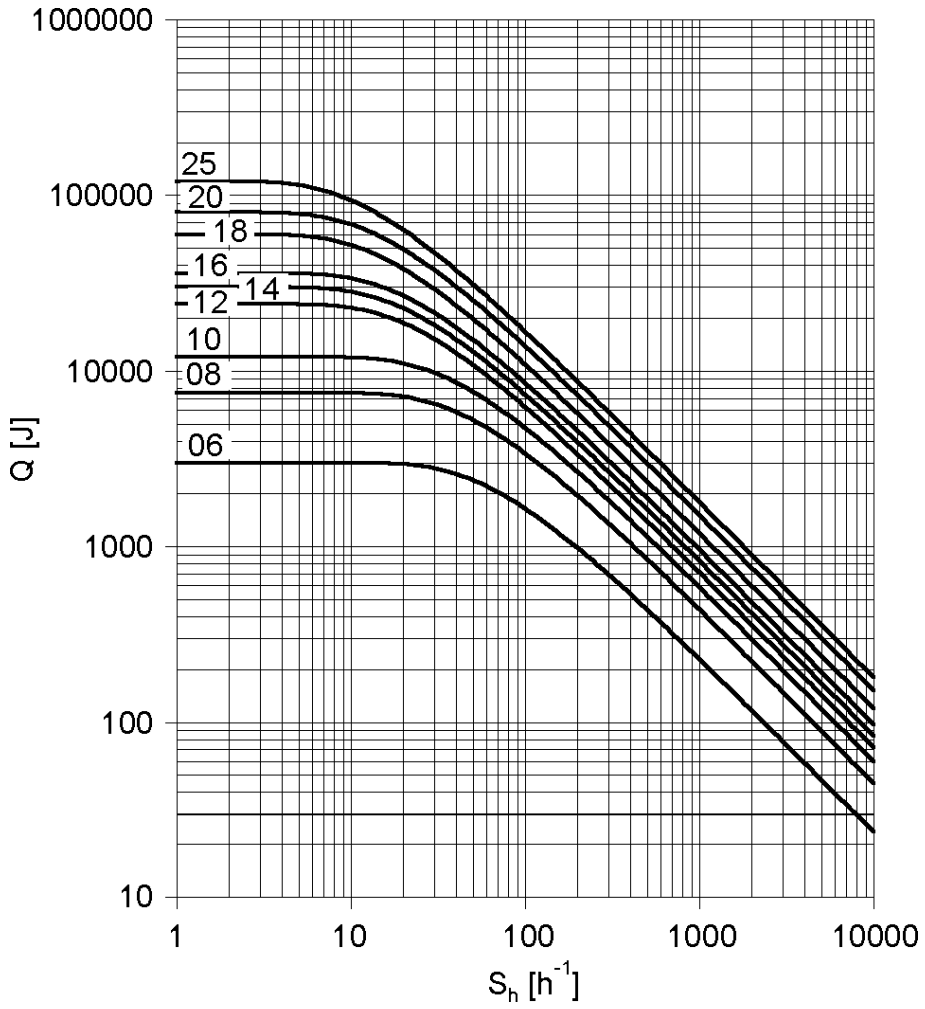
Supply voltages:
- AC 230 V
- AC 400 V

During the switching operation the bridge/half-wave rectifier functions as a bridge rectifier for the overexcitation time $t_{ü}$ and then as a half-wave rectifier. This combination optimises the performance of the brake – depending on the assignment of brake coil voltage and supply voltage:

- **Short-time overexcitation of the brake coil**
  Activating the brake coil for the overexcitation time $t_{ü}$ with twice the rated voltage allows the disengagement time to be reduced. The brake opens more quickly and wear on the friction lining is reduced.
  These features make this activation version particularly suitable for lifting applications. It is therefore only available in combination with a brake with increased braking torque.
- **Holding current reduction (cold brake)**
  By reducing the holding current, the bridge/half-wave rectifier is able to reduce the power input to the open brake. As the brake heats up less, this type of activation is known as "cold brake".

Spring-applied brakes

Permissible friction energy



Q =Switching energy per switching cycle
S_h =Operating frequency
Brake size = 06 to 25

Spring-applied brakes

Rated data with reduced braking torque

► Please enquire for braking torques and maximum switching work values not listed here.

Size			06	08	10	12	14	16	18	20	25
Power input											
	P_{in}	[kW]	0.020	0.025	0.030	0.040	0.050	0.055	0.085	0.10	0.11
Braking torque											
100	M_B	[Nm]	2.50	3.50	7.00	14.0	35.0	60.0	80.0	145	265
1000	M_B	[Nm]	2.30	3.10	6.10	12.0	30.0	50.0	65.0	115	203
1200	M_B	[Nm]	2.30	3.10	6.00	12.0	29.0	48.0	63.0	112	199
1500	M_B	[Nm]	2.20	3.00	5.80	11.0	28.0	47.0	61.0	109 [1)]	193 [1)]
1800	M_B	[Nm]	2.10	2.90	5.70	11.0	28.0	46.0	60.0 [1)]		
3000	M_B	[Nm]	2.00	2.80	5.30	10.0	26.0 [1)]	43.0 [1)]			
3600	M_B	[Nm]	2.00	2.70	5.20	10.0 [1)]					
Maximum switching energy											
100	Q_E	[KJ]	3.00	7.50	12.0	24.0	30.0	36.0	60.0	80.0	120
1000	Q_E	[KJ]	3.00	7.50	12.0	24.0	30.0	36.0	60.0	80.0	120
1200	Q_E	[KJ]	3.00	7.50	12.0	24.0	30.0	36.0	60.0	80.0	120
1500	Q_E	[KJ]	3.00	7.50	12.0	24.0	30.0	36.0	60.0	24.0 [1)]	36.0 [1)]
1800	Q_E	[KJ]	3.00	7.50	12.0	24.0	30.0	36.0	36.0 [1)]		
3000	Q_E	[KJ]	3.00	7.50	12.0	24.0	18.0 [1)]	11.0 [1)]			
3600	Q_E	[KJ]	3.00	7.50	12.0	7.00 [1)]					
Transition operating frequency											
	$S_{hü}$	[1/h]	79.0	50.0	40.0	30.0	28.0	27.0	20.0	19.0	15.0
Moment of inertia											
	J	[kgcm²]	0.015	0.061	0.20	0.45	0.63	1.50	2.90	7.30	20.0
Mass											
	m	[kg]	0.90	1.50	2.60	4.20	5.80	8.70	12.6	19.5	31.0

[1)] In the region of the load limit the value for friction energy Q_{BW} can be reduced to 40 %.

Spring-applied brakes

Rated data with reduced braking torque

► Activation via half-wave or bridge rectifier

Size			06	08	10	12	14	16	18	20	25
Friction energy											
	Q_{BW}	[MJ]	113	210	264	706	761	966	1542	2322	3522
Delay time											
Engaging	t_{11}	[ms]	11.0	14.0	20.0	21.0	37.0	53.0	32.0	47.0	264
Rise time											
Braking torque	t_{12}	[ms]	13.0	10.0	17.0	19.0	22.0	30.0	20.0	100	120
Engagement time											
	t_1	[ms]	24.0		37.0	40.0	59.0	83.0	52.0	147	384
Disengagement time											
	t_2	[ms]	35.0	37.0	57.0	65.0	148	169	230	207	269

► Activation via bridge/half-wave rectifier

Design			Holding current reduction (cold brake)								
Size			06	08	10	12	14	16	18	20	25
Friction energy											
	Q_{BW}	[MJ]	113	210	264	706	761	966	1542	2322	3522
Overexcitation time											
	$t_{ü}$	[ms]	300				1300				
Min. rest time											
	t	[ms]	900				3900				
Delay time											
Engaging	t_{11}	[ms]	12.0	22.0	35.0	49.0	61.0	114	83.0	126	304
Rise time											
Braking torque	t_{12}	[ms]	14.0	16.0	30.0	45.0	37.0	65.0	52.0	269	138
Engagement time											
	t_1	[ms]	26.0	38.0	66.0	93.0	97.0	180	134	395	443
Disengagement time											
	t_2	[ms]	35.0	37.0	57.0	65.0	148	169	230	207	269

► The brake response and application times are guide values. The engagement time is 10 times longer with AC-side switching. With the maximum air gap the disengagement time t_2 – depending on the brake and control – is up to 4 times longer than the disengagement time with the rated air gap.

Spring-applied brakes

Rated data with standard braking torque

► Please enquire for braking torques and maximum switching work values not listed here.

Size			06	08	10	12	14	16	18	20	25
Power input											
	P_{in}	[kW]	0.020	0.025	0.030	0.040	0.050	0.055	0.085	0.10	0.11
Braking torque											
100	M_B	[Nm]	4.00	8.00	16.0	32.0	60.0	80.0	150	260	400
1000	M_B	[Nm]	3.70	7.20	14.0	27.0	51.0	66.0	121	206	307
1200	M_B	[Nm]	3.60	7.00	14.0	27.0	50.0	65.0	118	201	300
1500	M_B	[Nm]	3.50	6.80	13.0	26.0	48.0	63.0	115	195 [1)]	291 [1)]
1800	M_B	[Nm]	3.40	6.70	13.0	26.0	47.0	61.0	112 [1)]		
3000	M_B	[Nm]	3.20	6.30	12.0	24.0	44.0 [1)]	57.0 [1)]			
3600	M_B	[Nm]	3.20	6.10	12.0	23.0 [1)]					
Maximum switching energy											
100	Q_E	[KJ]	3.00	7.50	12.0	24.0	30.0	36.0	60.0	80.0	120
1000	Q_E	[KJ]	3.00	7.50	12.0	24.0	30.0	36.0	60.0	80.0	120
1200	Q_E	[KJ]	3.00	7.50	12.0	24.0	30.0	36.0	60.0	80.0	120
1500	Q_E	[KJ]	3.00	7.50	12.0	24.0	30.0	36.0	60.0	24.0 [1)]	36.0 [1)]
1800	Q_E	[KJ]	3.00	7.50	12.0	24.0	30.0	36.0	36.0 [1)]		
3000	Q_E	[KJ]	3.00	7.50	12.0	24.0	18.0 [1)]	11.0 [1)]			
3600	Q_E	[KJ]	3.00	7.50	12.0	7.00 [1)]					
Transition operating frequency											
	$S_{hü}$	[1/h]	79.0	50.0	40.0	30.0	28.0	27.0	20.0	19.0	15.0
Moment of inertia											
	J	[kgcm²]	0.015	0.061	0.20	0.45	0.63	1.50	2.90	7.30	20.0
Mass											
	m	[kg]	0.90	1.50	2.60	4.20	5.80	8.70	12.6	19.5	31.0

[1)] In the region of the load limit the value for friction energy Q_{BW} can be reduced to 40 %.

Spring-applied brakes

Rated data with standard braking torque

► Activation via half-wave or bridge rectifier

Size			06	08	10	12	14	16	18	20	25
Friction energy											
	Q_{BW}	[MJ]	85.0	158	264	530	571	966	1542	2322	3522
Delay time											
Engaging	t_{11}	[ms]	15.0		28.0		17.0	27.0	33.0	65.0	110
Rise time											
Braking torque	t_{12}	[ms]	13.0	16.0	19.0	25.0		30.0	45.0	100	120
Engagement time											
	t_1	[ms]	28.0	31.0	47.0	53.0	42.0	57.0	78.0	165	230
Disengagement time											
	t_2	[ms]	45.0	57.0	76.0	115	210	220	270	340	390

► Activation via bridge/half-wave rectifier

Design			Holding current reduction (cold brake)								
Size			06	08	10	12	14	16	18	20	25
Friction energy											
	Q_{BW}	[MJ]	85.0	158	264	530	571	966	1542	2322	3522
Overexcitation time											
	$t_{ü}$	[ms]	300				1300				
Min. rest time											
	t	[ms]	900				3900				
Delay time											
Engaging	t_{11}	[ms]	16.0	25.0	31.0	48.0	33.0	58.0	80.0	102	154
Rise time											
Braking torque	t_{12}	[ms]	14.0	27.0	21.0	43.0	49.0	64.0	109	157	168
Engagement time											
	t_1	[ms]	30.0	52.0		90.0	82.0	122	189	259	322
Disengagement time											
	t_2	[ms]	45.0	57.0	76.0	115	210	220	270	340	390

► The brake response and application times are guide values. The engagement time is 10 times longer with AC-side switching. With the maximum air gap the disengagement time t_2 – depending on the brake and control – is up to 4 times longer than the disengagement time with the rated air gap.

Spring-applied brakes

Rated data with increased braking torque

► Please enquire for braking torques and maximum switching work values not listed here.

Size			10	12	14	16	16	18	20	20	25	25
Power input												
	P_{in}	[kW]	0.030	0.040	0.050	0.055	0.055	0.085	0.10	0.10	0.11	0.11
Braking torque												
100	M_B	[Nm]	23.0	46.0	75.0	100	125	200	315	400	490	600
1000	M_B	[Nm]	20.0	39.0	64.0	83.0	103	162	249	317	376	461
1200	M_B	[Nm]	20.0	39.0	62.0	81.0	101	158	244	309	367	449
1500	M_B	[Nm]	19.0	38.0	60.0	78.0	98.0	153	237 [1]	300 [1]	356 [1]	436 [1]
1800	M_B	[Nm]	19.0	37.0	59.0	77.0	96.0	150 [1]				
3000	M_B	[Nm]	17.0	34.0	55.0 [1]	71.0 [1]	89.0 [1]					
3600	M_B	[Nm]	17.0	33.0 [1]								
Maximum switching energy												
100	Q_E	[KJ]	12.0	24.0	30.0	36.0	36.0	60.0	80.0	80.0	120	120
1000	Q_E	[KJ]	12.0	24.0	30.0	36.0	36.0	60.0	80.0	80.0	120	120
1200	Q_E	[KJ]	12.0	24.0	30.0	36.0	36.0	60.0	80.0	80.0	120	120
1500	Q_E	[KJ]	12.0	24.0	30.0	36.0	36.0	60.0	24.0 [1]	24.0 [1]	36.0 [1]	36.0 [1]
1800	Q_E	[KJ]	12.0	24.0	30.0	36.0	36.0	36.0 [1]				
3000	Q_E	[KJ]	12.0	24.0	18.0 [1]	11.0 [1]	11.0 [1]					
3600	Q_E	[KJ]	12.0	7.00 [1]								
Transition operating frequency												
	$S_{hü}$	[1/h]	40.0	30.0	28.0	27.0	27.0	20.0	19.0	19.0	15.0	15.0
Moment of inertia												
	J	[kgcm²]	0.20	0.45	0.63	1.50	1.50	2.90	7.30	7.30	20.0	20.0
Mass												
	m	[kg]	2.60	4.20	5.80	8.70	8.70	12.6	19.5	19.5	31.0	31.0

[1] In the region of the load limit the value for friction energy Q_{BW} can be reduced to 40 %.

► Activation via half-wave or bridge rectifier

Size			10	12	14	16		18	20		25	
Friction energy												
	Q_{BW}	[MJ]	198	353	253	563	241	578	1596	580	2465	1409
Delay time												
Engaging	t_{11}	[ms]	10.0	16.0	11.0	22.0	17.0	24.0	46.0	17.0	77.0	38.0
Rise time												
Braking torque	t_{12}	[ms]	19.0	25.0		30.0		45.0	100		120	
Engagement time												
	t_1	[ms]	29.0	41.0	36.0	52.0	47.0	69.0	146	117	197	158
Disengagement time												
	t_2	[ms]	109	193	308	297	435	356	378	470	451	532

Spring-applied brakes

Rated data with increased braking torque

► Activation via bridge/half-wave rectifier

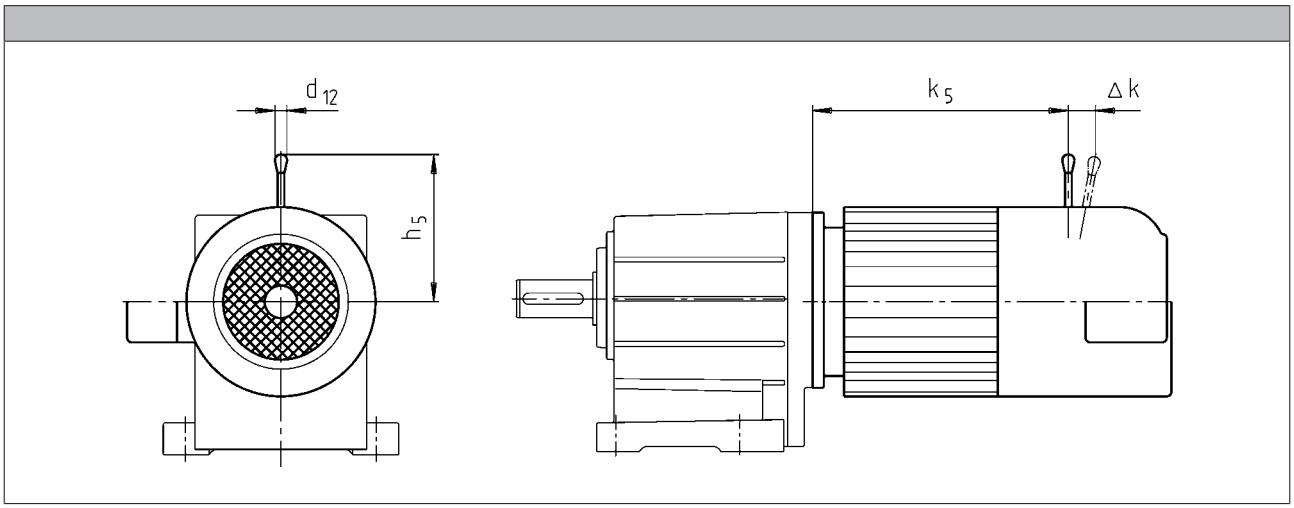
Design			Holding current reduction (cold brake)									
Size			10	12	14	16		18	20		25	
Friction energy	Q_{BW}	[MJ]	198	353	253	563	241	578	1596	580	2465	1409
Overexcitation time	$t_{ü}$	[ms]	300			1300						
Min. rest time	t	[ms]	900			3900						
Delay time												
Engaging	t_{11}	[ms]	24.0	27.0	17.0	41.0	21.0	60.0	69.0	17.0	123	85.0
Rise time												
Braking torque	t_{12}	[ms]	44.0	43.0	37.0	55.0	37.0	113	148	100	190	270
Engagement time	t_1	[ms]	68.0	70.0	54.0	97.0	57.0	173	217	334	313	355
Disengagement time	t_2	[ms]	109	193	308	297	435	356	378	470	451	532

Design			Over-excitation									
Size			10	12	14	16		18	20		25	
Friction energy	Q_{BW}	[MJ]	264	706	761	966		1542	2322		3522	
Overexcitation time	$t_{ü}$	[ms]	300			1300						
Min. rest time	t	[ms]	900			3900						
Delay time												
Engaging	t_{11}	[ms]	29.0	54.0	31.0	70.0	46.0	86.0	103	55.0	171	135
Rise time												
Braking torque	t_{12}	[ms]	53.0	87.0	68.0	93.0	83.0	160	222	319	266	430
Engagement time	t_1	[ms]	82.0	141	99.0	163	129	246	325	374	437	565
Disengagement time	t_2	[ms]	53.0	81.0	117	141	168	151	160	167	184	204

► The brake response and application times are guide values. The engagement time is 10 times longer with AC-side switching. With the maximum air gap the disengagement time t_2 – depending on the brake and control – is up to 4 times longer than the disengagement time with the rated air gap.

Spring-applied brakes

Manual release lever



Motor frame size	Size				
	Brake				
		k_5	Δ k	h_5	d_{12}
		[mm]	[mm]	[mm]	[mm]
063-32 063-42	06	173	29	107	13.0
071-32 071-42	06 08	186 187	29 27	107 116	13.0 13.0
080-32 080-42	06 08	207 218	29 27	107 116	13.0 13.0
090-32	08 10	245 256	27 28	116 132	13.0 13.0
100-12 100-32	10 12	294 296	28 37	132 161	13.0 13.0
112-22	12 14	292 296	37 41	161 195	13.0 24.0
132-12 132-22 132-32	14 16	373 373	41 55	195 240	24.0 24.0

The following combinations with manual release lever and motor connection in the same position are not possible:

- HAN connector with connection in position 1
- Inverter motec
- Terminal box of motor sizes 071, 080, 090 for brake and retracting (M□□MA BR/BS/BA/BI)

Resolver

Stator-fed resolver with two stator windings offset by 90° and one rotor winding with transformer winding.

► The three-phase AC motors with resolver cannot be used for speed-dependent safety functions in connection with the SM 301 safety module.

Product key				
				RS1
Accuracy				
			[']	-10 ... 10
Absolute positioning				
				1 revolution
Max. input voltage				
DC	$U_{in,max}$		[V]	10.0
Max. input frequency				
	$f_{in,max}$		[kHz]	4.00
Ratio				
Stator / rotor		± 5 %		0.30
Rotor impedance				
	Z_{ro}		[Ω]	51 + j90
Stator impedance				
	Z_{so}		[Ω]	102 + j150
Impedance				
	Z_{rs}		[Ω]	44 + j76
Min. insulation resistance				
At DC 500 V	R		[MΩ]	10.0
Number of pole pairs				
				1

Incremental encoder and SinCos absolute value encoder

► The three-phase AC motors with incremental encoders or SinCos absolute value encoders cannot be used for speed-dependent safety functions in connection with the SM 301 safety module.

Encoder type			HTL incremental				TTL incremental			SinCos absolute value
Product key			IG128-24V-H	IG512-24V-H	IG1024-24V-H	IG2048-24V-H	IG512-5V-T	IG1024-5V-T	IG2048-5V-T	AM1024-8V-H
Encoder type										Multi-turn
Pulses			128	512	1024	2048	512	1024	2048	1024
Output signals			HTL				TTL			1 Vss
Interfaces			A, B track	A, B, N track and inverted						Hiperface
Absolute revolutions			0							4096
Accuracy		[']	-22.5 ... 22.5	-2 ... 2						-0.8 ... 0.8
Min. input voltage										
DC	$U_{in,min}$	[V]	8.00				4.75			7.00
Max. input voltage										
DC	$U_{in,max}$	[V]	26.0	30.0			5.25			12.0
Max. current consumption										
	I_{max}	[A]	0.040	0.15						0.080
Limit frequency										
	f_{max}	[kHz]	30.0	160			300			200
Inverter assignment			E84AVSC E84AVHC	E84AVHC			E84AVTC E94A ECS EVS93			

Inverters
- Inverter Drives 8400 StateLine (E84AVSC)
- Inverter Drives 8400 HighLine (E84AVHC)
- Inverter Drives 8400 TopLine (E84AVTC)

Servo-Inverters
- Servo Drives 9400 (E94A)
- 9300 servo inverters (EVS93)
- Servo Drives ECS

Blowers

► The use of a blower enables operation below 20 Hz without torque derating.

Rated data for 50 Hz

Size	Number of phases	Connection method					
Motor							
			U_{min}	U_{max}	P_{max}	I_{max}	m
			[V]	[V]	[kW]	[A]	[kg]
063	1		230	277	0.027	0.11	2.00
	3	Δ	200	303	0.028	0.12	
		Y	346	525		0.070	
071	1		230	277	0.027	0.10	2.10
	3	Δ	200	303	0.031	0.11	
		Y	346	525		0.060	
080	1		230	277	0.029	0.11	2.30
	3	Δ	200	303	0.031		
		Y	346	525		0.060	
090	1		220	277	0.065	0.29	2.70
	3	Δ	200	303	0.091	0.38	
		Y	346	525		0.22	
100	1		220	277	0.066	0.28	3.00
	3	Δ	200	303	0.091	0.37	
		Y	346	525		0.22	
112	1		220	277	0.071	0.28	3.10
	3	Δ	200	303	0.097	0.35	
		Y	346	525		0.20	
132	1		230	277	0.098	0.40	4.20
	3	Δ	200	303	0.12	0.58	
		Y	346	525		0.33	
160	1		230	277	0.25	0.97	6.20
	3	Δ	200	303		0.87	
		Y	346	525		0.50	
180	1		230	277		0.97	8.00
	3	Δ	200	303		0.87	
		Y	346	525		0.50	

Blowers

Rated data for 50 Hz

Size	Number of phases	Connection method					
Motor							
			U_{min}	U_{max}	P_{max}	I_{max}	m
			[V]	[V]	[kW]	[A]	[kg]
200	1		230	277	0.25	0.97	8.00
	3	Δ	200	303		0.87	
		Y	346	525		0.50	
225		Δ	200	400	0.28	1.10	15.0
		Y	346	525	0.17	0.35	

Rated data for 60 Hz

Size	Number of phases	Connection method					
Motor							
			U_{min}	U_{max}	P_{max}	I_{max}	m
			[V]	[V]	[kW]	[A]	[kg]
063	1		230	277	0.032	0.12	2.00
	3	Δ	220	332	0.028	0.10	
		Y	380	575		0.060	
071	1		230	277	0.033	0.12	2.10
	3	Δ	220	332	0.029	0.10	
		Y	380	575		0.060	
080	1		230	277	0.037	0.14	2.30
	3	Δ	220	332	0.034	0.10	
		Y	380	575		0.060	
090	1		220	277	0.065	0.25	2.70
	3	Δ		332	0.077	0.33	
		Y	380	575		0.19	
100	1		220	277	0.075	0.30	3.00
	3	Δ		332	0.087	0.31	
		Y	380	575		0.18	
112	1		220	277	0.094	0.37	3.10
	3	Δ		332	0.10	0.31	
		Y	380	575		0.18	
132	1		230	277	0.15	0.57	4.20
	3	Δ	220	332		0.44	
		Y	380	575		0.25	
160		Δ	220	332	0.36	0.93	6.20
		Y	380	575		0.56	
180		Δ	220	332		0.93	8.00
		Y	380	575		0.56	
200		Δ	220	332		0.93	
		Y	380	575		0.56	
225		Δ	220	400	0.28	0.76	15.0
		Y	380	575	0.26	0.43	

Temperature monitoring

► The thermal sensors are integrated in the windings. The use of an additional motor protection switch is recommended.

TKO thermal contacts

Function	Operating temperature	Min. reset temperature	Max. reset temperature	Max. input current	Max. input voltage
					AC
	T	T_{min}	T_{max}	$I_{in,max}$	$U_{in,max}$
	-5 ... 5				
	[°C]	[°C]	[°C]	[A]	[V]
NC contact	150	90.0	135	2.50	250

PTC thermistor

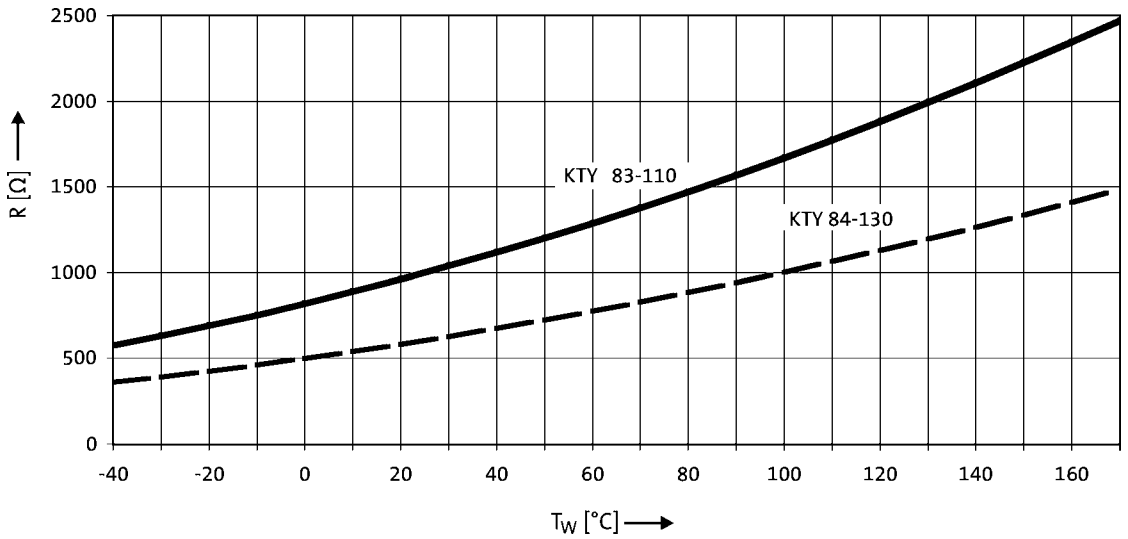
Function	Operating temperature	Rated resistance			Standard
		155 °C	-20 °C	140 °C	
	T	R_N	R_N	R_N	
	-5 ... 5				
	[°C]	[Ω]	[Ω]	[Ω]	
Sudden change in resistance	150	550	30.0	250	DIN 44080 DIN VDE 0660 Part 303

Temperature monitoring

KTY temperature sensor

	Function	Rated resistance			Max. input current	
		25 °C	150 °C	170 °C	25 °C	170 °C
		R_N	R_N	R_N	$I_{in,max}$	$I_{in,max}$
		[Ω]	[Ω]	[Ω]	[A]	[A]
KTY83-110	Continuous resistance change	1000	2225	2471	0.010	0.002
KTY84-130	Continuous resistance change	603	1334	1482	0.010	0.002

Variation of resistance



► If the detector is supplied with a measured current of 1 mA, the above relationship between the temperature and the resistance applies.

Terminal box

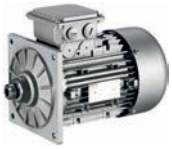
The MF three-phase AC motors are designed specifically for inverter operation. With a base frequency of 120Hz, the rated voltage has been specified at approximately 200 V in delta connection (up to 2.2 kW) and approximately 350V in star configurations.

In the standard version, the motors are connected in the terminal box. As an option, the motors are also available with the connectors described on the following pages as long as the permissible ratings are not exceeded.

Motor terminal box - built-on accessories assignment: 4-pole / 6-pole motors

Motor type	M□□MAXX	M□□MARS M□□MAIG M□□MAAG	M□□MAZE
Motor frame size			
	Terminal box		
063-32 063-42	KK1	KK2	
071-32 071-42	KK1	KK2	KK2
080-32 080-42	KK1	KK2	KK2
090-32	KK1	KK2	KK2
100-12 100-32	KK1	KK2	KK2
112-22	KK1	KK2	KK2
132-12 132-22 132-32	KK1	KK3	KK3

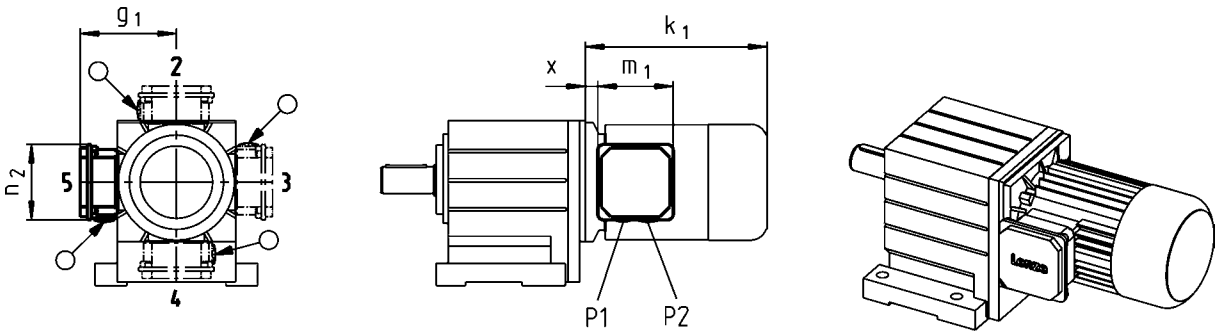
Motor type	M□□MABR	M□□MABS M□□MABI M□□MABA	M□□MABZ
Motor frame size			
	Terminal box		
063-32 063-42	KK2	KK3	
071-32 071-42	KK2	KK3	KK2
080-32 080-42	KK2	KK3	KK2
090-32	KK2	KK3	KK2
100-12 100-32	KK2	KK3	KK2
112-22	KK2	KK3	KK2
132-12 132-22 132-32	KK3	KK3	KK3



Terminal box

Dimensions of KK1

- For motors with motor terminal box KK1, the connector position can be selected in accordance with the terminal box position.
- If preferred positions are not specified in the order, the cable entry will be positioned as circled on the diagram below.



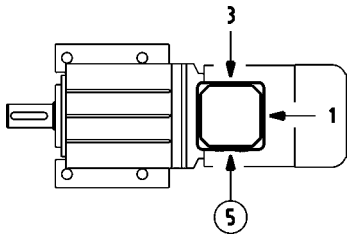
Size						
Motor						
	x	g_1	m_1	n_2	P_1	P_2
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
063	21 12 [1)]	100 117 [1)]	75.0 93.0 [1)]	75.0 93.0 [1)]	M16x1.5 M20x1.5 [1)]	M20x1.5 M20x1.5
071	24 15 [1)]	109 126 [1)]				
080	14	150	115	115	M20x1.5	M25x1.5
090	19	157				
100	20	166				
112	22	176				
132	33	195	122	122	M32x1.5	M32x1.5

[1)] UL/CSA approval: cURus

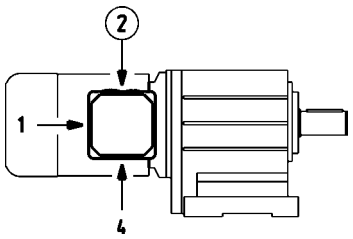
Terminal box

Cable entry position when using KK1

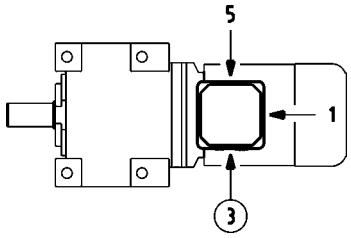
Terminal box in position 2



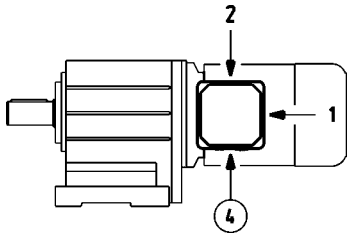
Terminal box in position 3



Terminal box in position 4

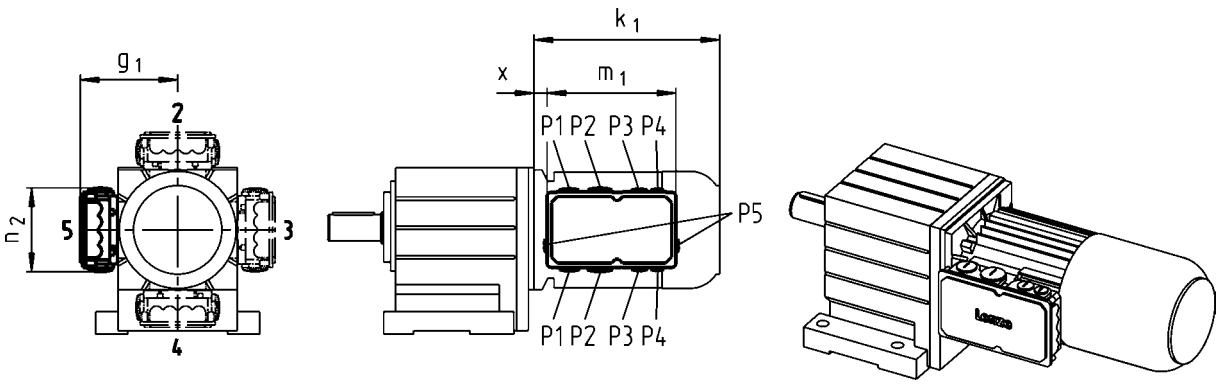


Terminal box in position 5



Terminal box

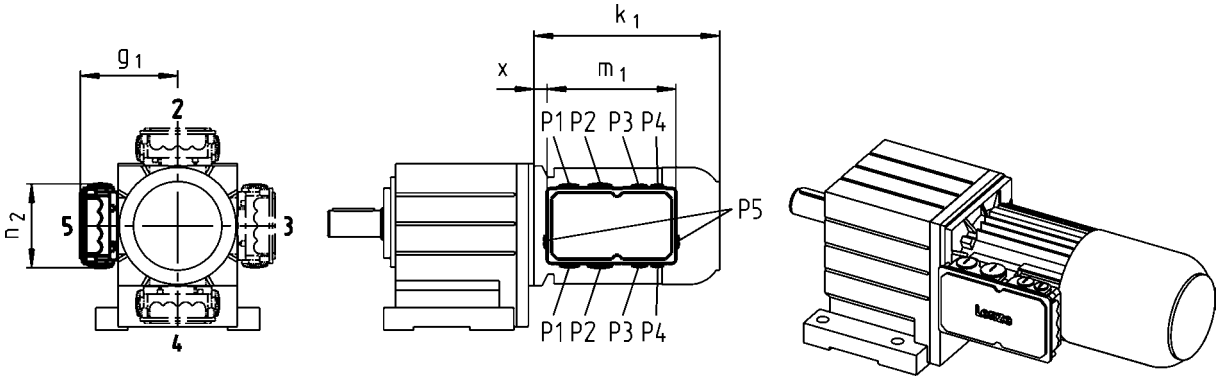
Dimensions of KK2



Size						
Motor						
	x	g_1	m_1	n_2	P_1	P_2
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
063	13	107	136	103	M16x1.5	M20x1.5
071	15	118				
080	17	132	152	121	M20x1.5	M25x1.5
090	22	137				
100	23	147				
112	25	158				

Terminal box

Dimensions of KK3



Size									
Motor									
	x	g_1	m_1	n_2	P_1	P_2	P_3	P_4	P_5
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
063	2	124	195	125	M25x1.5	M32x1.5	M20x1.5	M20x1.5	
071	5	133							
080	15	142							
090	20	147							
100	21	158							
112	23	168							
132	38	187							
160	35	210	226	127	M50x1.5	M16x1.5		M16x1.5	
180	73	230							
225	95	346	354	205		M63x1.5 [1)]	M50x1.5 [1)]		M16x1.5

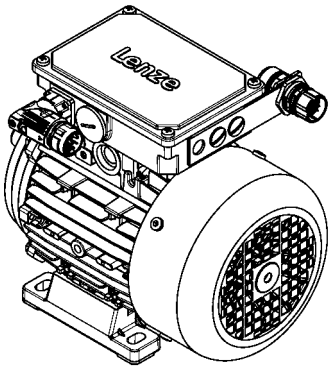
[1)] Cable entry only possible at one position.
Terminal box position 2: cable entry at position 5.
Terminal box position 3: cable entry at position 2.
Terminal box position 4: cable entry at position 3.
Terminal box position 5: cable entry at position 4.

Plug connectors

ICN, HAN and M12 connectors (only for IG128-24V-H incremental encoder) are available for the three-phase AC motors.

ICN connector

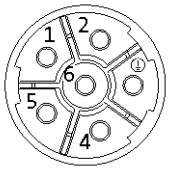
A connector is used for power, brake and temperature monitoring. The connections to the feedback system and the blower each employ a separate connector.



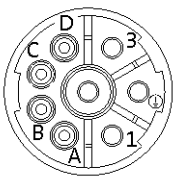
Connection for power, brake and temperature monitoring

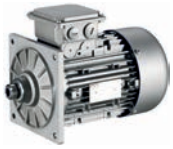
The connectors can be rotated through 270° and are fitted with a bayonet catch for SpeedTec connectors. As this connector is also compatible with conventional union nuts, existing mating connectors can continue to be used without difficulty. The motor connection is determined in the terminal box and must be checked before commissioning.

► ICN 6-pole

Pin assignment			
Contact	Designation	Meaning	
1	BD1 / BA1	Brake +/AC	
2	BD2 / BA2	Brake /AC	
PE	PE	PE conductor	
4	U	Phase U power	
5	V	Phase V power	
6	W	Phase W power	

► ICN 8-pole

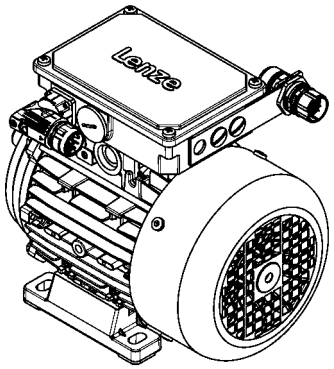
Pin assignment			
Contact	Designation	Meaning	
1	U	Phase U power	
PE	PE	PE conductor	
3	V	Phase V power	
4	W	Phase W power	
A	TB1 / TP1 / R1	Thermal sensor: TKO/PTC/ +KTY	
B	TB2 / TP2 / R2	Thermal sensor: TKO/PTC/-KTY	
C	BD1 / BA1	Brake +/AC	
D	BD2 / BA2	Brake /AC	



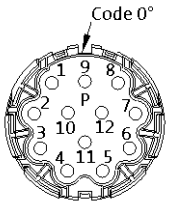
ICN connector

Feedback connection

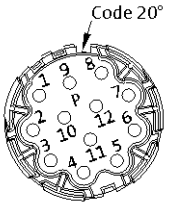
All encoder systems (apart from IG128-24V-H) are also available with an ICN connector fixed to the motor terminal box for exceptionally fast commissioning. The connectors are fitted with a bayonet fixing, which is also compatible with conventional union nuts. Existing mating connectors can therefore continue to be used without difficulty.



► Resolver

Pin assignment			
Contact	Designation	Meaning	
1	+Ref	Transformer windings	
2	-Ref		
3	+VCC ETS	Supply: Electronic nameplate	
4	+COS	Cosine stator windings	
5	-COS		
6	+SIN	Sine stator windings	
7	-SIN		
8		Not assigned	
9			
10			
11	+KTY	KTY temperature sensor	
12	-KTY		

► Hiperface incremental encoder and SinCos absolute value encoder

Pin assignment			
Contact	Designation	Meaning	
1	B	Track B/+SIN	
2	A^-	Track A inverse/-COS	
3	A	Track A/+COS	
4	$+U_B$	Supply +	
5	GND	Mass	
6	Z^-	Zero track inverse/-RS485	
7	Z	Zero track/+RS485	
8		Not assigned	
9	B^-	Track B inverse/-SIN	
10		Not assigned	
11	+KTY	KTY temperature sensor	
12	-KTY		

ICN connector

Motor terminal box with ICN connectors - built-on accessories assignment: 4-pole / 6-pole motors

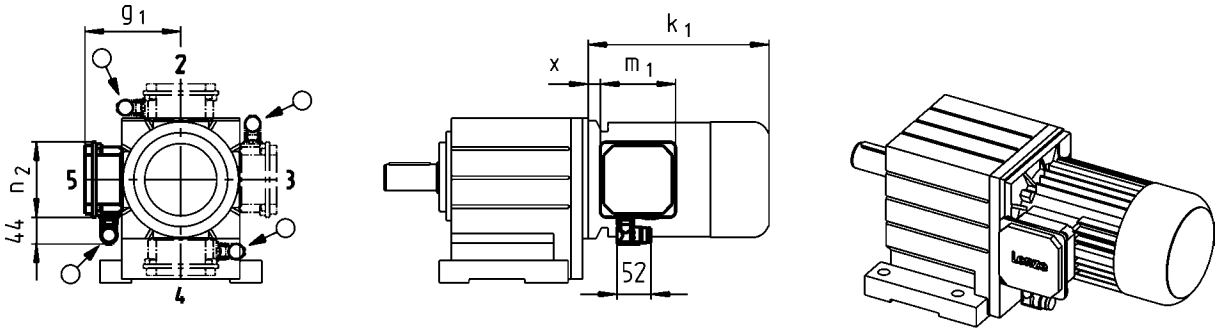
Motor type	M□□MAXX	M□□MARS M□□MAIG M□□MAAG	M□□MAZE
Motor frame size			
	Terminal box		
063-32 063-42	KK1	KK2	
071-32 071-42	KK1	KK2	KK2
080-32 080-42	KK1	KK2	KK2
090-32	KK1	KK2	KK2
100-12 100-32	KK1	KK2	KK2

Motor type	M□□MABR	M□□MABS M□□MABI M□□MABA	M□□MABZ
Motor frame size			
	Terminal box		
063-32 063-42	KK2	KK3	
071-32 071-42	KK2	KK3	KK2
080-32 080-42	KK2	KK3	KK2
090-32	KK2	KK3	KK2
100-12 100-32	KK2	KK3	KK2

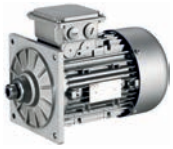
ICN connector

Dimensions of KK1

- For motors with connectors, the connector position can be selected in accordance with the terminal box position.
- If preferred positions are not specified in the order, the connector will be positioned as circled on the diagram below.



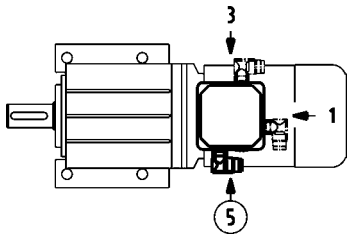
Size				
Motor				
	x	g_1	m_1	n_2
	[mm]	[mm]	[mm]	[mm]
063	12	117	93.0	93.0
071	15	126		
080	14	150	115	115
090	19	157		
100	20	166		
112	22	176		
132	33	195	122	122



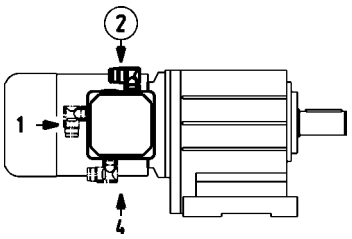
ICN connector

Connector position when using KK1

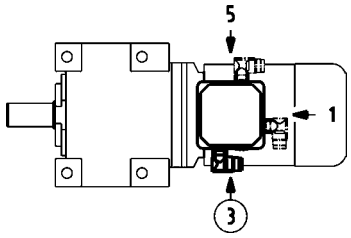
Terminal box in position 2



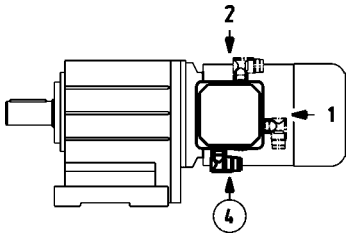
Terminal box in position 3



Terminal box in position 4



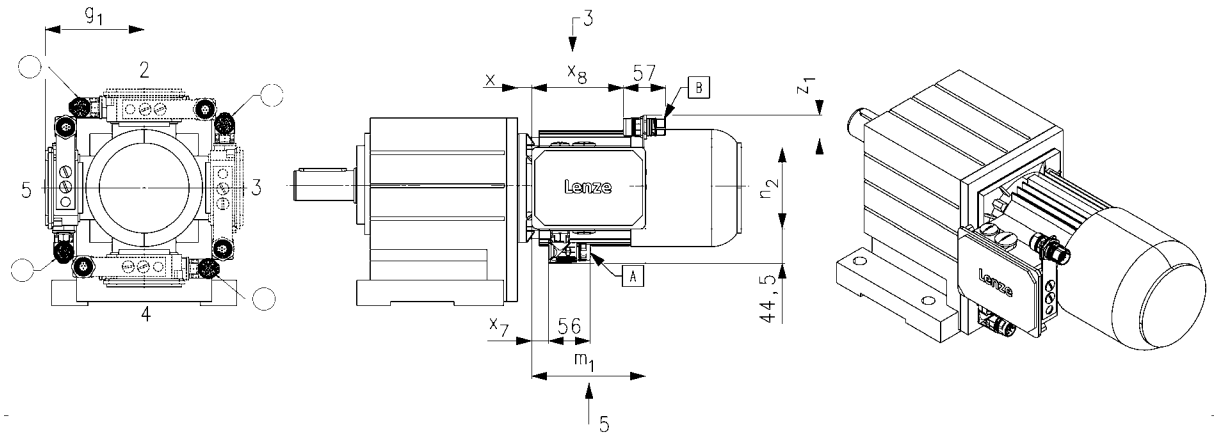
Terminal box in position 5



ICN connector

Dimensions of KK2/KK3

- For motors with connectors, the connector position can be selected in accordance with the terminal box position.
- If preferred positions are not specified in the order, the connector will be positioned as circled on the diagram below.

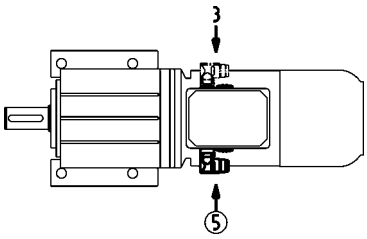


Size							
Motor							
	x	g_1	m_1	n_2	x_7	x_8	$z_{1, max}$
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
063	13	107	136	103	16	109	43
071	15	118					
080	17	132	152	121	23	125	41
090	22	137					
100	23	147					
112	25	158					
132	38	187	195	125	27	166	71

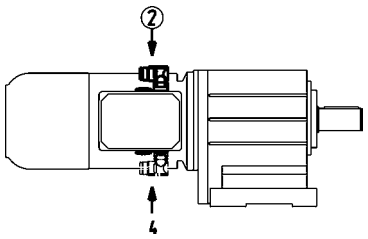
ICN connector

Connector position when using KK2/KK3

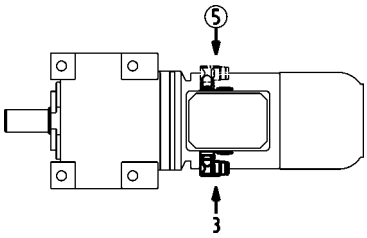
Terminal box in position 2



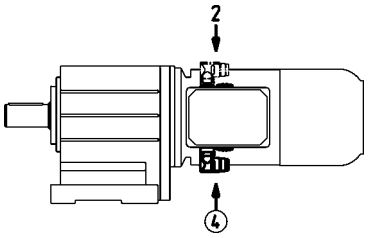
Terminal box in position 3

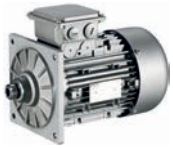


Terminal box in position 4



Terminal box in position 5

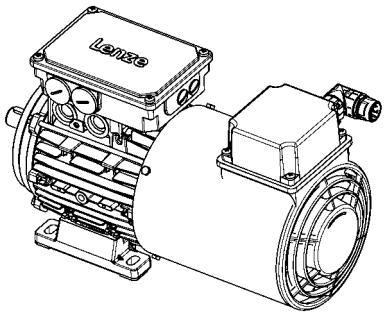




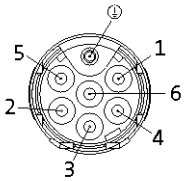
ICN connector

Blower connection

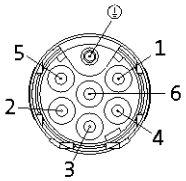
The blower is also optionally available with an ICN connector fixed to the terminal box of the blower for exceptionally fast commissioning. The connectors are fitted with a bayonet fixing, which is also compatible with conventional union nuts. Existing counter plugs can therefore continue to be used without difficulty.

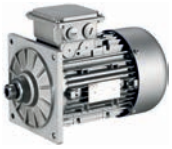


► Blower 1-ph

Pin assignment			
Contact	Designation	Meaning	
PE	PE	PE conductor	
1	U1	Fan	
2	U2		
3		Not assigned	
4			
5			
6			

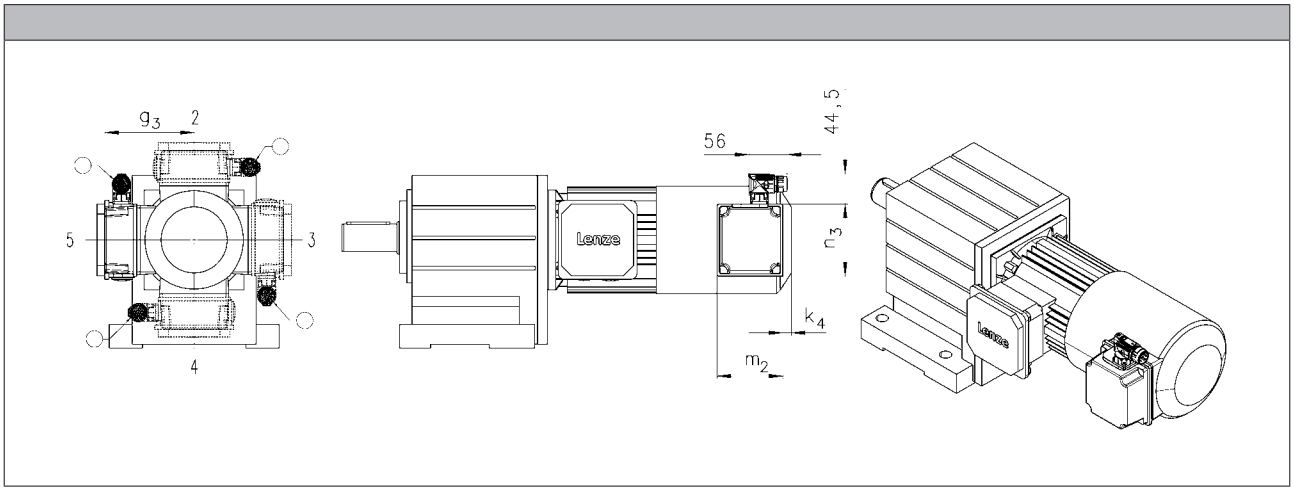
► Blower 3-ph

Pin assignment			
Contact	Designation	Meaning	
PE	PE	PE conductor	
1	U	Phase U power	
2		Not assigned	
3	V	Phase V power	
4		Not assigned	
5			
6	W	Phase W power	



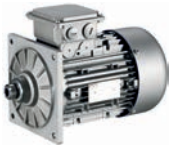
ICN connector

Dimensions of blower



Size				
Motor				
	k_4	g_3	m_2	n_3
	[mm]	[mm]	[mm]	[mm]
063	12	115	95	105
071		122		
080	13	132	96	106
090	22	141	95	105
100		150		
112		162		
132	32	182		
160	31	209	96	106
180				
225				

► In addition, the cover of the blower terminal box (including connectors) can be rotated progressively through 90° if necessary.

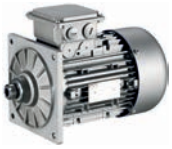


M12 connector

IG128-24V-H incremental encoder connection

As a standard this incremental encoder is equipped with a connection cable of about 0.5 m length and with a common industry standard M12 connector at its end.

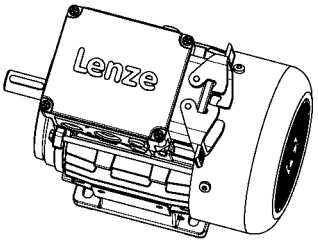
Pin assignment			
Contact	Designation	Meaning	
1	$+U_B$	Supply +	
2	B	Track B	
3	GND	Mass	
4	A	Track A	

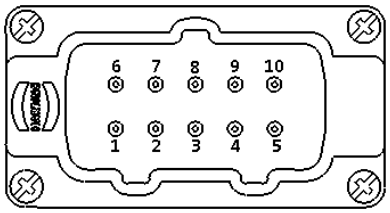


HAN connector

10E

In the case of the rectangular HAN-10E connectors, all six ends of the three winding phases are taken out to the power contacts. The motor circuit is therefore determined in the mating connector.

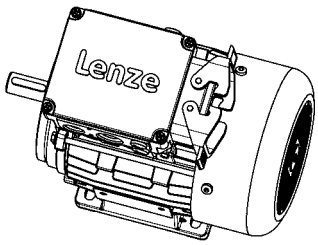


Pin assignment		
Contact	Meaning	
1	Terminal board: U1	
2	Terminal board: V1	
3	Terminal board: W1	
4	Brake +/AC	
5	Brake -/AC	
6	Terminal board: W2	
7	Terminal board: U2	
8	Terminal board: V2	
9	Thermal sensor: +KTY/PTC/TKO	
10	Thermal sensor: KTY/PTC/TKO	

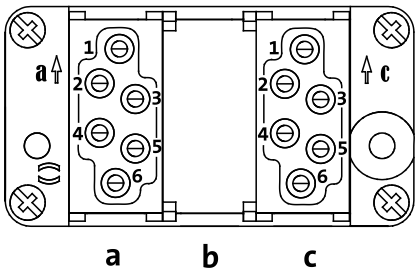
HAN connector

Modular

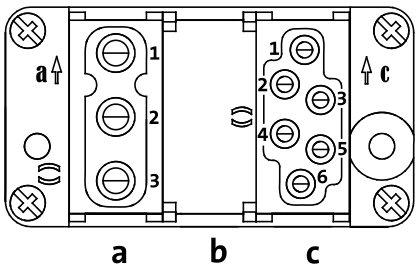
The connector is available with two different power modules (16 A or 40 A), depending on the rated motor current. The motor connection is determined in the terminal box and must be checked before commissioning.



► HAN modular 16 A

Pin assignment			
Module	Contact	Meaning	
A	1	Terminal board: U1	
	2	Terminal board: V1	
	3	Terminal board: W1	
B		Dummy module	
C	1	Thermal sensor: +KTY/PTC/TKO	
	2	Brake +/AC	
	3	Brake -/AC	
	4	Rectifier: Switching contact	
	5		
	6	Thermal sensor: KTY/PTC/TKO	

► HAN modular 40 A

Pin assignment			
Module	Contact	Meaning	
A	1	Terminal board: U1	
	2	Terminal board: V1	
	3	Terminal board: W1	
B		Dummy module	
C	1	Thermal sensor: +KTY/PTC/TKO	
	2	Brake +/AC	
	3	Brake -/AC	
	4	Rectifier: Switching contact	
	5		
	6	Thermal sensor: KTY/PTC/TKO	

HAN connector

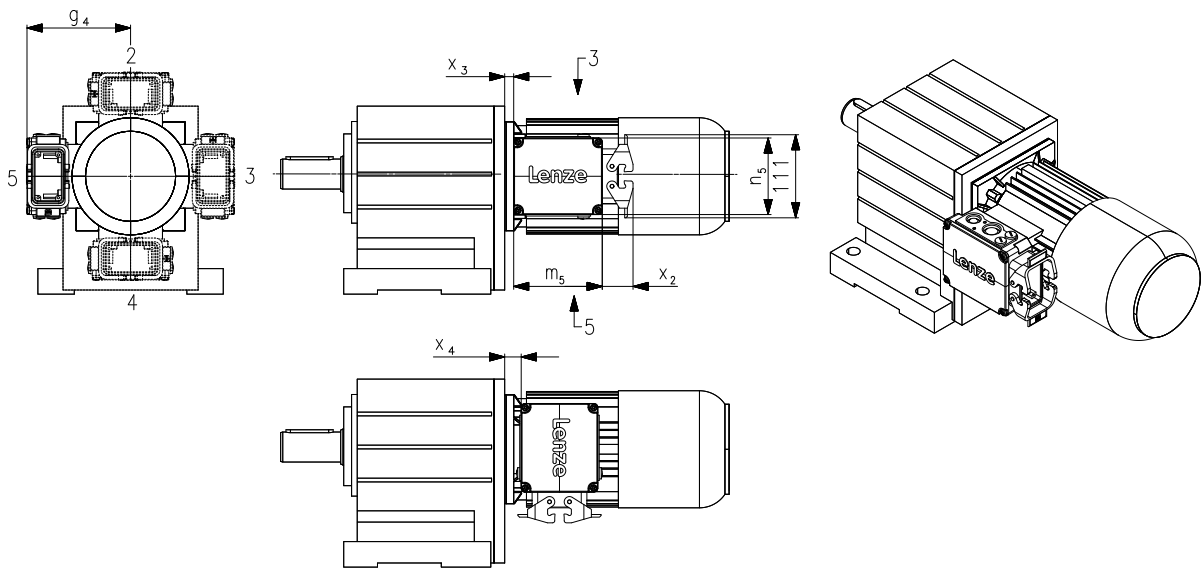
Motor type	M□□MAXX M□□MABR	M□□MAZE M□□MABZ
Motor frame size		
	Terminal box with HAN connector	
063-32 063-42	HAN-10E HAN modular	
071-32 071-42	HAN-10E HAN modular	HAN-10E HAN modular
080-32 080-42	HAN-10E HAN modular	HAN-10E HAN modular
090-32	HAN-10E HAN modular	HAN-10E HAN modular
100-12 100-32	HAN-10E HAN modular	HAN-10E HAN modular
112-22		
132-12 132-22 132-32	HAN modular	HAN modular

Motor terminal box with HAN connectors - built-on accessories assignment: 4-pole / 6-pole motors

HAN connector

Dimensions

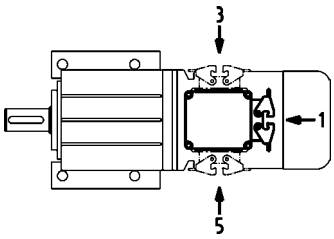
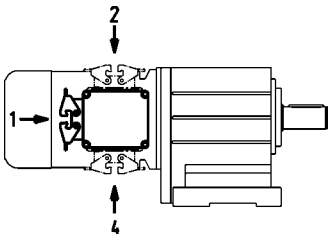
- For motors with connectors, the connector position can be selected in accordance with the terminal box position.
- Unless the connector position is specified, it will be supplied in position 1.

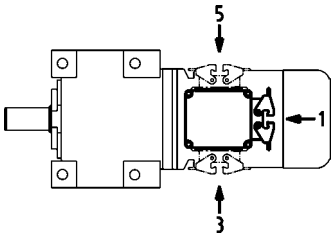
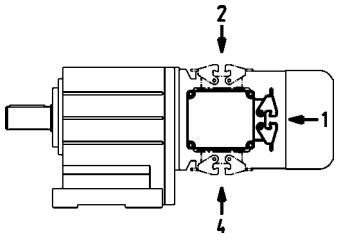


Size			
Motor			
	g_4	x_3	x_4
	[mm]	[mm]	[mm]
063	120	5.00	6.00
071	129	7.00	8.00
080	138	11.0	19.0
090	143	15.0	23.0
100	154	16.0	24.0
112	164	13.5	21.5
132	233	34.5	4.50
160	248	39.0	9.00

HAN connector

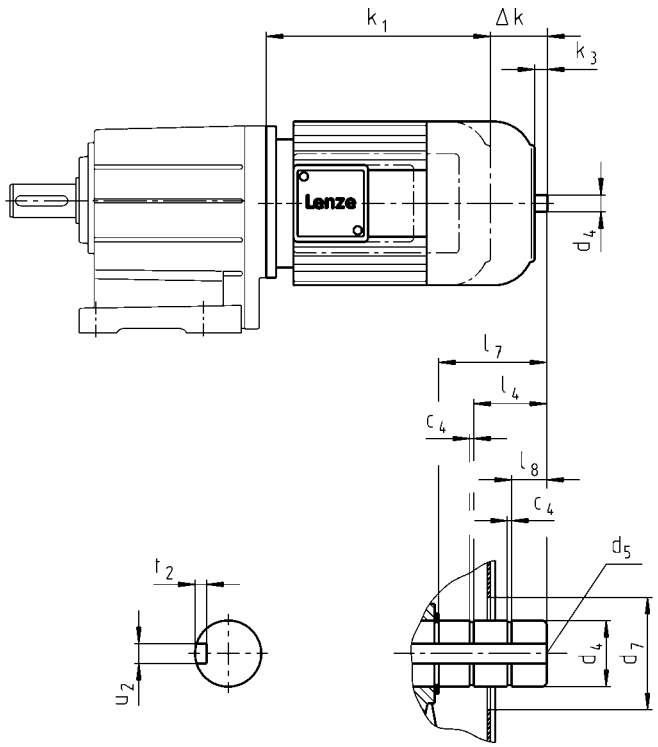
Position of connector

Connector in position 2	Connector in position 3
	

Connector in position 4	Connector in position 5
	

2nd shaft end

Dimensions, self-ventilated (4/6-pole)



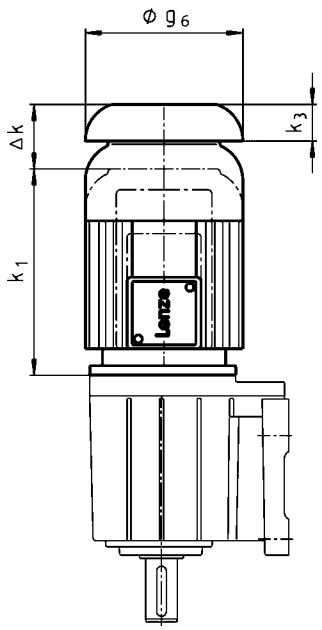
Motor type	
Built-on accessories	M□□MAZE M□□MABZ

Motor frame size												
	Δ k	k_3	c_4	d_4	d_4	d_5	d_7	l_4	l_7	l_8	u_2	t_2
				h6	j6							
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
071-32 071-42	47	11.0	1.10	14.0		M5	34.0		19.0	3.00	5.00	3.00
080-32 080-42	68	9.00	1.10	14.0		M5	34.0		19.0	4.50	5.00	3.00
090-32	57	9.00	1.10	14.0		M5	34.0		19.0	5.00	5.00	3.00
100-12 100-32	71	18.5	1.30		20.0	M6	34.0	17.0	32.5	10.5	6.00	3.50
112-22	84	16.0	1.30		20.0	M6	34.0	17.0	28.5	7.00	6.00	3.50
132-12 132-22 132-32	101	24.5	1.60		30.0	M10	46.0	24.5	42.0	8.50	8.00	4.00

[1] During operation, appropriate measures must be taken to make fan cover opening safe.

Protection cover

Dimensions, self-ventilated (4/6-pole)

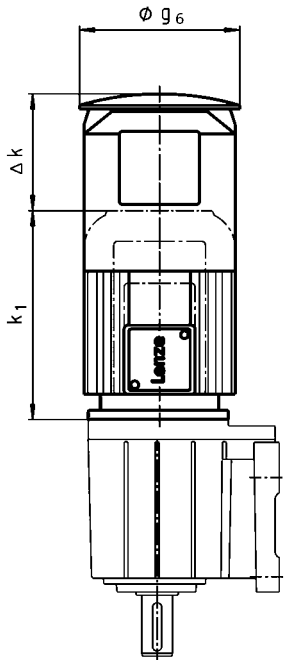


	Motor type					
	M□□MAXX	M□□MABR	M□□MABS M□□MABI M□□MABA	M□□MARS M□□MAIG M□□MAAG		

Motor frame size						
	Δ k	Δ k	Δ k	Δ k	k_3	g_6
	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]
063-32 063-42	26	66	129	82	11.0	123
071-32 071-42	26	78	122	78	12.0	138
080-32 080-42	26	99	137	127	16.0	156
090-32	26	94	131	113	15.0	176
100-12 100-32	31	107	132	112	17.0	194
112-22	31	121	151	111	18.0	218
132-12 132-22 132-32	31	141	156	134	20.0	257

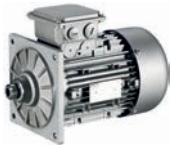
Protection cover

Dimensions, forced ventilated (4/6-pole)



	Motor type			
	M□□MAXX	M□□MABR M□□MABS M□□MABI	M□□MARS M□□MAIG M□□MAAG	

Motor frame size				
	Δ k	Δ k	Δ k	g_6
	[mm]	[mm]	[mm]	[mm]
063-32 063-42	169	209	169	133
071-32 071-42	165	202	165	150
080-32 080-42	168	224	168	170
090-32	157	210	157	188
100-12 100-32	137	198	137	210
112-22	135	216	216	249
132-12 132-22 132-32	140	226	226	300



Internet version

Lenze SE
Hans-Lenze-Straße 1
D-31855 Aerzen
Phone: +49 (0)5154 82-0
Telefax: +49 (0)5154 82 28 00

www.Lenze.com